Topics:

- Machine learning intro, applications (CV, NLP, etc.)
- Parametric models and their components

CS 4644 / 7643-A ZSOLT KIRA

Machine Learning Applications



• PSO due tomorrow night!

- Please do it, and give others a chance at waitlist if your background is not sufficient (beef it up and take it next time)
- Do it even if you're on the waitlist!
- **Piazza**: not all enrolled!
 - Enroll now! <u>http://piazza.com/gatech/spring2022/cs46447643a/</u> (Code: DLSPR22)
 - Make it active!
- Office hours start late this week or next week





Collaboration

- Only on HWs and project (not allowed in PSO).
- You may discuss the questions
- Each student writes their own answers
- Write on your homework anyone with whom you collaborate
- Each student must write their own code for the programming part
- Do NOT search for code implementing what we ask; search for concepts

• Zero tolerance on plagiarism

- Neither ethical nor in your best interest
- Always credit your sources
- Don't cheat. We will find out.





• Grace period

- 2 days grace period for each assignment (**EXCEPT PSO**)
 - Intended for checking submission NOT to replace due date
 - No need to ask for grace, no penalty for turning it in within grace period
 - Can NOT use for PS0
- After grace period, you get a 0 (no excuses except medical)
 - Send all medical requests to dean of students (https://studentlife.gatech.edu/)
 - Form: <u>https://gatech-advocate.symplicity.com/care_report/index.php/pid224342</u>
- **DO NOT SEND US ANY MEDICAL INFORMATION!** We do not need any details, just a confirmation from dean of students





CS231n Convolutional Neural Networks for Visual Recognition

Python Numpy Tutorial

This tutorial was contributed by Justin Johnson.

We will use the Python programming language for all assignments in this course. Python is a great generalpurpose programming language on its own, but with the help of a few popular libraries (numpy, scipy, matplotlib) it becomes a powerful environment for scientific computing.

We expect that many of you will have some experience with Python and numpy; for the rest of you, this section will serve as a quick crash course both on the Python programming language and on the use of Python for scientific computing.

http://cs231n.github.io/python-numpy-tutorial/

Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n



Machine Learning Overview

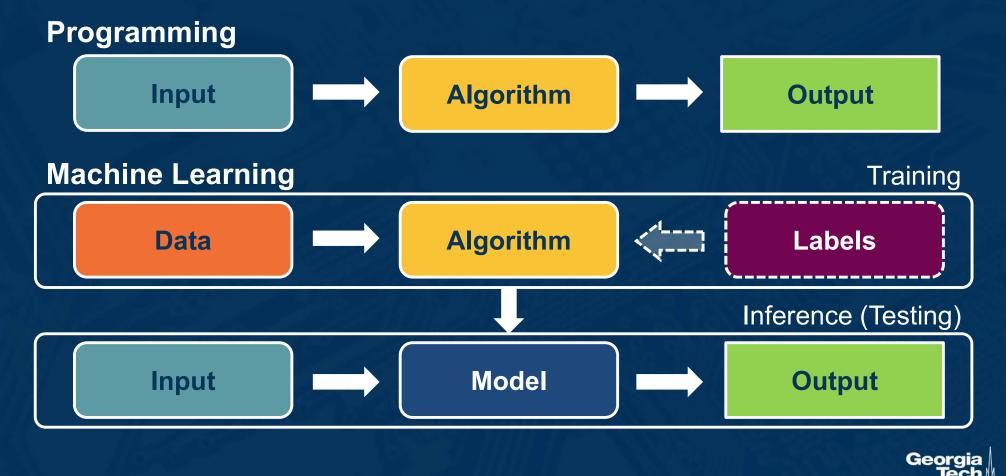


What is Machine Learning (ML)?

"A computer program is said to learn from experience E with respect to some class of tasks T and performance measure P, if its performance at tasks in T, as measured by P, improves with experience E."

Tom Mitchell (Machine Learning, 1997)

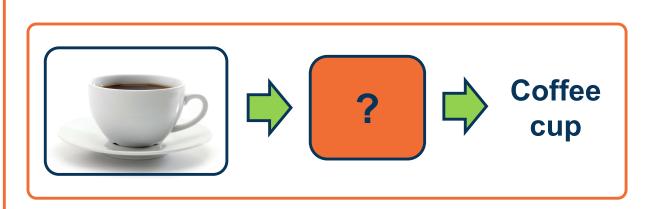
How is it Different than Programming?



Machine learning thrives when it is **difficult to design an algorithm** to perform the task

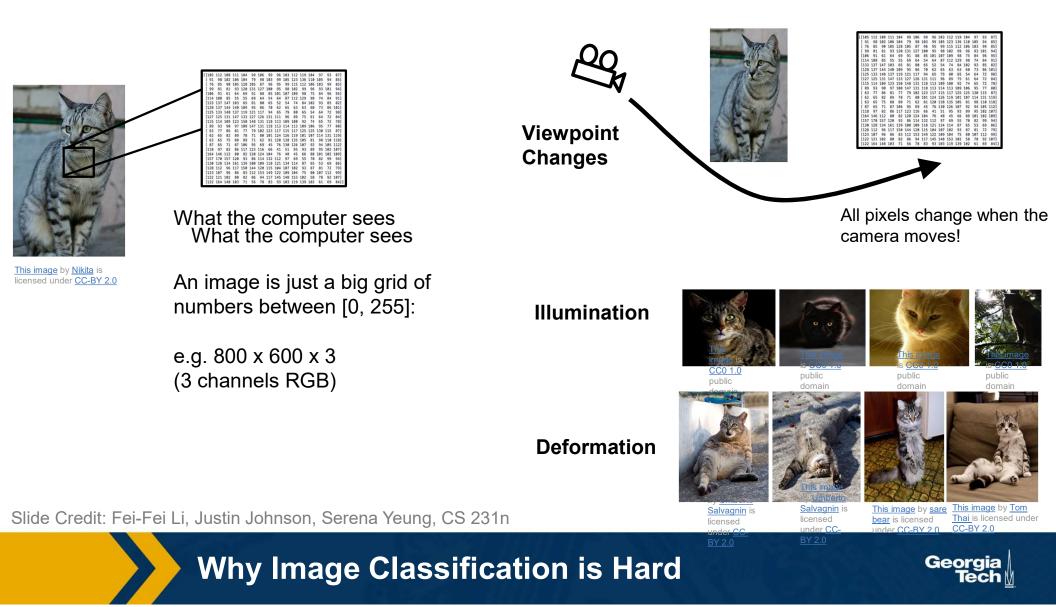
Applications:

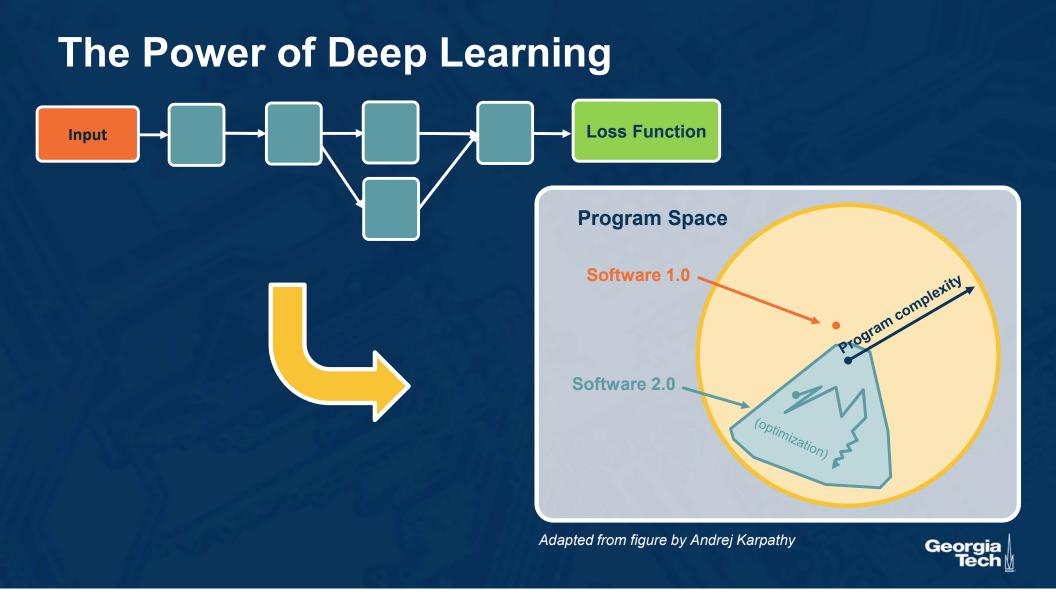
```
algorithm quicksort(A, lo, hi) is
    if lo < hi then
        p := partition(A, lo, hi)
        quicksort(A, lo, p - 1)
        quicksort(A, p + 1, hi)
algorithm partition(A, lo, hi) is
    pivot := A[hi]
    i := lo
    for j := lo to hi do
        if A[j] < pivot then
            swap A[i] with A[j]
        i := i + 1
    swap A[i] with A[hi]
    return i
```



Machine Learning Applications

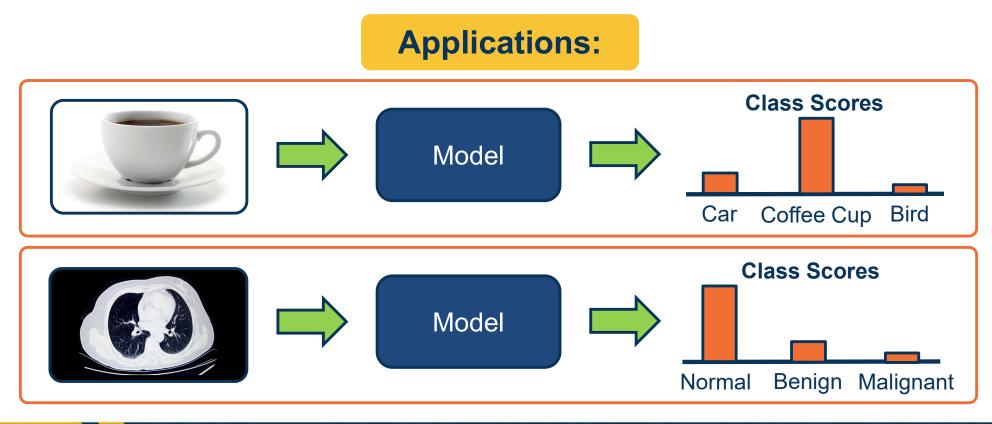






Given an image, output class label

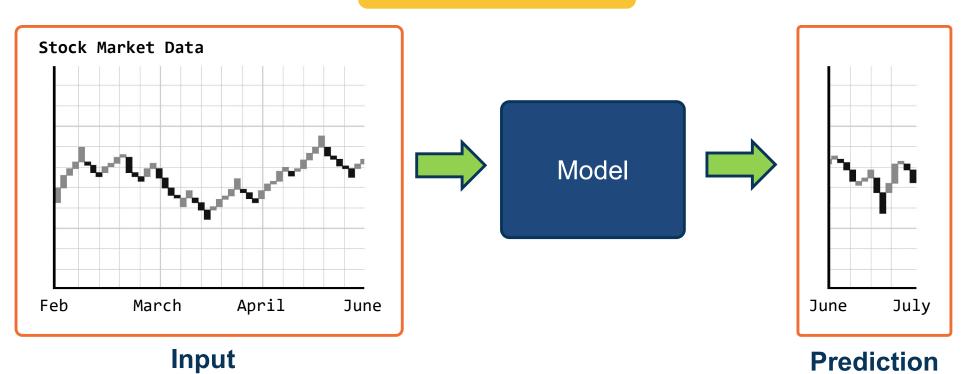
• Often output **probability distribution** over labels



Example: Image Classification

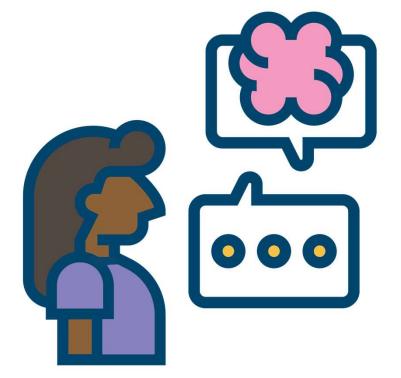
Given a series of measurements, output prediction for next time period

Application:





Example: Time Series Prediction



Very large number of NLP sub-tasks:

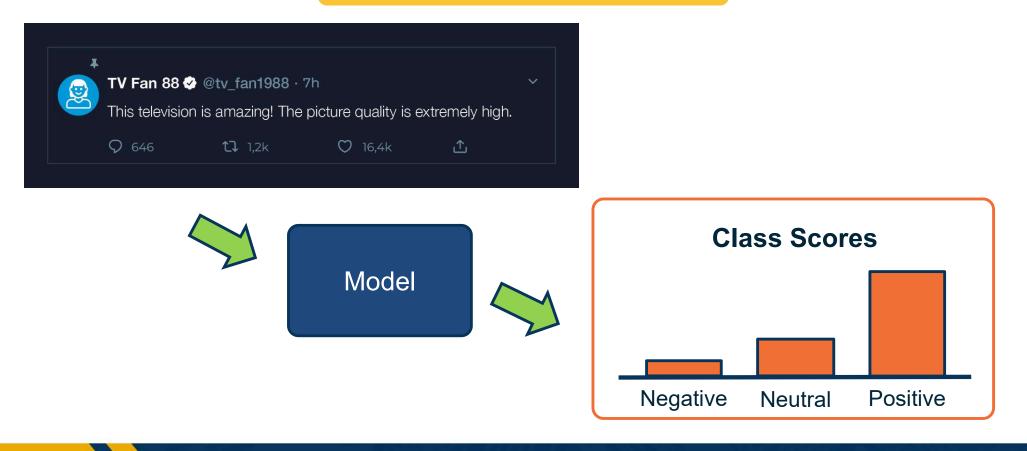
- Syntax Parsing
- Parts of speech
- Named entity recognition
- Summarization
- Similarity / paraphrasing

Different from classification: Variable length sequential inputs and/or outputs

Example: Natural Language Processing (NLP)



Sentiment Analysis:

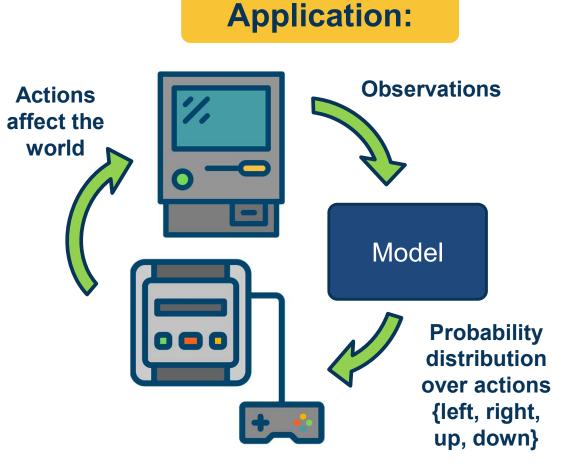


Example: Natural Language Processing (NLP)

Decision-making tasks

- Sequence of inputs/outputs
- Actions affect the environment

Combination of perception and decisionmaking/controls



Example: Decision-Making Tasks

Robotics involves a **combination** of AI/ML techniques:

- Sense: Perception
- Plan: Planning
- Act: Controls/Decision-Making

Some things are **learned** (perception), while others programmed

Evolving landscape





Example: Robotics

Supervised Learning and Parametric Models



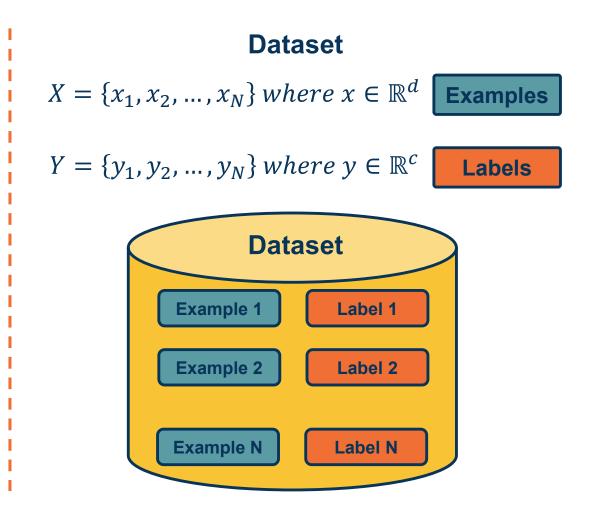
Supervised	Unsupervised	Reinforcement
Learning	Learning	Learning





Supervised Learning

- Train Input: $\{X, Y\}$
- Learning output: $f : X \rightarrow Y$, e.g. P(y|x)





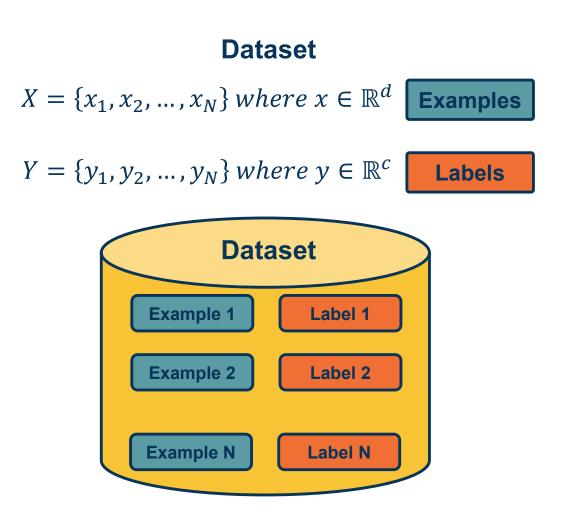


Supervised Learning

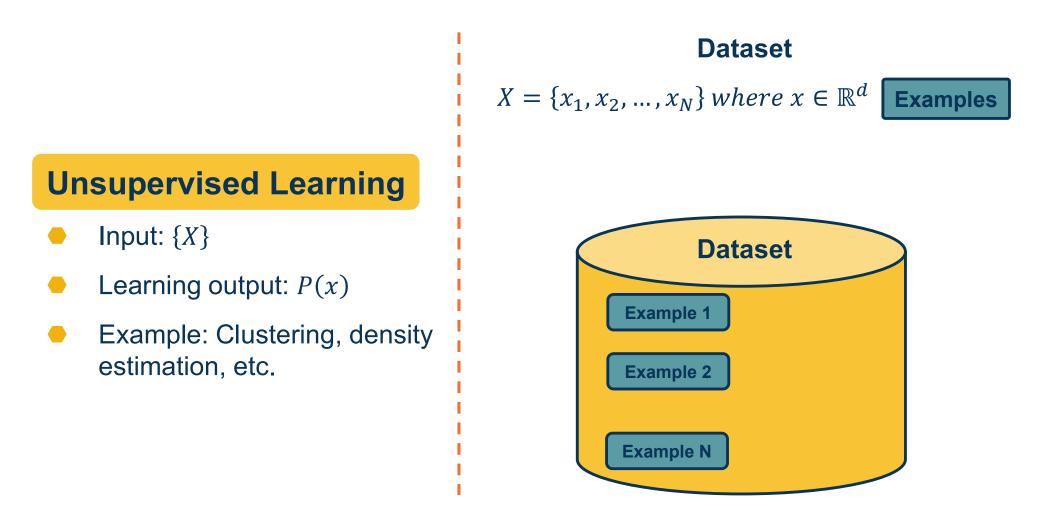
- Train Input: $\{X, Y\}$
- Learning output: $f : X \rightarrow Y$, e.g. P(y|x)

Terminology:

- Model / Hypothesis Class
 - $H: \{h: X \to Y\}$
 - Learning is search in hypothesis space
- Note inputs x_i and y_i are each represented as vectors



Types of Machine Learning

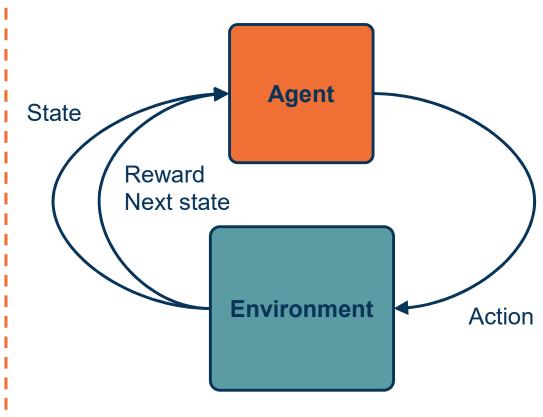


Types of Machine Learning



Reinforcement Learning

- Supervision in form of reward
- No supervision on what action to take



Adapted from: http://cs231n.stanford.edu/slides/2020/lecture_17.pdf





Supervised Learning

- Train Input: $\{X, Y\}$
- Learning output: f: $X \rightarrow Y$, e.g. P(y|x)

Unsupervised Learning

- Input: {X}
- Learning output: P(x)
- Example: Clustering, density estimation, etc.

Reinforcement Learning

- Supervision in form of reward
- No supervision on what action to take

Very often combined

Sometimes within the same model!





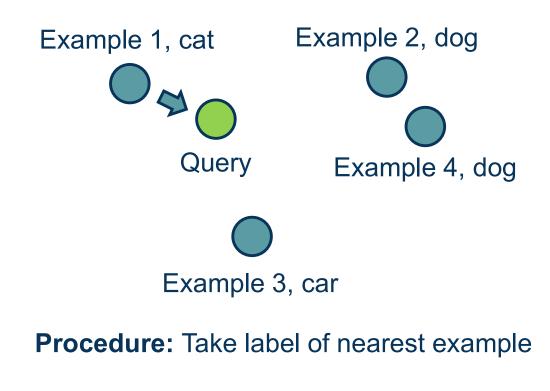
Non-Parametric Model

No explicit model for the function, **examples**:

- Nearest neighbor classifier
- Decision tree

Capacity (size of hypothesis class) grow with size of training data!

Non-Parametric – Nearest Neighbor







• Expensive

- No Learning: most real work done during testing
- For every test sample, must search through all dataset very slow!
- Must use tricks like approximate nearest neighbour search
- Doesn't work well when large number of irrelevant features
 - Distances overwhelmed by noisy features
- Curse of Dimensionality
 - Distances become meaningless in high dimensions

Problems with Instance-Based Learning



k-Nearest Neighbor on images never used.

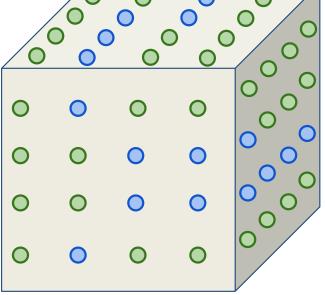
- Curse of dimensionality

 Lots of weird behavior in high-dimensional spaces, e.g. orthogonality of random vectors, percentage of points around shell, etc.

Dimensions = 2Points = 4^2 Dimensions = 1 \bigcirc \bigcirc Points = 40 \mathbf{O} \bigcirc \mathbf{O} \bigcirc 0 \bigcirc \bigcirc \bigcirc \bigcirc Slide Credit: Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n

Curse of Dimensionality

Dimensions = 3 Points = 4^3



27

Parametric Model

Explicitly model the function $f : X \rightarrow Y$ in the form of a parametrized function f(x, W) = y, **examples**:

Logistic regression/classification

Neural networks

Capacity (size of hypothesis class) **does not** grow with size of training data!

Learning is **search**

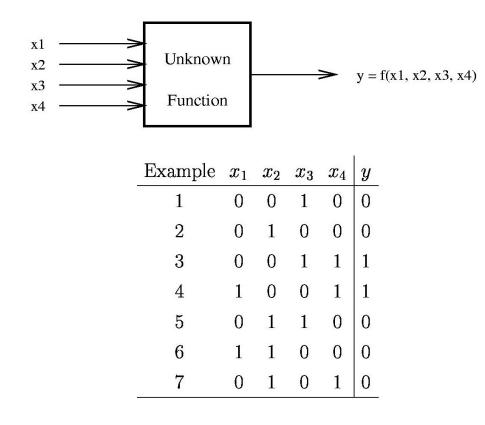
Supervised Learning

Parametric – Linear Classifier

$$f(x,W) = Wx + b$$



A Learning Problem



No Assumptions means no learning

Learning from a Broader Perspective

Training Stage: Training Data { (x_i, y_i) } \rightarrow h (Learning)

Testing Stage Test Data $x \rightarrow h(x)$ (Apply function, Evaluate error)





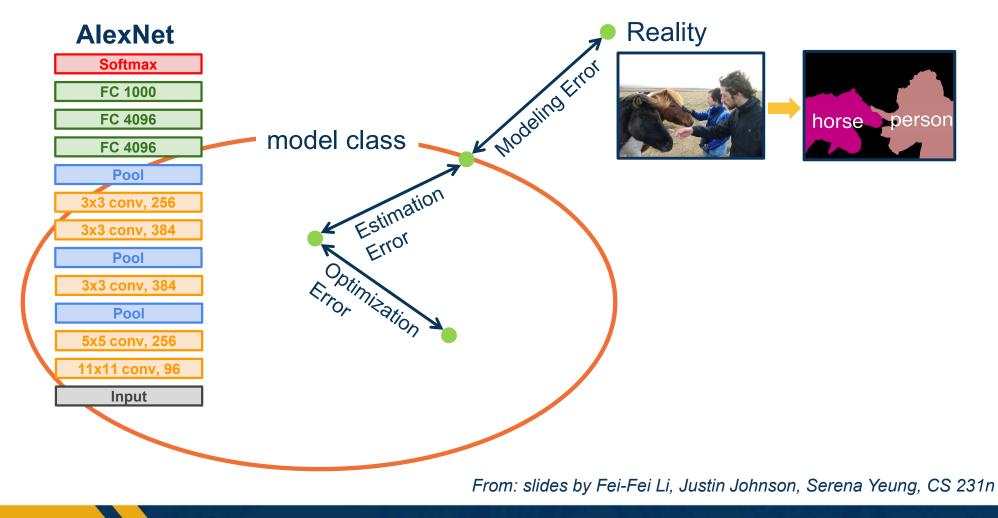
Probabilities to rescue:

X and Y are random variables $D = (x_1, y_1), (x_2, y_2), ..., (x_N, y_N) \sim P(X,Y)$

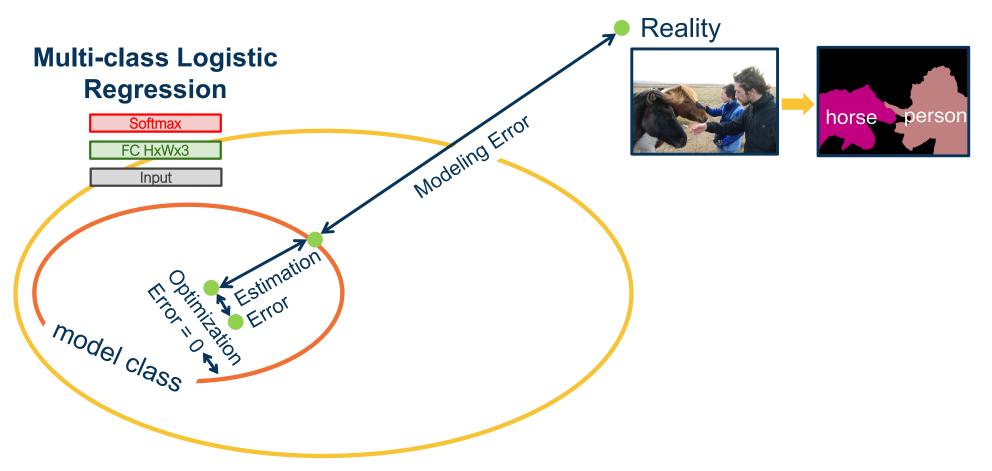
IID: Independent Identically Distributed
 Both training & testing data sampled IID from P(X,Y)
 Learn on training set
 Have some hope of *generalizing* to test set





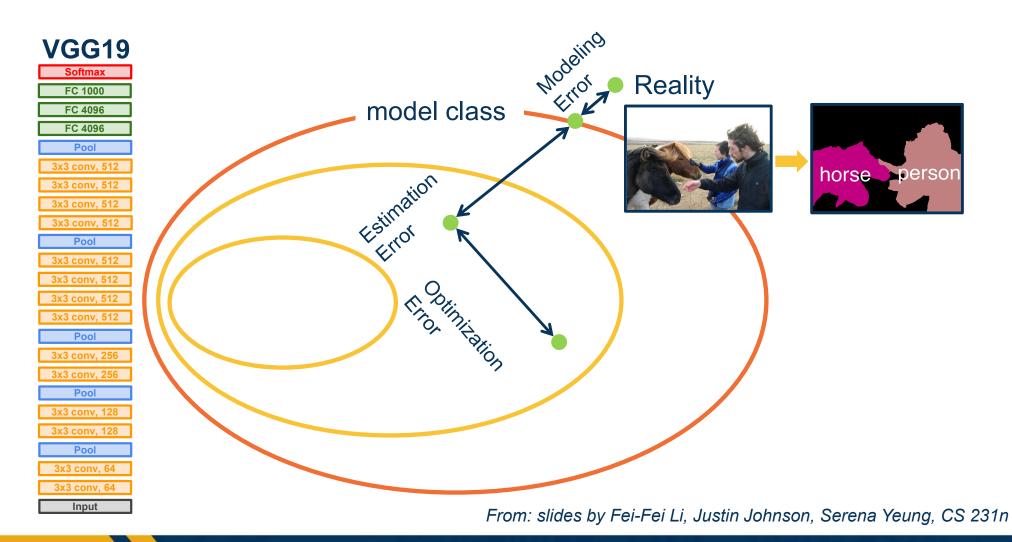






From: slides by Fei-Fei Li, Justin Johnson, Serena Yeung, CS 231n







20 years of research in Learning Theory oversimplified:

If you have:

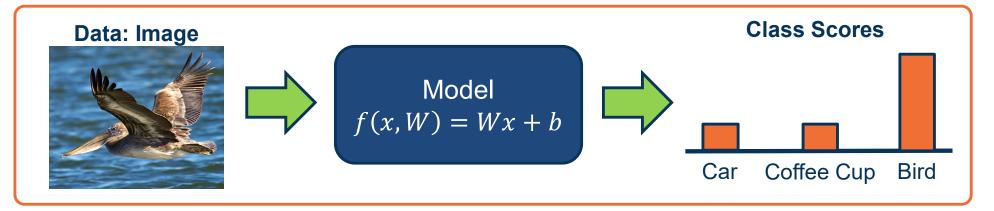
Enough training data D and H is not too complex then *probably* we can generalize to unseen test data

Caveats: A number of recent empirical results question our intuitions built from this clean separation.

Zhang et al., Understanding deep learning requires rethinking generalization







Input {X, Y} where:

- X is an image
- Y is a ground truth label annotated by an expert (human)
- f(x, W) = Wx + b is our model, chosen to be a linear function in this case
- W and b are the parameters (weights) of our model that must be learned





Input image is **high-dimensional**

- For example n=512 so 512x512 image = 262,144 pixels
- Learning a classifier with highdimensional inputs is hard

Before deep learning, it was typical to perform **feature engineering**

 Hand-design algorithms for converting raw input into a lowerdimensional set of features



$$x = \begin{bmatrix} x_{11} & x_{12} & & x_{1n} \\ x_{21} & x_{22} & \cdots & x_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \cdots & x_{nn} \end{bmatrix}$$

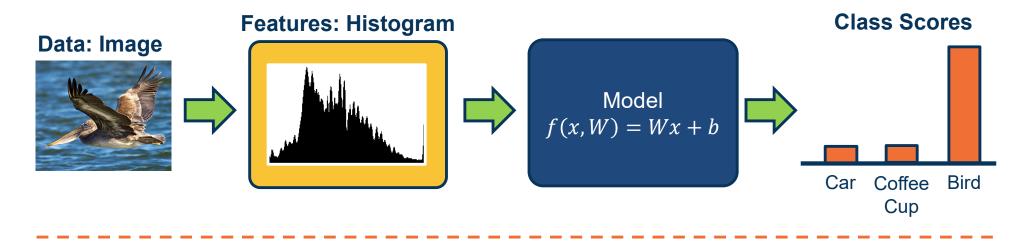
Input Representation: Feature Engineering

Example: Color histogram

- Vector of numbers representing number of pixels fitting within each bin
- We will later see that learning the feature representation itself is much more effective



Input Representation: Feature Engineering

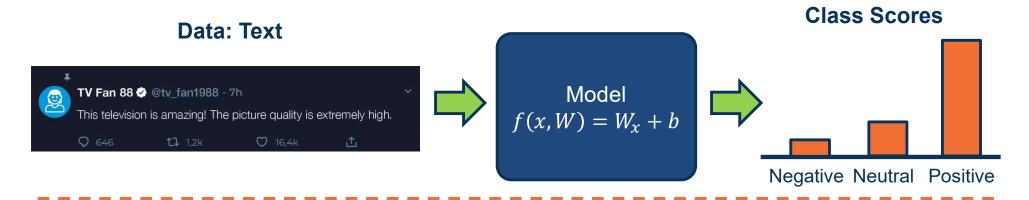


Input {X, Y} where:

- X is an image histogram
- Y is a ground truth label represented a probability distribution
- f(x, W) = Wx + b is our model, chosen to be a linear function in this case
- W and b are the weights of our model that must be learned

Example: Image Classification





Input {X, Y} where:

- X is a sentence
- Y is a ground truth label annotated by an expert (human)
- f(x,W) = Wx + b is our model, chosen to be a linear function in this case
- W and b are the weights of our model that must be learned

Word Histogram

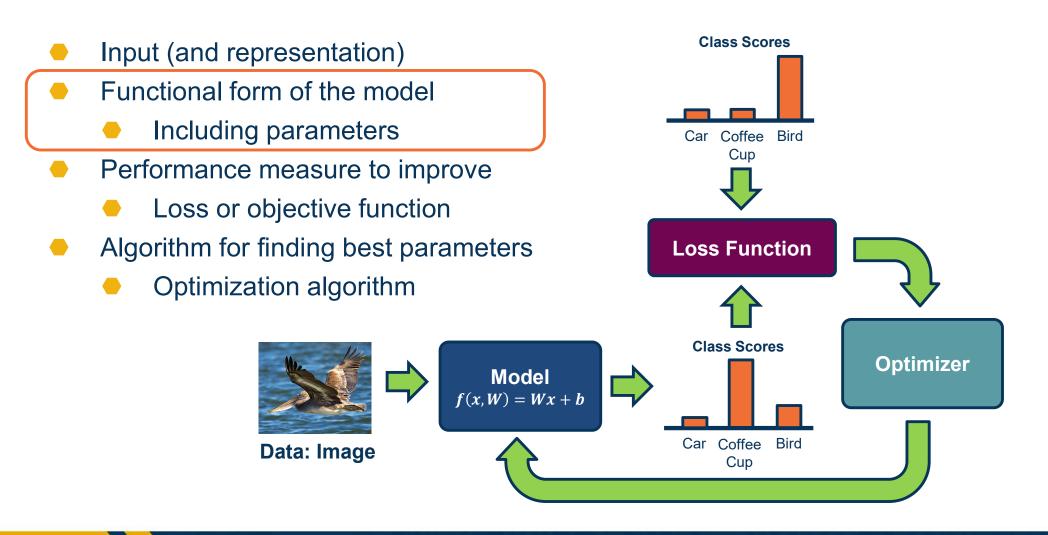
Word	Count	
this	1	
that	0	
is	2	
extremely	1	
hello	0	
onomatopoeia	0	

Example: Image Classification

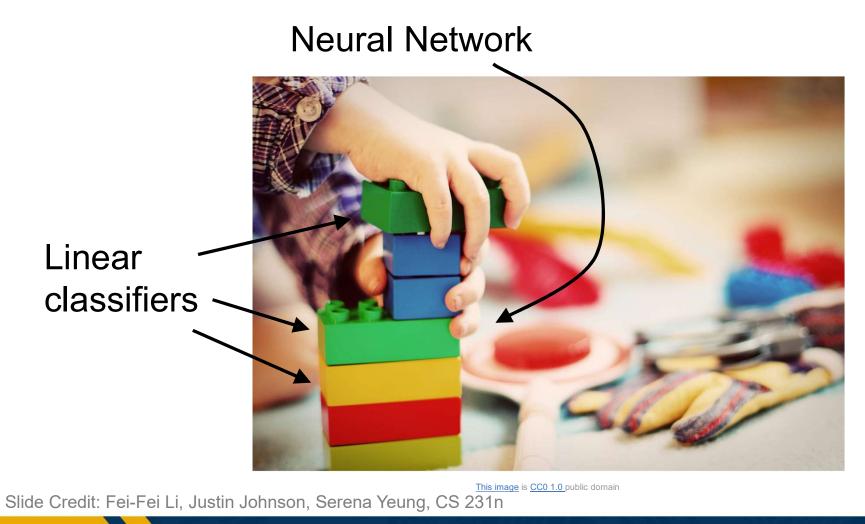


Components of a Parametric Learning Algorithm



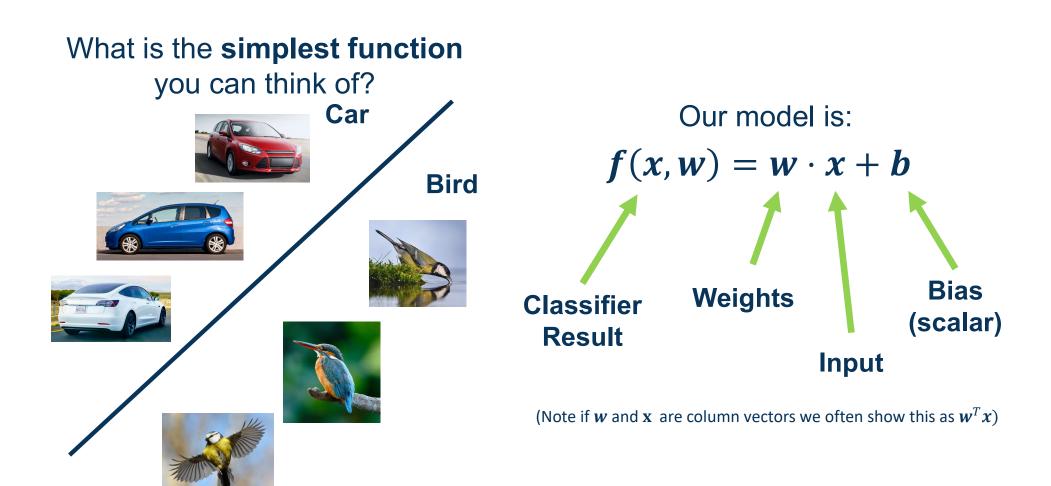


Components of a Parametric Model



Deep Learning as Legos

Georg







Linear Classification and Regression

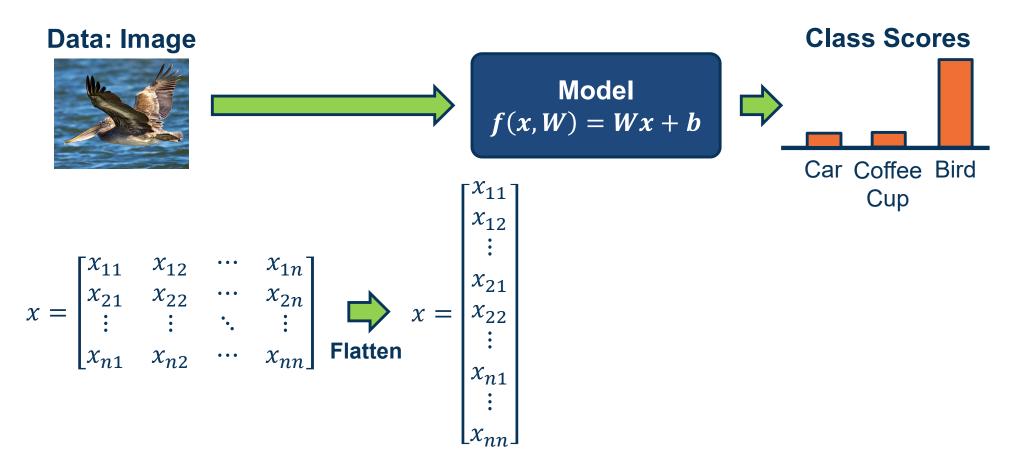
Simple linear classifier:

- Calculate score: $f(x, w) = w \cdot x + b$
- Binary classification rule
 (*w* is a vector):

 $y = \begin{cases} 1 & \text{if } f(x, w) > = 0 \\ 0 & \text{otherwise} \end{cases}$

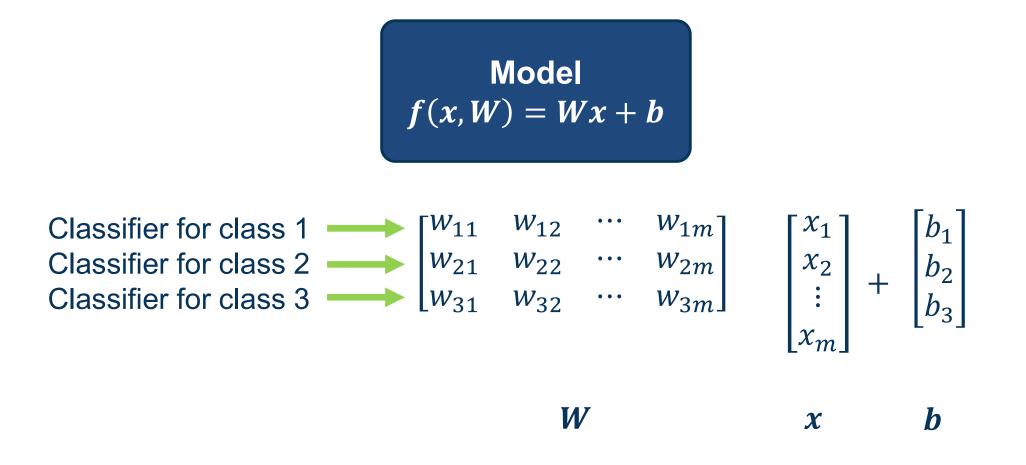
For multi-class classifier take class with highest (max) score f(x, W) = Wx + b





To simplify notation we will refer to inputs as $x_1 \cdots x_m$ where $m = n \times n$

Input Dimensionality



(Note that in practice, implementations can use xW instead, assuming a different shape for W. That is just a different convention and is equivalent.)



- We can move the bias term into the weight matrix, and a "1" at the end of the input
- Results in one matrix-vector multiplication!

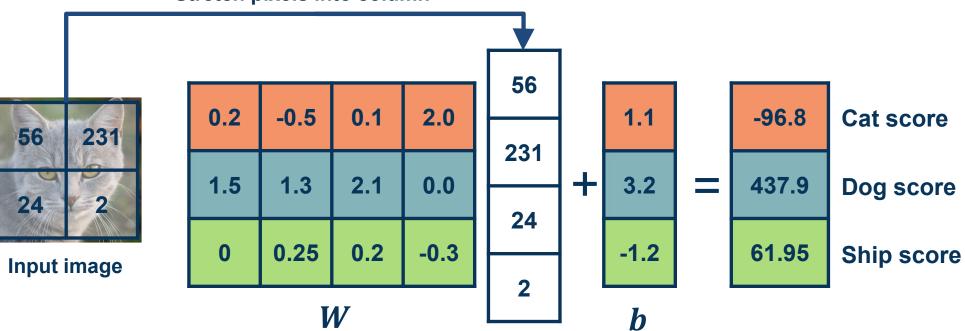
Model f(x, W) = Wx + b

 $\begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1m} & b_1 \\ w_{21} & w_{22} & \cdots & w_{2m} & b_2 \\ w_{31} & w_{32} & \cdots & w_{3m} & b_3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_m \\ 1 \end{bmatrix}$





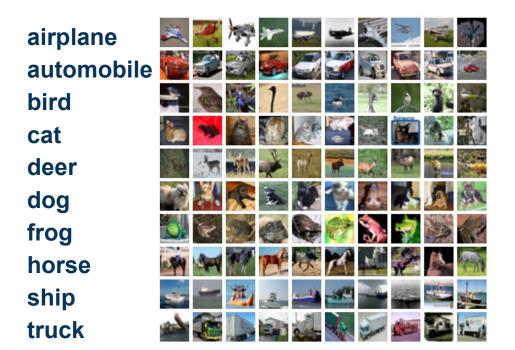
Example with an image with 4 pixels, and 3 classes (cat/dog/ship)



Stretch pixels into column

Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n





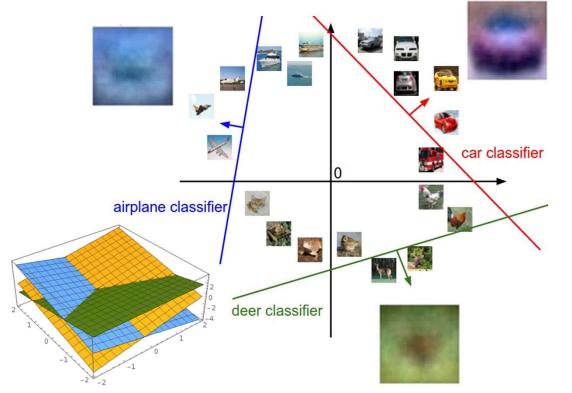
Visual Viewpoint

We can convert the weight vector back into the shape of the image and visualize



Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n





Geometric Viewpoint

f(x,W) = Wx + b



Array of **32x32x3** numbers (3072 numbers total)

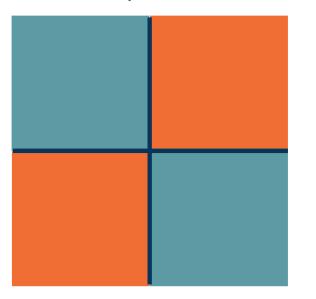
Plot created using Wolfram Cloud

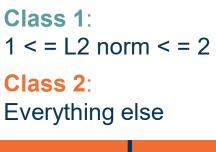
Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n





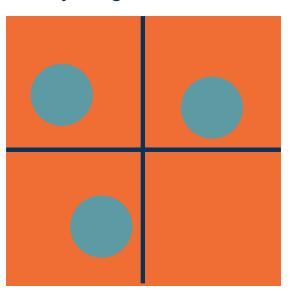
Class 1: number of pixels > 0 odd Class 2: number of pixels > 0 even





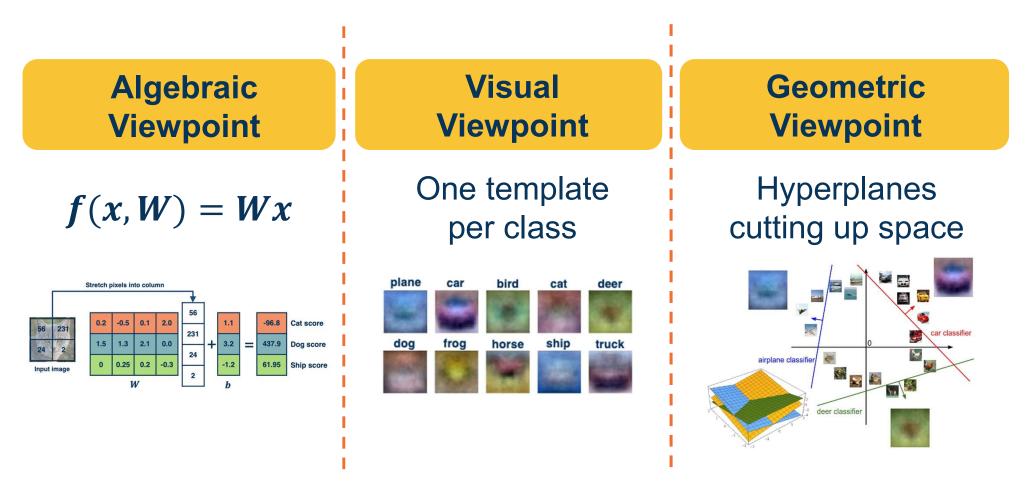


Class 1: Three modes Class 2: Everything else



Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n



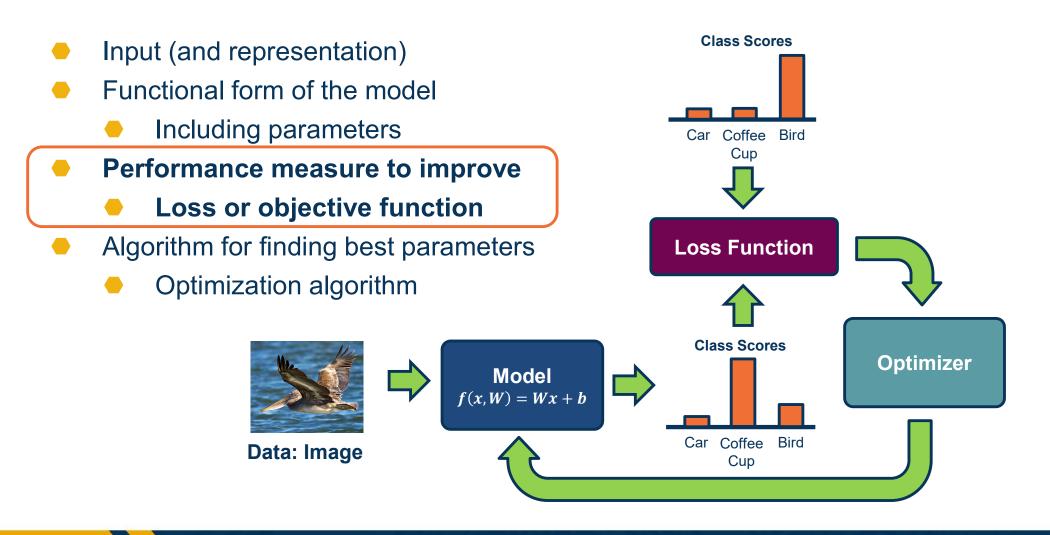


Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n



Performance Measure for a Classifier



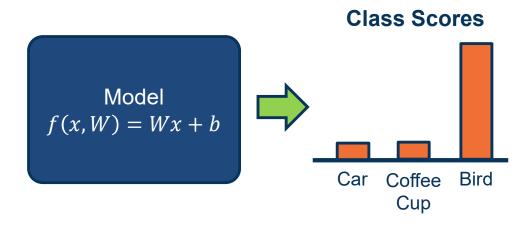


Components of a Parametric Model

- The output of a classifier can be considered a score
- For binary classifier, use rule:

 $y = \begin{cases} 1 & \text{if } f(x, w) > = 0 \\ 0 & \text{otherwise} \end{cases}$

- Can be used for many classes by considering one class versus all the rest (one versus all)
- For multi-class classifier can take the maximum



Classification using Scores

Several issues with scores:

- Not very interpretable (no bounded value)
- We often want probabilities
- More interpretable
- Can relate to probabilistic view of machine learning

We use the **softmax** function to convert scores to probabilities

$$s = f(x, W)$$
 Scores

$$P(Y = k | X = x) = \frac{e^{s_k}}{\sum_j e^{s_j}}$$
 Softmax
Function



We need a performance measure to **optimize**

- Penalizes model for being wrong
- Allows us to modify the model to reduce this penalty
- Known as an objective or loss function

In machine learning we use **empirical risk minimization**

- Reduce the loss over the training dataset
- We average the loss over the training data

Given a dataset of examples:

 $\{(x_i, y_i)\}_{i=1}^N$

Where x_i is image and y_i is (integer) label

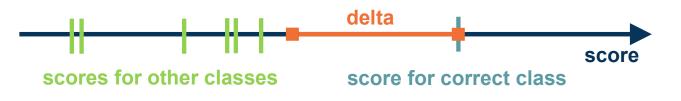
Loss over the dataset is a sum of loss over examples:

 $L = \frac{1}{N} \sum L_1(f(x_i, W), y_i)$





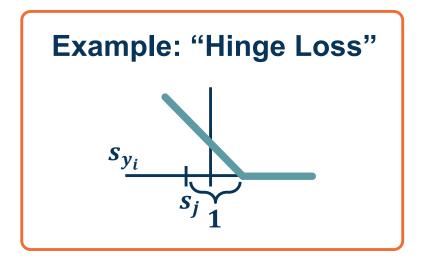
Given an example $(x_{i,}y_{i})$ where x_{i} is the image and where y_{i} is the (integer) label,



and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_{i} = \sum_{j \neq y_{i}} \begin{cases} 0 & \text{if } s_{y_{i}} \geq s_{j} + \\ s_{j} - s_{y_{i}} + 1 & \text{otherwise} \end{cases}$$
$$= \sum_{j \neq y_{i}} max(0, s_{j} - s_{y_{i}} + 1)$$



Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n

Performance Measure for Scores

1

Given an example $(x_{i,}y_{i})$ where x_{i} is the image and where y_{i} is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

 $max(0, s_j - s_{y_i} + 1)$

the SVM loss has the form:

 $= \max(0, 5.1 - 3.2 + 1)$

 $+\max(0, -1.7 - 3.2 + 1)$

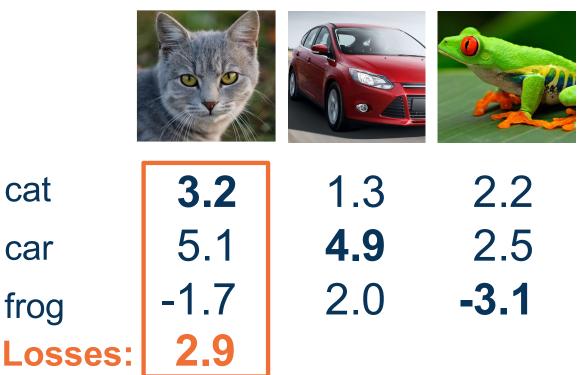
 $= \max(0, 2.9) + \max(0, -3.9)$

 $L_i =$

= 2.9 + 0

= 2.9

Suppose: 3 training examples, 3 classes. With some *W* the scores f(x,W)=Wx are:



Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n

SVM Loss Example



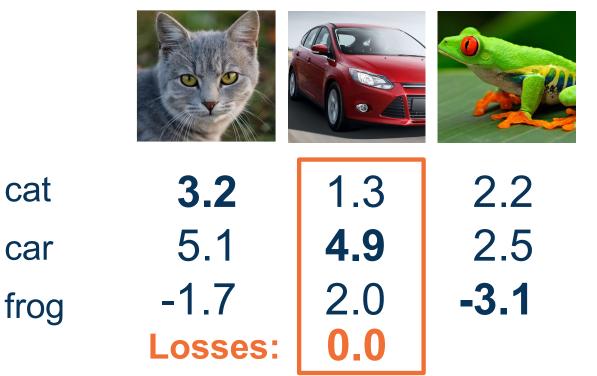
Given an example $(x_{i,}y_{i})$ where x_{i} is the image and where y_{i} is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

= 0

the SVM loss has the form: $L_{i} = \sum_{j \neq y_{i}} max(0, s_{j} - s_{y_{i}} + 1)$ = max(0, 1.3 - 4.9 + 1) + max(0, 2.0 - 4.9 + 1) = max(0, -2.6) + max(0, -1.9) = 0 + 0 Cat

Suppose: 3 training examples, 3 classes. With some *W* the scores f(x,W)=Wx are:



Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n

SVM Loss Example

Given an example $(x_{i,}y_{i})$ where x_{i} is the image and where y_{i} is the (integer) label,

and using the shorthand for the scores vector: $s = f(x_i, W)$

the SVM loss has the form:

$$L_i = \sum_{j \neq y_i} max(0, s_j - s_{y_i} + 1)$$

L = (2.9 + 0 + 12.9)/3 = **5.27** Suppose: 3 training examples, 3 classes. With some *W* the scores f(x,W)=Wx are:



cat	3.2	1.3	2.2
car	5.1	4.9	2.5
frog	-1.7	2.0	-3.1
osses:	2.9	0	12.9

Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS 231n

SVM Loss Example



- We will learn complex, parameterized functions
 - Start w/ simple building blocks such as linear classifiers
- Key is to learn parameters, but learning is hard
 - Sources of generalization error
 - Add bias/assumptions via architecture, loss, optimizer
- Components of parametric classifiers:
 - Input/Output, Model (function), Loss function, Optimizer
 - Example: Image/Label, Linear Classifier, Hinge Loss, ?

