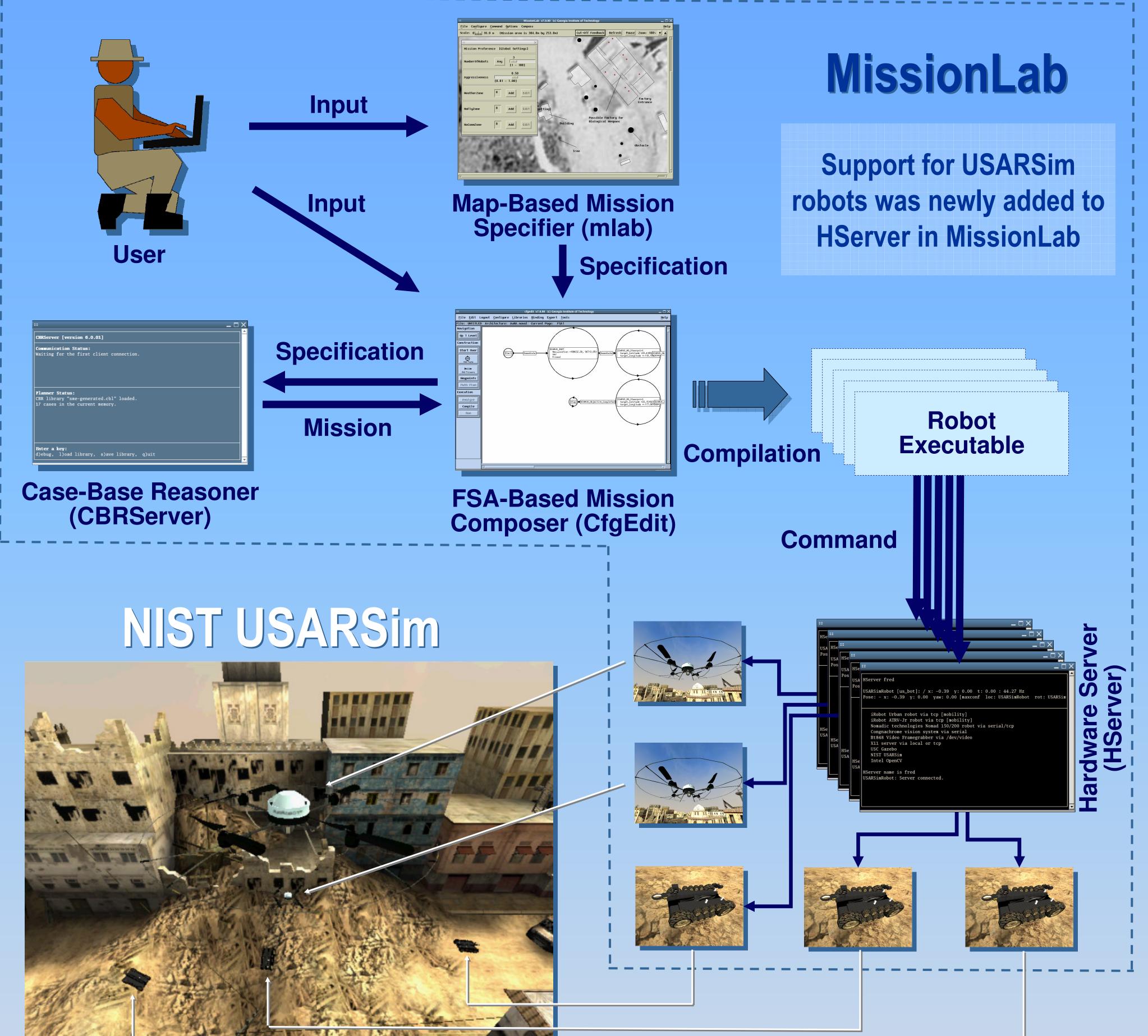
## Micro Autonomous Sensors & Technology (MAST) Georgia Tech Mobile Robot Laboratory





**MAST environment created** 

## **Future Work**

- Create communication sensitive missions.
- Add a communication sensor model in USARSim.
- Improve the usability of MissionLab to launch a swarm of robots.

