

OpenCL Spec

CS4803DGC Design and Programming of Game Console Spring 2011

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OpenCL

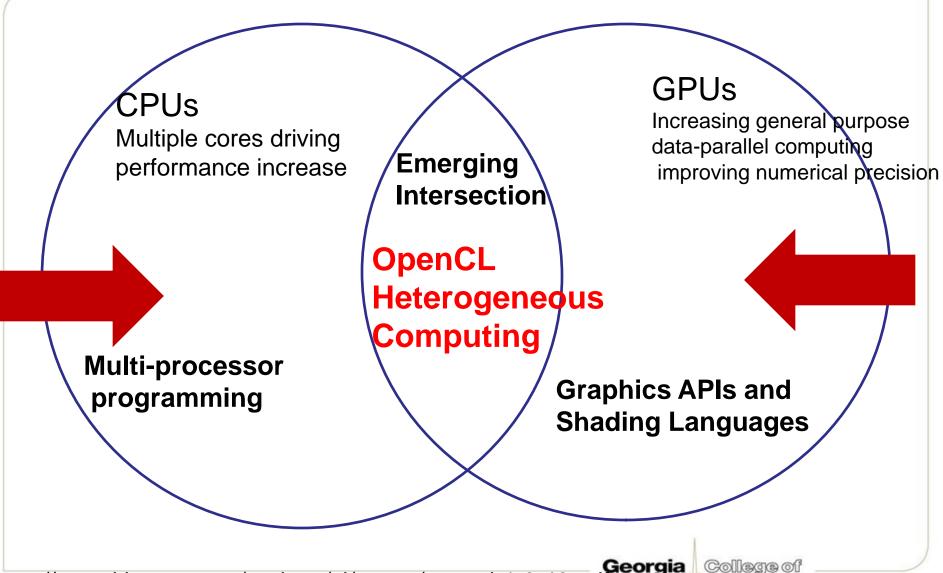
- OpenCL (open computing Language): a framework for writing programs that execute across heterogeneous platforms considering CPUs, GPUs, and other processors.
- Initiated by Apple Inc. Now AMD, Intel, NVIDIA, etc.
- AMD gave up CTM (close to Metal) and decided to support OpenCL
- Nvidia, Intel, Cell support openCL now.





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Processor Parallelism





OpenCL standard ...

- Supports both data- and task-based parallel programming models (CPU: task, GPU: data)
- Utilizes a subset of ISO C99 with extensions for parallelism
- Defines consistent numerical requirements based on IEEE 754
- Defines a configuration profile for handheld and embedded devices
- Efficiently interoperates with OpenGL, OpenGL ES and other graphics APIs



Impacts of openCL

- Software developers write parallel programs that will run on many devices
- Hardware developers target openCL
- Enables OpenCL on mobile and embedded silicon



OpenCL Architecture

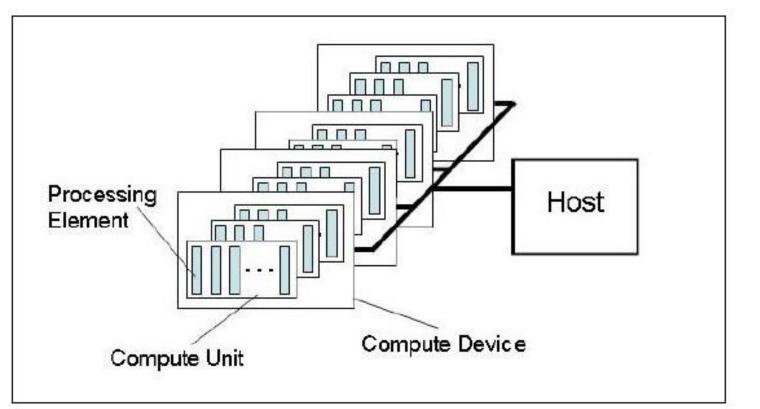
- Platform Model
- Memory Model
- Execution Model
- Programming Model



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Platform Model



One Host+ one ore more compute devices

- -Each compute device is composed of one or more compute units
- -Each compute unit is further divided into one or more processing units



Execution Model

- OpenCL Program:
 - Kernels
 - Basic unit of executable code similar to C function
 - Data-parallel or task-parallel
 - Host Program
 - Collection of compute kernels and internal functions
 - Analogous to a dynamic library



Execution Model

Kernel Execution

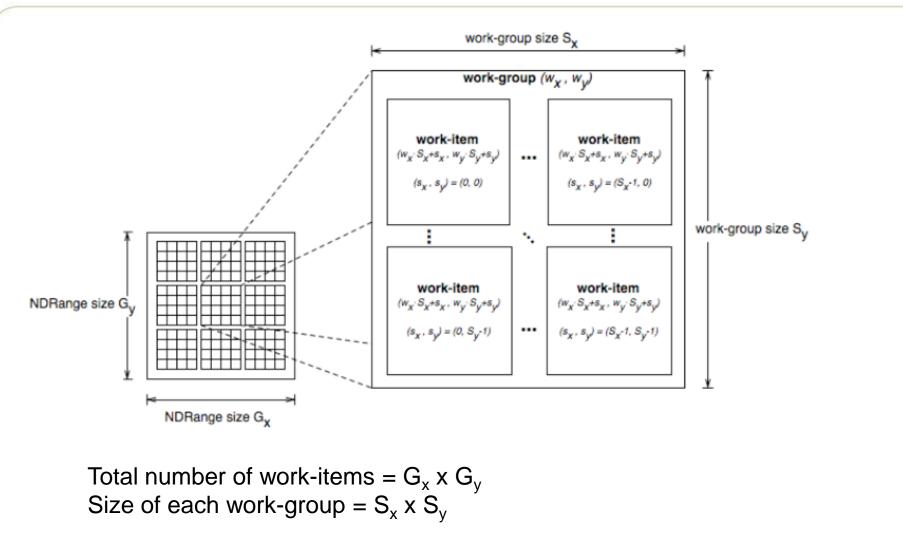
- The host program invokes a kernel over an index space called an *NDRange*
 - NDRange = "N-Dimensional Range"
 - NDRange can be a 1, 2, or 3-dimensional space
- A single kernel instance at a point in the index space is called a *work-item*
 - Work-items have unique global IDs from the index space
 - CUDA thread lds
- Work-items are further grouped into *work-groups*
 - Work-groups have a unique work-group ID
 - Work-items have a unique local ID within a work-group
 - CUDA Block IDs



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An Example of NDR





Context and Command Queues

- Contexts are used to contain and manage the state of the "world"
- Kernels are executed in contexts defined and manipulated by the host
 - Devices
 - Kernels OpenCL functions
 - Program objects kernel source and executable
 - Memory objects

Command-queue - coordinates execution of kernels

- Kernel execution commands
- Memory commands transfer or mapping of memory object data
- Synchronization commands constrains the order of commands
- Applications queue compute kernel execution instances
 - Queued in-order
 - Executed in-order or out-of-order
 - Events are used to implement appropriate synchronization of execution instances



Command Queues

- Command queues associate a context with a device
 - Despite the figure below, they are not a physical connection





Memory Objects

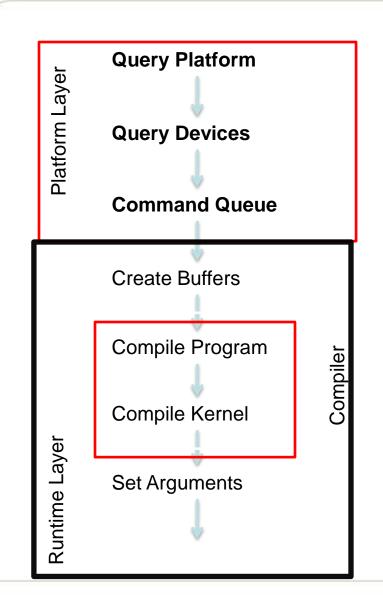
- Memory objects are OpenCL data that can be moved on and off devices
 - Objects are classified as either buffers or images
- Buffers
 - Contiguous chunks of memory stored sequentially and can be accessed directly (arrays, pointers, structs)
 - Read/write capable
- Images
 - Opaque objects (2D or 3D)
 - Can only be accessed via read_image() and write_image()
 - Can either be read or written in a kernel, but not both



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OpenCL Steps



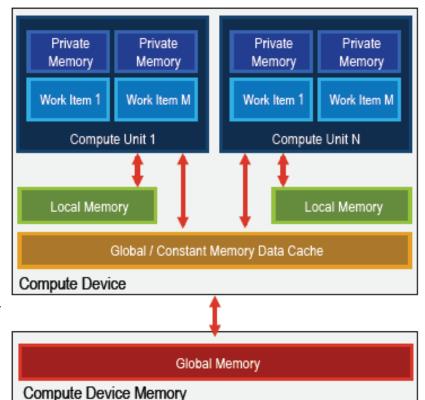
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Memory Model

- Shared memory
 - Relaxed consistency
 - (similar to CUDA)
- Global memory
 - Global memory in CUDA
- Constant memory
 - Constant memory in CUDA
- Local memory (local memory to work group)
 - Shared memory in CUDA
- Private memory (private to a work item)
 - local memory in CUDA

http://www.khronos.org/registry/cl/specs/opencl-1.0.48.pdf



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Memory Region

	Global	Constant	Local	Private
Host	Dynamic allocation Read/write access	Dynamic allocation Read/write access	Dynamic allocation No access	Dynamic allocation No access
Kernel	No allocation Read/Write access	Static allocation Read-only access	Static allocation Read/write access	Static allocation Read/write access



Memory Consistency

- a relaxed consistency memory model
 - Across work-items (threads) no consistency
 - Within a work-item (thread) load/store consistency → in order execution
 - Consistency of memory shared between commands are enforced through synchronization

Data Parallel Programming Model

Define N-Dimensional computation domain

- Each independent element of execution in an N-Dimensional domain is called a *work-item*
- N-Dimensional domain defines the total number of work-items that execute in parallel = global work size
- Work-items can be grouped together workgroup
 - Work-items in group can communicate with each other
 - Can synchronize execution among work-items in group to coordinate memory access

• Execute multiple work-groups in parallel

Mapping of global work size to work-group can be implicit or explicit

Task Parallel Programming Model

- Data-parallel execution model must be implemented by all OpenCL compute devices
- Users express parallelism by
 - using vector data types implemented by the device,
 - enqueuing multiple tasks, and/or
 - enqueuing native kernels developed using a programming model orthogonal to OpenCL.



Synchronization

- Work-items in a single-work group

 Similar to _synchthreads ();
- Synchronization points between commands and command-queues
 - Similar to multiple kernels in CUDA but more generalized.
 - Command-queue barrier
 - Ensure all previously queued commands are executed and memory are reflected.
 - Waiting on an event.



OpenCL Framework

- OpenCL Platform layer: The platform layer allows the host program to discover openCL devices and their capabilities and to create contexts.
- **OpenCL Runtime:** The runtime allows the host program to manipulate contexts once they have been created.
- OpenCL Compiler: The OpenCL compiler creates program executables that contain OpenCL kernels



Platform Layer

- Platform layer allows applications to query for platform specific features
- Querying platform info (i.e., OpenCL profile)

Querying devices

- clGetDeviceIDs()
 - Find out what compute devices are on the system
 - Device types include CPUs, GPUs, or Accelerators
- clGetDeviceInfo()
- Queries the capabilities of the discovered compute devices such as:
 - Number of compute cores
 - NDRange limits
 - Maximum work-group size
 - Sizes of the different memory spaces (constant, local, global)
 - Maximum memory object size



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Platform Layer

Creating contexts

cl_context clCreateContext (cl_context_properties properties, cl_uint num_devices, const cl_device_id *devices, void (*pfn_notify)(const char *errinfo, const void *private_info, size_t cb, void *user_data), void *user_data, cl_int *errcode_ret)

- Contexts are used by the OpenCL runtime to manage objects and execute kernels on one or more devices
- Contexts are associated to one or more devices
- Multiple contexts could be associated to the same device
- clCreateContext() and clCreateContextFromType() returns a handle to the created contexts



Command-Queues

- Command-queues store a set of operations to perform
- Command-queues are associated to a context
- Multiple command-queues can be created to handle independent commands that don't require synchronization
- Execution of the command-queue is guaranteed to be completed at sync points



Memory Objects

- Buffer objects
 - One-dimensional collection of objects (like C arrays)
 - Valid elements include scalar and vector types as well as user defined structures
 - Buffer objects can be accessed via pointers in the kernel

Image objects

- Two- or three-dimensional texture, frame-buffer, or images
- Must be addressed through built-in functions

Sampler objects

- Describes how to sample an image in the kernel
- Addressing modes
- Filtering modes



OpenCL C for Compute Kernels

Derived from ISO C99

- A few restrictions: recursion, function pointers, functions in C99 standard headers ...
- Preprocessing directives defined by C99 are supported

Built-in Data Types

- Scalar and vector data types, Pointers
- Data-type conversion functions: convert_type<_sat><_roundingmode>
- Image types: image2d_t, image3d_t and sampler_t

Built-in Functions — Required

- work-item functions, math.h, read and write image
- Relational, geometric functions, synchronization functions
- Built-in Functions Optional
 - double precision, atomics to global and local memory
 - selection of rounding mode, writes to image3d_t surface

http://www.khronos.org/registry/cl/specs/opencl-1.0.48.pdf

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OpenCL C language Restrictions

- Pointers to functions are not allowed
- Pointers to pointers allowed within a kernel, but not as an argument
- Bit-fields are not supported
- Variable length arrays and structures are not supported
- Recursion is not supported
- Writes to a pointer of types less than 32-bit are not supported
- Double types are not supported, but reserved
 - (Newer CUDA support this)
- 3D Image writes are not supported
- Some restrictions are addressed through extensions

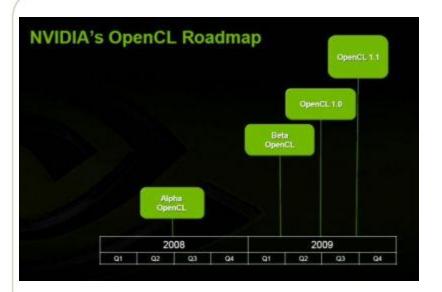


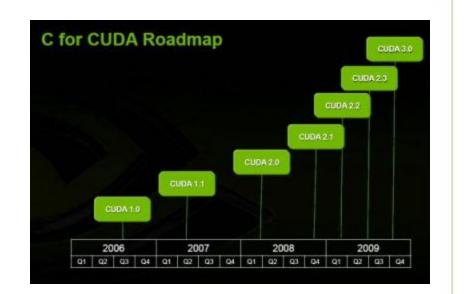
OpenCL vs. CUDA

atecal + TextureMemory consistencyWeak consistencyWeak consistencySynchronizationSynchronization using a work-group barrier (between work-items)Using synch_threads Between threads		OpenCL	CUDA
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Synchronization Synchronization using a work-group barrier (between work-items) Using synch_threads	Memory model	I	
work-group barrier Between threads (between work-items)	Memory consistency	Weak consistency	Weak consistency
	Synchronization	work-group barrier	0.1
Compilation Dynamic compilation Static compilation	Compilation	Dynamic compilation	Static compilation



CUDA ? OpenCL?





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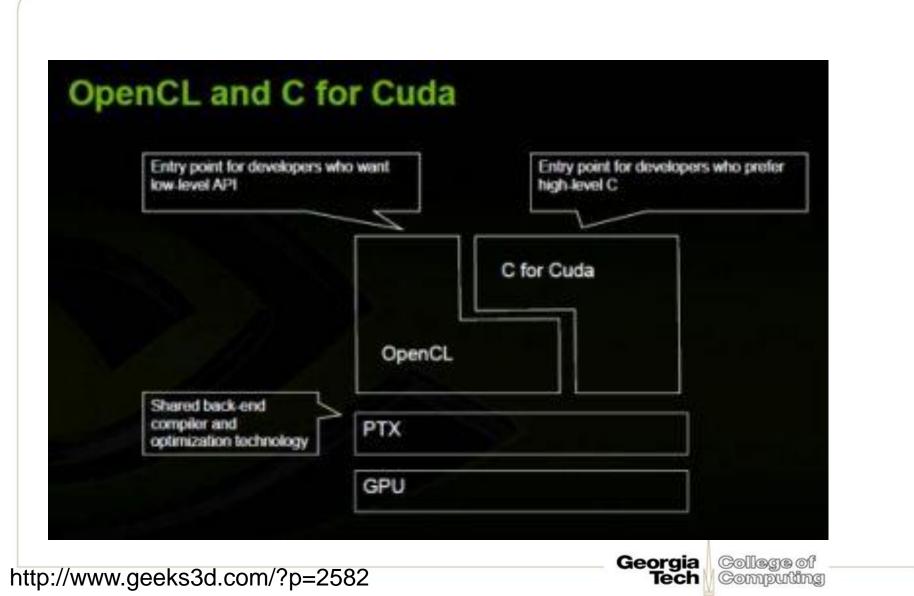
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http://www.geeks3d.com/?p=2582



OpenCL and C for CUDA



OpenCL Compilation System

- LLVM Low Level Virtual Machine
- Kernels compiled to LLVM IR
- Open Source Compiler
 - Platform, OS independent
 - Multiple back ends
- <u>http://llvm.org</u>

