

P, NP, PH, PSPACE

Yufan

Note Title

2/8/2010

A deterministic TM is said to be in $\text{SPACE}(S(n))$ if it uses space $O(S(n))$ on inputs of length n . Similarly it is in $\text{TIME}(t(n))$ if it uses time $O(t(n))$ on such inputs.

A language L is polynomial-time decidable if $\exists k$ and a TM M to decide L s.t.

$$M \in \text{TIME}(n^k)$$

Note that k is independent of n .

e.g. PATH, i.e. does there exist a path between s and t in a given graph has a polynomial-time decider.

Median

Min/Max weight spanning tree.

P is the class of languages with polynomial time TMs.

$$P = \bigcup_K \text{TIME}(n^K)$$

Do all decidable languages belong to P ?

HAM PATH \exists path from s to t that visits every vertex in G exactly once?

SAT Given a boolean formula, \exists a setting of its variables that makes the formula true?

$$F = (x_1 \vee x_2 \vee \bar{x}_3) \wedge (\bar{x}_1 \vee x_3 \vee \bar{x}_2) \wedge (\bar{x}_1 \vee \bar{x}_3 \vee x_2)$$

No polytime algorithms known for these problems.

They can be solved (decided) by polynomial-time

NONDETERMINISTIC TMs.

"guess" the path

"guess" the assignment

Recall that a NTM accepts iff any one of its computation paths accepts. The path amounts to a verification of the YES answer.

We have $\text{NSPACE}(A(n))$ and $\text{NTIME}(t(n))$

NP is the class of languages that can be decided by polynomial-time NTMs.

$$\text{NP} = \bigcup_K \text{NTIME}(n^K)$$

Alternatively, NP is the class of languages with the property that membership ("YES") can be verified in polynomial-time using a polynomial-sized certificate.

e.g. SAT : if F is satisfiable, a valid assignment is the certificate

HAMPATH : if G has a HAM path then the sequence of vertices visited is the certificate.

Clearly $P \subseteq NP$

From Savitch's theorem,

$$NPSPACE = PSPACE$$

Since the space requirement only squares.

$$\text{Also } NTIME(t(n)) \subseteq DTIME(2^{O(t(n))})$$

EXPTIME := Languages that can be decided in exponential time.

$$P \subseteq NP \subseteq PSPACE \subseteq EXP$$

Amazingly, we do not know if

these containments are strict, i.e., \exists a language L

$$L \in EXP \text{ and } L \notin PSPACE$$

$$\text{or } L \in PSPACE \text{ and } L \notin NP$$

$$\text{or } L \in NP \text{ and } L \notin P$$

We know that $P \subsetneq EXP$ from the Time Hierarchy Theorem.

$$L \in NP \Leftrightarrow \exists \text{NTM } M \text{ s.t.}$$

$$L = \{x \mid \exists \text{ accepting path in } M \text{ on input } x\}$$

The class of languages that are complements of languages in NP is called CoNP

$$L \in \text{CoNP} \Leftrightarrow \exists \text{NTM } M \text{ s.t.}$$

$$L = \{x \mid \text{Every valid computation path of } M \text{ is ^{an} accepting for } x\}$$

$$L \in \text{CoNP} \Leftrightarrow \bar{L} \in NP \Leftrightarrow$$

$$\bar{L} = \{x \mid x \notin L\} \quad L = \{x \mid x \text{ is not accepted by a TM for } L \text{ on any path}\}$$

— L is rejected on every path —

How to verify membership in a CoNP language?

Short (polynomial-size) certificate that $x \notin L$,

e.g. G does not have a HAM PATH?

F does not ————— satisfying assignment?

$$\text{SAT} : \{ F \mid \exists x : F(x) = 1 \}$$

$$\overline{\text{SAT}} : \{ F \mid \forall x : F(x) = 0 \}$$

$$\Sigma_2^{\text{SAT}} : \{ F \mid \exists x \forall y F(x, y) = 1 \}$$

$$\Pi_2^{\text{SAT}} : \{ F \mid \forall x \exists y F(x, y) = 0 \}$$

⋮

$$\Sigma_i^{\text{SAT}} : \{ F \mid \underbrace{\exists x_1 \forall x_2 \dots}_{i \text{ quantifiers}} F(x_1, \dots) = 1 \}$$

$$\Pi_i^{\text{SAT}} : \{ F \mid \forall x_1 \dots F(\dots) = 0 \}$$

Alternating Turing Machines that can at each

node of computation accept if any one path emanating from the node accepts or if all paths accept.

$$\text{PH} = \bigcup_i \underbrace{\sum_i \bigcup_k \text{TIME}(n^k)}_{\text{PH} \subseteq \text{PSPACE}} = \bigcup_i \Pi_i \bigcup_k \text{TIME}(n^k)$$

$$\text{PH} \subseteq \text{PSPACE}$$

How hard are problems in PSPACE?

We don't know, but we can define the hardest problems.

A language L is said to be PSPACE-complete if

(a) $L \in \text{PSPACE}$

(b) $\forall B \in \text{PSPACE}$

\exists polynomial-time reduction $B \rightarrow L$

i.e. using L as an oracle/procedure and polynomial additional time, B can be solved in PSPACE

" L is at least as hard as any problem in PSPACE".

(If only (b) holds, L is PSPACE-hard).

Do there exist COMPLETE languages for PSPACE?

TQBF: True Quantified Boolean Formula

$F = \forall x_1, x_2 \exists x_3 \forall x_4 \dots P(x_1, x_2, \dots, x_n)$

TQBF = $\{ F : F \text{ is true} \}$

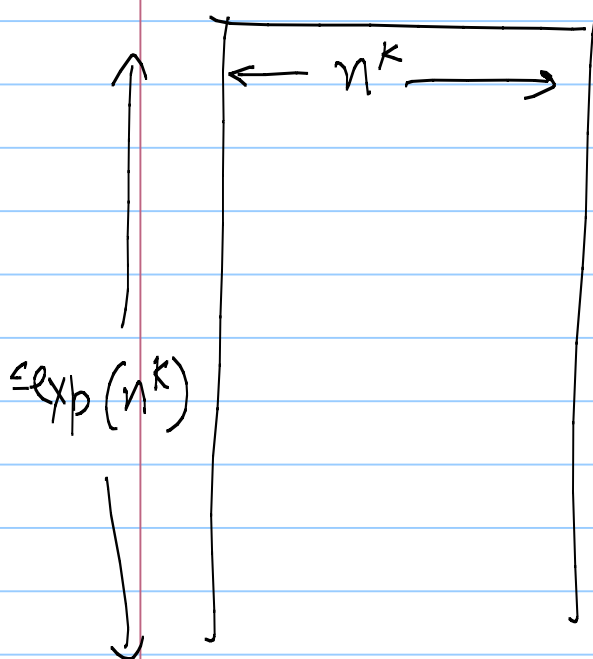
Thm TQBF is PSPACE-complete.

Pf. TQBF \in PSPACE

For this we just give an ATM that matches the quantifiers of a given formula and the depth of the tree is the # variables.

Any problem $B \in$ PSPACE has a reduction
 $B \rightarrow L$

Since $B \in$ PSPACE \exists TM M that decides B
Examine the computation tableau of M on input w



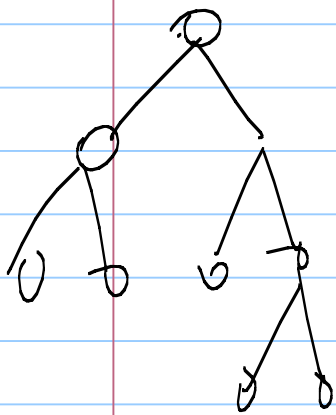
we can write a boolean formula F_B to check that the computation is valid, the start is valid and the end state is ACCEPT.

$w \in B \Leftrightarrow F_B$ is true

But F_B has exponential size!

$F_{\text{start}, \text{accept}, t}$: Formula that checks tableaux from start to accept using at most t steps.

$$F_{s, a, t} = \exists u \left(\phi_{s, u, \lfloor \frac{t}{2} \rfloor} \wedge \phi_{u, a, \lfloor \frac{t}{2} \rfloor} \right)$$



if $t = 1$ or 0 , we can write an explicit formula.

Does this work? No! still exponential size.

We can use universal quantifiers.

$$F_{s, a, t} = \exists u \forall (x, y) \in \{(s, u), (u, a)\} F_{x, y, \lfloor \frac{t}{2} \rfloor}$$

$$\forall x \in \{y, z\} F \equiv \forall x (x=y \vee x=z) \Rightarrow F$$

$$\forall x \neg (x=y \vee x=z) \vee F$$

$$\forall x \neg ((x \rightarrow y) \wedge (y \rightarrow x) \vee \dots)$$

$$\forall x \neg ((\exists y \vee y) \wedge (\exists y \vee x) \vee \dots)$$

Every boolean $F \rightarrow$ AND/OR/NOT. Now $\text{size}(F) = O(n^{2k})$.