

Image-based Rendering



Image-based Rendering (IBR)

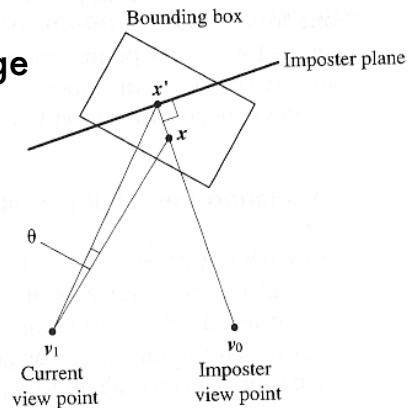


- Goal of all IBR techniques
 - Decouple Rendering Time from Scene Complexity
- Represent geometry as imagery
 - Captured from real scenes
 - Enable imagery not possible with local illumination models
 - Pre-computed from geometry
- Use imagery during rendering

Simple 2D IBR: Planar Imposters



- Replace geometry with texture-mapped billboard
 - Rely on frame coherence
- Use until error is too large
 - How to compute error?
- Question
 - Where/what size is plane?



Varying Rendering Resources



- Partition objects based on distance to viewer
 - Render into different layers
 - Composite layers back-to-front
- Render closer objects more often
 - Devote more rendering resources to them!
- Metrics to determine validity of each layer
 - Geometric, photometric, sampling

Adding and Using Depth Information



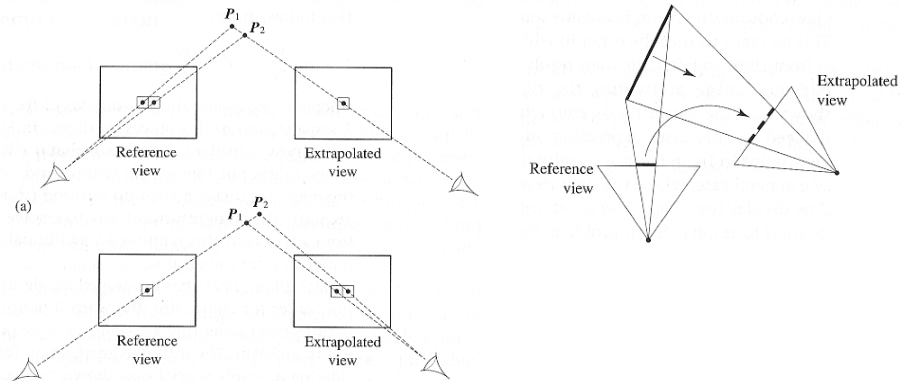
- Three approaches
 - One depth value per imposter (previous technique)
 - | Doesn't support motion parallax, planar nature perceptible
 - Save z-value per pixel
 - | 3D Image Warping
 - Multiple image and depth values per pixel
 - | Layered Depth Images (LDI)

3D Image Warping (Image + Z-buffer)



- Can think of it as sparse data volume
 - Contains visible pixels for a single view
- Can generate a new view
 - Account for 3D structure: parallax, hidden surfaces
- Should be close to old one
 - Necessary data will not be there if eye moves too much

Problems with 3D Image Warping

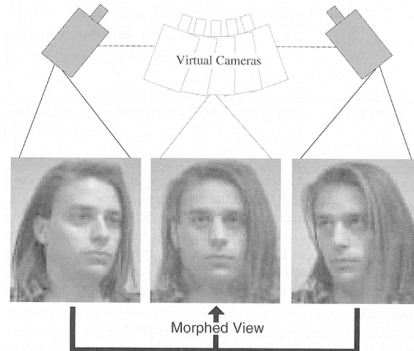


Layered Depth Images

- Improve on 3D Image Warping by adding additional data for each pixel
 - All surfaces intersected by ray through pixel
 - | Save surface normals at each pixel
 - Data size linear with average depth complexity
- Can model a scene with a set of LDIs
 - Becomes a 4D dataset, rather than 3D

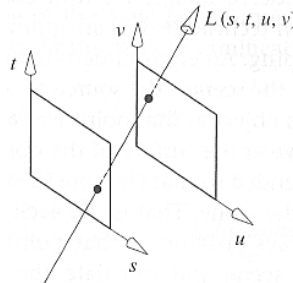
View Interpolation

- Take a collection of depth images
 - Interpolate between any pair of them
- Depth + camera info gives 3D of each pixel



4D Approaches: The Lumigraph or Light Field Rendering

- Store the radiance in all directions from each point in space
 - 5D: $L(x,y,z,\alpha,\beta)$
- Simplify: store only for occlusion free space
 - 4D: $L(s,t,u,v)$



Rendering a Light Field

- Intersect view ray with planes to get (s, t, u, v)
- Set pixel to $L(s, t, u, v)$

