

Max-flow:

Monday 10/6/14

input: directed $G=(V,E)$, $s \in V$, $t \in V$,
with for $e \in E$: capacity $c_e > 0$.

output: flow f of max size where

$$\text{Size}(f) = \sum_{w: s \rightarrow w \in E} f_{sw}$$

Constraints:

for all $e \in E$: $0 \leq f_e \leq c_e$

for all $v \in V - \{s, t\}$: flow-in to v = flow-out of v

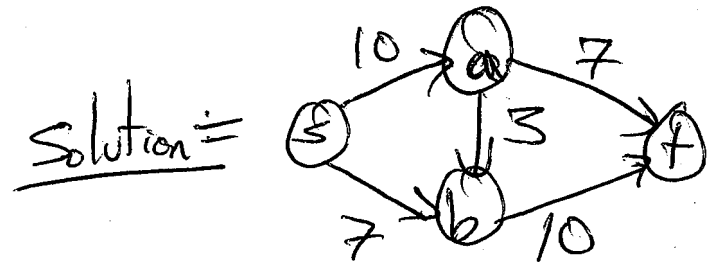
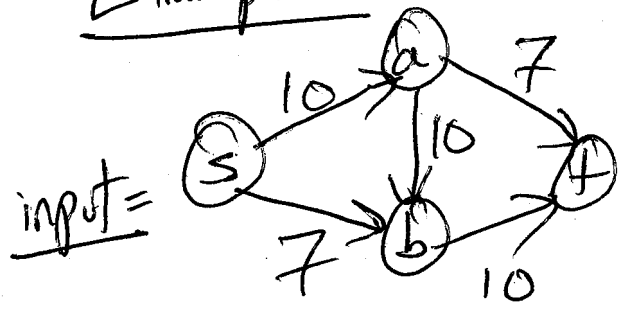
How does simplex work on the LP for Max-flow?

Start with $f_e = 0$ for all $e \in E$.

Try to make some edge constraint tight
i.e., for $e \in E$, make $f_e = c_e$.

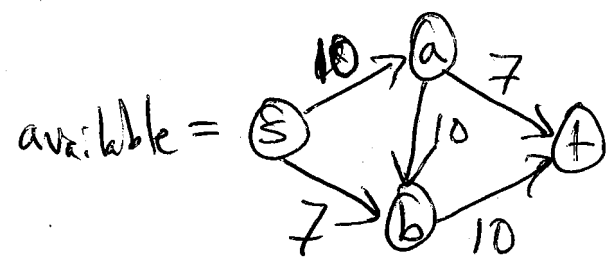
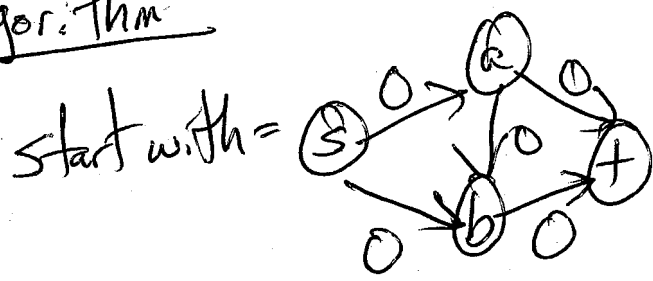
To do this, find an st-path P with available capacity & send as much flow as possible along P.

Example:

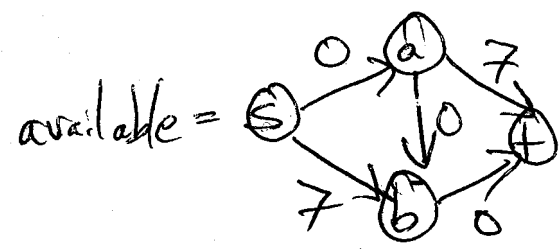
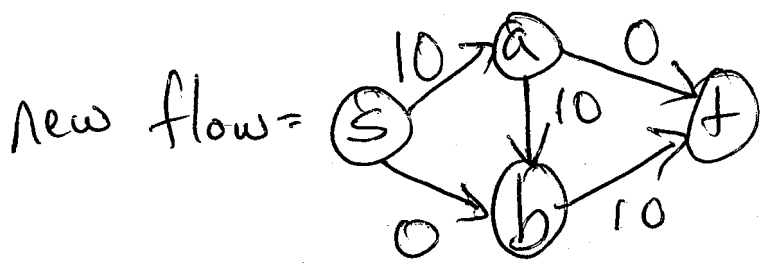


Size(f) = 17

Algorithm:



take path $s \rightarrow a \rightarrow b \rightarrow t$ & send 10 units



No st-path.

Can send flow "backwards" along edge $a \rightarrow b$
 by decreasing its flow
 So add edge $b \rightarrow a$ with available capacity $f_{ab} > 0$.

For a flow network on $G=(V, E)$
 with capacities c_e & a flow f_e

Residual network $G^f=(V, E^f)$

has edges $v \rightarrow w$ with residual capacity r_{vw}

where:

$$r_{vw} = \begin{cases} c_{vw} - f_{vw} & \text{if } \overrightarrow{vw} \in E \text{ \& } f_{vw} < c_{vw} \\ f_{wv} & \text{if } \overleftarrow{vw} \in E \text{ \& } f_{wv} > 0 \end{cases}$$

For earlier example, residual network =

Use path $s \rightarrow b \rightarrow a \rightarrow t$ to send 7 units

New flow =

which is optimal!

Ford-Fulkerson algorithm:

input: $G=(V,E)$ with integer capacities $c_e > 0$ for $e \in E$

1) Set $f_e = 0$ for all $e \in E$

2) Build residual network G^f

3) Check for a st-path P in G^f

4) If no st-path, return (f)

5) Otherwise, let $b = \min$ residual capacity along P in G^f

$$\text{i.e., } b = \min_{e \in P} r_e$$

6) Augment f by b units along P :

for each ~~e~~ $\vec{vw} \in P$

if \vec{vw} is a forward edge (so $\vec{vw} \in E$)

then $\uparrow f_{vw}$ by b

if \vec{vw} is a backward edge (so $\overleftarrow{vw} \in E$)

then $\downarrow f_{vw}$ by b .

7) Repeat, until no st-path in G^f .

Running time:

If capacities are integers,

then flow increases by ≥ 1 unit per round

So if $C = \text{size of max flow}$

then $\leq C$ rounds.

each round uses a BFS/DFS,

So $O(|V| + |E|)$ per round.

$= O(|E|)$ assuming G is connected.

$\Rightarrow O(|E|C)$ total time

Pseudopolynomial running time since it depends on the numbers in the input

Edmonds-Karp [72]: $O(|E||V|)$ rounds

$\Rightarrow O(|V||E|^2)$ total time.

Dinits [70] showed $O(|V|^2|E|)$

No requirement on the capacities (don't need to be integers)

In G^f , run BFS & take a shortest path to augment

\uparrow # of edges (don't worry about any weights)

Observations about Ford-Fulkerson:

When can edges get added or deleted from G^f :

1) If $\vec{vw} \in E$ & is a forward edge then

a) \vec{vw} is deleted if it becomes saturated (i.e., if $b = r_{vw}$)

b) \vec{wv} is added if \vec{vw} had zero flow ($f_{vw} = 0$)

2) If $\vec{zv} \in E$ is a ~~forward~~ backward edge then

a) \vec{zv} is deleted if flow along \vec{vz} is removed ($b = r_{zv} = f_{vz}$)

b) \vec{vz} is added if it was full before ($f_{vz} = c_{vz}$)

Note: New edges are reverse of edges in P (which are in G_f)

Argue that an edge can get added or deleted from G_f at most $O(n)$ times for Edmonds-Karp, and thus $O(mn)$ rounds

$m = |E|$
 $n = |V|$

For a BFS tree T ,
 $s = \text{level } 0$, mark neighbors of s level 1, their unmarked neighbors as level 2 etc.

For a shortest path P , where

$$P = v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_{i-1} \rightarrow v_i$$

$$\text{So } v_0 = s \ \& \ v_i = t$$

then v_i is on level i , otherwise there is a shorter path.

And max level is $\leq n$.

Claim: During the entire algorithm, for a vertex v , its level(v) is non-decreasing.

Proof of claim:

for edge \vec{vw} to get added to G^f

then \vec{wv} is in P so $\text{level}(w) < \text{level}(v)$

So this new edge \vec{vw} goes from
higher level \rightarrow lower level
 $\text{level}(v) > \text{level}(w)$

So adding \vec{vw} can't make
any vertex closer to s &
hence it doesn't \downarrow any vertices
level. \square

At least one edge \vec{vw} is deleted from G^f in
each round because b is set to
saturate at least one edge of P .

If \vec{vw} is deleted with v on level i
& w on level $i+1$.

We may add \vec{vw} back in if $\vec{wv} \in P$ but then
 $\text{level}(w) < \text{level}(v)$ & since $\text{level}(w) \geq i+1$ ^{by the claim,}
so when we add edge \vec{vw} back in, $\text{level}(v) \geq i+2$.

(9)

Therefore, an edge can get deleted & added back in $\leq \frac{1}{2}$ times.

Since ≥ 1 edge is deleted per round & are $O(m)$ edges then $O(nm)$ rounds.

Each round takes $O(m)$ time to do a BFS.

So $O(nm^2)$ total time.

Best algorithms take $O(nm)$ time

[Orlin '13], [King-Rao-Tarjan '94]

was $O(nm)$ for $m = \Omega(n^{1+\epsilon})$.