

8803 Machine Learning Theory

Homework # 2

Due: February 18th 2010

This homework is due by the start of class on February 18th. You can either submit the homework via the course page on T-Square or hand it in at the beginning of the class on February 18th.

Groundrules:

- Your work will be graded on correctness, clarity, and conciseness.
- You may collaborate with others on this problem set and consult external sources. However, you must *write your own solutions* and *list your collaborators/sources* for each problem.

Problems:

1. What is the VC-dimension d of axis-parallel rectangles in R^3 ? Specifically, a legal target function is specified by three intervals $[x_{min}, x_{max}]$, $[y_{min}, y_{max}]$, and $[z_{min}, z_{max}]$, and classifies an example (x, y, z) as positive iff $x \in [x_{min}, x_{max}]$, $y \in [y_{min}, y_{max}]$, and $z \in [z_{min}, z_{max}]$.
2. **VC-dimension of linear separators:** In this problem you will prove that the VC-dimension of the class H_n of halfspaces (another term for linear threshold functions) in n dimensions is $n + 1$. We will use the following definition: The *convex hull* of a set of points S is the set of all convex combinations of points in S ; this is the set of all points that can be written as $\sum_{x_i \in S} \lambda_i x_i$, where each $\lambda_i \geq 0$, and $\sum_i \lambda_i = 1$. It is not hard to see that if a halfspace has all points from a set S on one side, then the entire convex hull of S must be on that side as well.
 - (a) [**lower bound**] Prove that $\text{VC-dim}(H_n) \geq n + 1$ by presenting a set of $n + 1$ points in n -dimensional space such that one can partition that set with halfspaces in all possible ways. (And, show how one can partition the set in any desired way.)
 - (b) [**upper bound part 1**] The following is “Radon’s Theorem,” from the 1920’s.

Theorem. *Let S be a set of $n + 2$ points in n dimensions. Then S can be partitioned into two (disjoint) subsets S_1 and S_2 whose convex hulls intersect.*

Show that Radon’s Theorem implies that the VC-dimension of halfspaces is *at most* $n + 1$. Conclude that $\text{VC-dim}(H_n) = n + 1$.
 - (c) [**upper bound part 2**] Now we prove Radon’s Theorem. We will need the following standard fact from linear algebra. If x_1, \dots, x_{n+1} are $n + 1$ points in n -dimensional space, then they are linearly dependent. That is, there exist real values $\lambda_1, \dots, \lambda_{n+1}$ *not all zero* such that $\lambda_1 x_1 + \dots + \lambda_{n+1} x_{n+1} = 0$.

You may now prove Radon’s Theorem however you wish. However, as a suggested first step, prove the following. For any set of $n + 2$ points x_1, \dots, x_{n+2} in n -dimensional space, there exist $\lambda_1, \dots, \lambda_{n+2}$ *not all zero* such that $\sum_i \lambda_i x_i = 0$ and $\sum_i \lambda_i = 0$. (This is called *affine dependence*.)

Extra Credit:

3. **PNF.** The class of k -term PNF is just like k -term DNF except that we use a *parity function* in place of the *OR* function. For instance, the following is a 2-term PNF:

$$x_1x_3\bar{x}_5 \oplus x_2x_4.$$

This function is positive on examples 11100 and 11011, and is negative on examples 00000 and 11110.

Give an algorithm that learns the class of 2-term PNF over $\{0,1\}^n$ in the mistake-bound model. Your algorithm should have a mistake bound polynomial in n and should be efficient (running in polynomial time per example) too. Your algorithm need *not* use 2-term PNF as its hypothesis representation.