

# [MATH2605] Homework 4

Feb. 2 - Feb. 9

## Problem 1: Matlab Practice #2

We will learn writing matlab scripts and using symbolics. Answer or do questions with \*.

1. Try `pwd`. This will show you the current working directory. You can use `cd` command to move to any other directory. You may create a matlab directory in your home directory and move to there.
2. Matlab script is a text file with extension '.m'. Try `edit test1.m`. This will open the matlab editor with a file "test1.m". You can write any matlab command and save the script file. You can execute this script by `test1`.  
\*From internet or matlab help, can you find whether this script is interpreted or compiled?
3. Try `help function`. \*Create a script that takes a matrix, and compute and return the largest and smallest eigenvalues. You may submit hand-written (or printed) copy of the script.
4. We now try symbolics. This will allow you to compute partial derivatives quickly. Try `syms x y real`; This will declare real variables  $x$  and  $y$ .
5. Define a function  $f(x,y)$  by  $f = (3*(1+x)^2 + x*y^3 + y^2) / (1+x^2+y^2)$ .
6. Try `help sym/diff` and read help. \*What is the command that computes  $\frac{\partial f}{\partial x}$  and  $\frac{\partial f}{\partial y}$ ?
7. Try `help pretty` and read help. Try `help simplify` and read help. \*Using the simplify and pretty commands, compute and submit the simplified forms of  $\frac{\partial f}{\partial x}$  and  $\frac{\partial f}{\partial y}$ ?
8. \*What are the commands that compute  $\frac{\partial}{\partial y} \frac{\partial f}{\partial x}$  and  $\frac{\partial}{\partial x} \frac{\partial f}{\partial y}$ ?  
\*Is  $\frac{\partial}{\partial x} \frac{\partial f}{\partial y} = \frac{\partial}{\partial y} \frac{\partial f}{\partial x}$  true?

## Problem 2

Last week, we have computed eigenvalues and eigenvectors of the two matrices  $\mathbf{A} = \begin{pmatrix} -1 & 2 & 2 \\ -1 & 2 & 1 \\ -2 & 2 & 3 \end{pmatrix}$ , and  $\mathbf{B} =$

$$\begin{pmatrix} 1 & 4 & 3 \\ -7 & 8 & 6 \\ 2 & 2 & 3 \end{pmatrix}.$$

The matrix  $\mathbf{A}$  has eigenvalues  $\{1, 1, 2\}$ , where 1 is the eigenvalue with multiplicity 2 that has two linearly independent eigenvectors. In contrast,  $\mathbf{B}$  has eigenvalues  $\{3, 3, 6\}$ , where 3 is the eigenvalue with multiplicity 2, but it has only one linearly independent eigenvector.

Note that  $\mathbf{A}$  has three linearly independent eigenvectors: two associated with 1 and another associated with 2. Therefore, we can construct an invertible eigenvector matrix  $\mathbf{V}_A$  and the diagonal eigenvalue matrix  $\mathbf{D}_A$  so that  $\mathbf{A}\mathbf{V}_A = \mathbf{V}_A\mathbf{D}_A$ . Since  $\mathbf{V}_A$  is invertible, we can right multiply  $\mathbf{V}_A^{-1}$  to obtain an eigenvalue decomposition  $\mathbf{A} = \mathbf{V}_A\mathbf{D}_A\mathbf{V}_A^{-1}$ . Since  $\mathbf{D}_A$  is diagonal, we say  $\mathbf{A}$  is diagonalizable.

However, even though we can construct an eigenvector matrix  $\mathbf{V}_B$  and the diagonal eigenvalue matrix  $\mathbf{D}_B$  so that  $\mathbf{B}\mathbf{V}_B = \mathbf{V}_B\mathbf{D}_B$ , the eigenvector matrix  $\mathbf{V}_B$  is not invertible. There are only two eigenvectors: one associated with 3 and

another associated with 6. We cannot construct a full rank, and therefore invertible, matrix  $\mathbf{V}_B$ . Therefore, we cannot have the eigenvalue decomposition  $\mathbf{B} = \mathbf{V}_B \mathbf{D}_B \mathbf{V}_B^{-1}$ , with a diagonal matrix  $\mathbf{D}_B$ . We say that  $\mathbf{B}$  is not diagonalizable.

In fact, if allow an off-diagonal term in  $\mathbf{D}_B$ , we can make  $\mathbf{B} = \mathbf{V}_B \mathbf{D}_B \mathbf{V}_B^{-1}$ . We can compute this by using the Matlab command *jordan*. Using this command, compute  $\mathbf{V}_B$  and  $\mathbf{D}_B$  and submit the matrix. Also verify that  $\mathbf{B} = \mathbf{V}_B \mathbf{D}_B \mathbf{V}_B^{-1}$ . Note that  $\mathbf{D}_B$  is not a diagonal matrix anymore. This is called the Jordan decomposition.

### Problem 3

Using Matlab, we can plot graphs of nonlinear surfaces.

Try *help meshgrid*, and read some. Try  $[X,Y] = \text{meshgrid}(-3:0.2:3, -3:0.2:3)$ ; . This will create an array  $X$  that varies along rows and  $Y$  that varies through columns.

Now, construct a function  $f(x, y) = x^2 + y^2/4 + 3xy + 2$ , by  $f = X.*X + Y.*Y/4 + 3*X.*Y + 2$ .

You can plot the surface by *surf(X,Y,f); xlabel('x'); ylabel('y'); zlabel('f')*; . Submit a hand-drawn sketch (or printed copy) of this graph.

The contour can be plotted by *contour(X,Y,f,-40:4:40)*. Submit a hand-drawn sketch (or a printed copy) of this contour graph. What each curves in this contour plot stands for?

The gradient of  $f(x, y)$  is  $\nabla f = [2x + 3y \quad y/2 + 3x]^T$ .

Compute the gradient by  $fx = 2*X + 3*Y$ ;  $fy = Y/2 + 3*X$ ;

The gradient vector can be drawn by *quiver(X,Y,fx,fy)*;

You can draw the contour and the gradient vectors together by using the 'hold' command.

Try *contour(X,Y,f,-40:4:40); axis equal; xlabel('x'); ylabel('y'); hold on; quiver(X,Y,fx,fy); hold off*;

What is the angle between the gradient vector and the contour line?

Critical point is the point where  $\nabla f = 0$ . Compute the critical point. Indicate the critical point in your contour graph.