

ON SUBDOMAINS: TESTING, PROFILES, AND COMPONENTS

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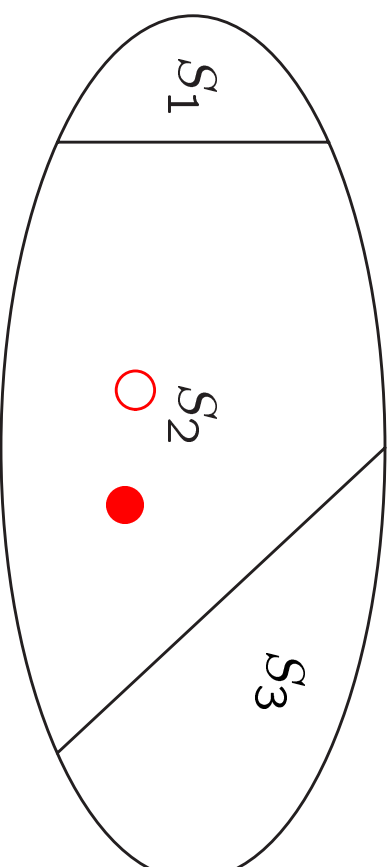
Components work joint with

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Subdomains and Testing

A program input space can be decomposed into subdomains:



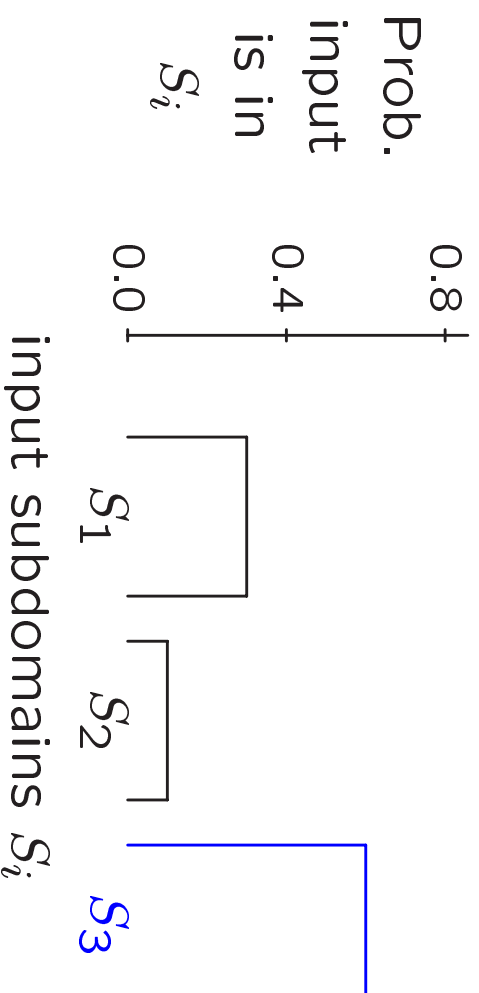
All non-random testing methods are subdomain methods:

- Choose subdomains whose points are “the same.”
- Select one test point from each subdomain.
- For analyzing X , “the same” *must be relative to X* .

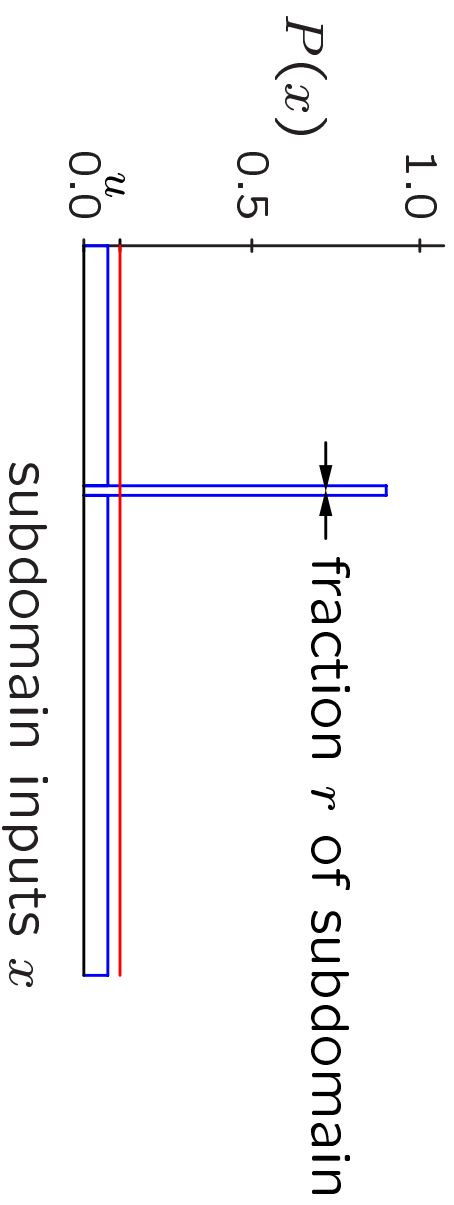
Operational Profile

Usage profiles are histograms described by a weighting vector:

profile $\langle .3, .1, .6 \rangle$:

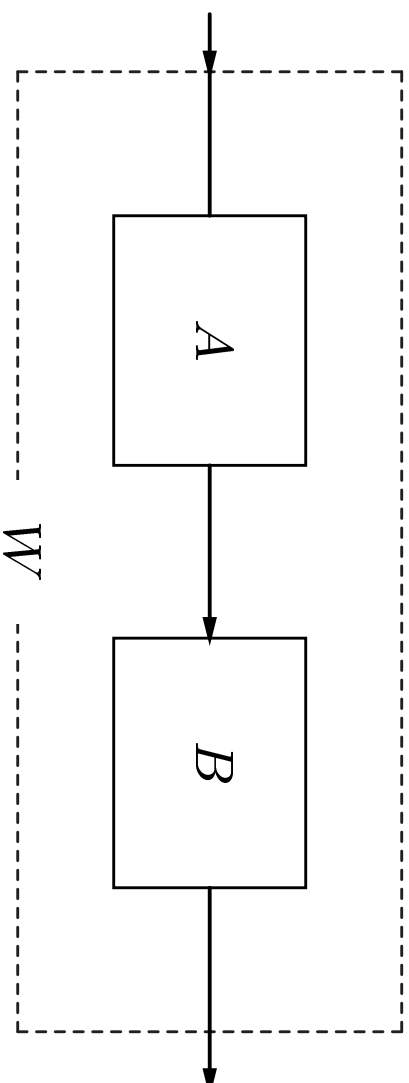


The Dreaded “Spiky” Profile



Failure rate: $r \approx 0$ | **measured**
 $1 - u \approx 1$ | **observed**

Component Reliability Theory



Measurements on A and B at component development time allow calculation for W at system design time.

Component Datasheet Mappings

For n subdomains input profile $P = \langle h_1, h_2, \dots, h_n \rangle$.

Reliability Mapping Measure failure rates f_i in each subdomain.

The component reliability is:

$$R = \sum_{i=1}^n h_i(1 - f_i).$$

Profile-transformation Mapping For arbitrary output

subdomains U_1, U_2, \dots, U_m , the output profile

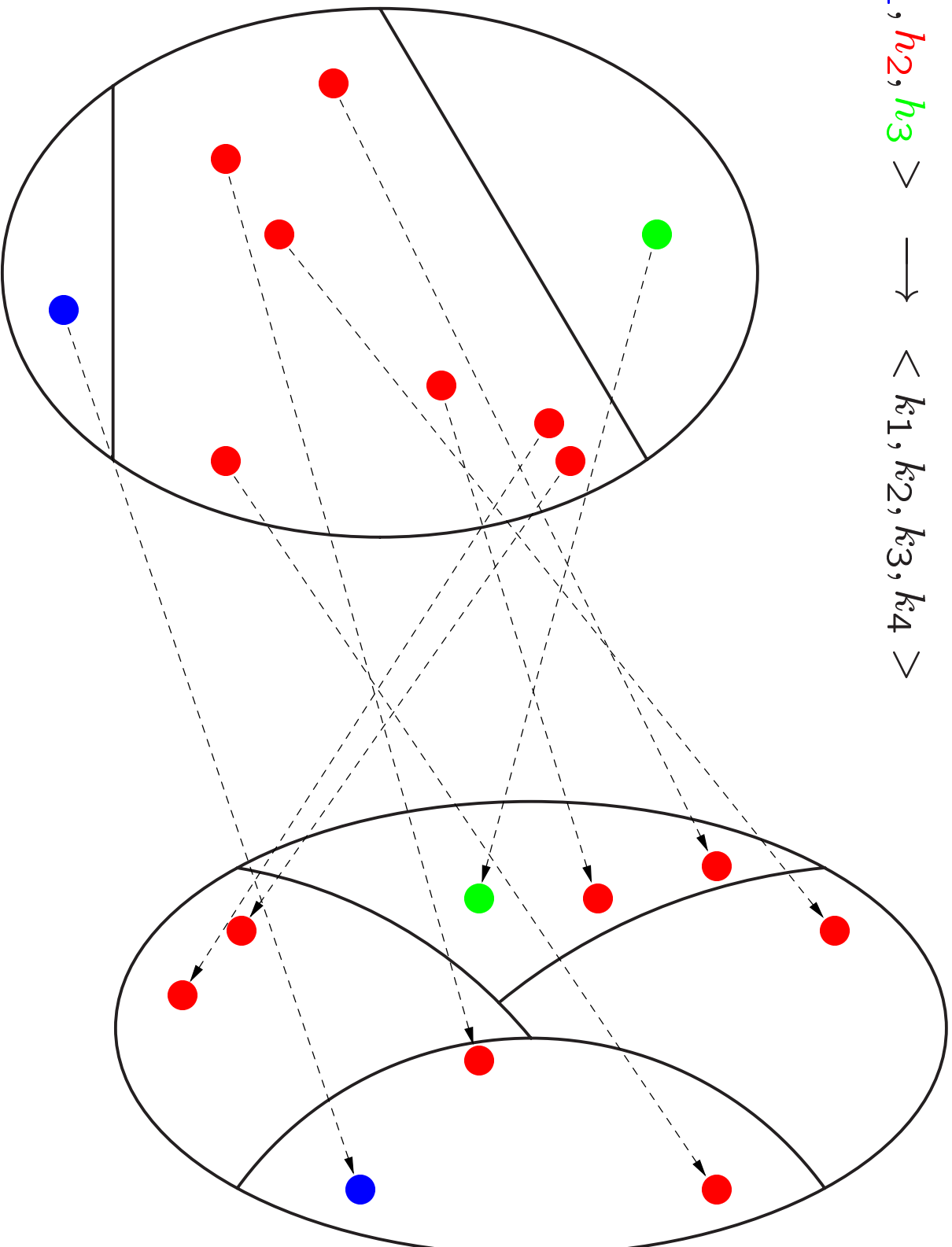
$Q = \langle k_1, k_2, \dots, k_m \rangle$ is:

$$k_j = \sum_{i=1}^n h_i \frac{|\{z \in S_i | c(z) \in U_j\}|}{|S_i|},$$

where c is the component function.

Profile Transformation

$$\langle h_1, h_2, h_3 \rangle \longrightarrow \langle k_1, k_2, k_3, k_4 \rangle$$



Example System Calculation

Key: parameter measured calculated

Integers limited to $2^{16} - 1$.

A 's function $e(x) = \sqrt{|x - 13|}$.

A 's subdomains:

$$S_1 = \{n | n < 0\}, S_2 = \{0\}, S_3 = \{n | n > 0\}.$$

failure rates $f_1 = .01$, $f_2 = 0$, $f_3 = .001$.

Input profile to A : $\langle .3, .1, .6 \rangle$.

Reliability of A alone:

$$.3(1 - .01) + .1(1 - 0) + .6(1 - .001) = .996$$

B's subdomains:

$$U_1 = \{n|n \leq 0\}, U_2 = \{n|1 \leq n \leq 10\},$$

$$U_3 = \{n|11 \leq n \leq 100\}, B_4 = \{n|n > 100\}.$$

failure rates .1, 0, 0, and .02 respectively.

Fraction of *A* outputs in *B*'s subdomains:

Subdomain	from S_1	from S_2	from S_3
U_1	0	0	0
U_2	.003	1.0	.002
U_3	.147	0	.162
U_4	.850	0	.836

B input profile $< 0, .102, .141, .757 >$:

$$k_1 = .3(0) + .1(0) + .6(0) = 0$$

$$k_2 = .3(.003) + .1(1.0) + .6(.002) = .102$$

$$k_3 = .3(.147) + .1(0) + .6(.162) = .141$$

$$k_4 = .3(.850) + .1(0) + .6(.836) = .757$$

Reliability of *B* alone:

$$0(1 - .1) + .102(1 - 0) + .141(1 - 0) + .757(1 - .02) = .986$$

System reliability $(.996)(.986) = .982$

Discussion: “The Same”

Functional (specification-based) subdomains *are* composed of “the same” points, but only if the program is correct.

Structural (program-based) subdomains are composed of “the same” points only in arcane program terms.

Intersecting subdomains is a good idea, but what subdomains should we start with? **A failure model of real defects is needed.**

Discussion: Continuity

The 'other' engineers can rely on the continuous properties of matter to interpolate between test points.

How can we use *specification* continuity?

How can we improve *program* continuity?