Modern OLTP Indexes (Part 2)

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Recap

Versioned Latch Coupling

- Optimistic coupling scheme where writers are <u>not</u> blocked on readers.
- Provides the benefits of optimistic coupling without wasting too much work.
- Every latch has a version counter.
- Writers traverse down the tree like a reader
 - Acquire latch in target node to block other writers.
 - Increment version counter before releasing latch.
 - Writer thread increments version counter and acquires latch in a single compare-and-swap instruction.

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• Reference

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Bw-Tree

- Latch-free B+Tree index built for the Microsoft Hekaton project.
- Key Idea 1: Delta Updates
 - ▶ No in-place updates.
 - Reduces cache invalidation.
- Key Idea 2: Mapping Table
 - Allows for CaS of physical locations of pages.
- Reference

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Today's Agenda

- Trie Index
- Trie Variants
 - Judy Arrays (HP)
 - ART Index (HyPer)
 - Masstree (Silo)

Trie Index

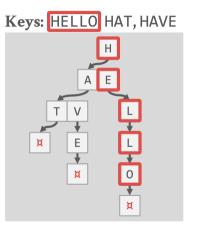
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Observation

- The inner node keys in a B+Tree cannot tell you whether a key exists in the index.
- You must always traverse to the leaf node.
- This means that you could have (at least) one buffer pool page miss per level in the tree just to find out a key does not exist.

Trie Index

- Use a **digital representation** of keys to examine prefixes one-by-one instead of comparing entire key.
 - ▶ *a.k.a.*, Digital Search Tree, Prefix Tree.



Properties

- Shape only depends on key space and lengths.
 - Does not depend on existing keys or insertion order.
 - Does not require rebalancing operations.
- All operations have O(k) complexity where <u>k</u> is the length of the key.

- The path to a leaf node represents the key of the leaf
- Keys are stored implicitly and can be reconstructed from paths.

- The **span** of a trie level is the number of bits that each partial key / digit represents.
 - ▶ If the digit exists in the corpus, then store a pointer to the next level in the trie branch.

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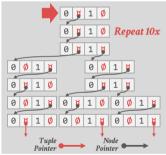
- Otherwise, store null.
- This determines the <u>fan-out</u> of each node and the **physical height** of the tree.

1-bit Span Trie **K10**→ 00000000 K25→ 00000000 **K31**→ 00000000 Tuple Pointer Node Pointer

00001010

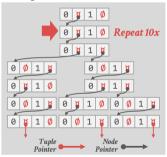
00011001

1-bit Span Trie



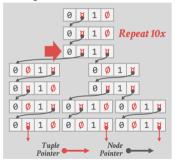
K10→	0	9999999	00001010
K25→	0	9999996	00011001
K31→	0	9000000	00011111

1-bit Span Trie



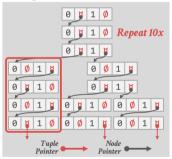
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K10→	00000000	00001010
K25→	00000000	00011001
K31→	00000000	00011111

1-bit Span Trie



		1		-
K10 → 0000				
K25 → 0000				
K31 → 0000	00006	000	1	1111

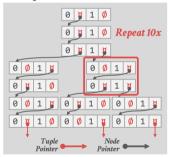
1-bit Span Trie



K10 → 00000000	0000 <mark>1010</mark>
K25 → 00000000	00011001
K31 → 00000000	00011111



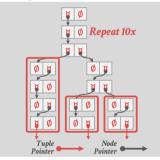
1-bit Span Trie



K10→	00000000	00001010
K25→	00000000	0001 <mark>10</mark> 01
K31→	00000000	0001 <mark>11</mark> 11



1-bit Span Trie



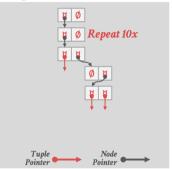
K10→	00000000	00001010
K25→	00000000	00011001
K31→	00000000	00011111



Radix Tree

- Omit all nodes with **only** a single child.
 - ▶ a.k.a., Patricia Tree.
- Can produce false positives
- So the DBMS always checks the original tuple to see whether a key matches.

1-bit Span Radix Tree



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Trie Variants

- Judy Arrays (HP)
- ART Index (HyPer)
- Masstree (Silo)

Judy Arrays

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Judy Arrays

- Variant of a 256-way radix tree (since a byte is 8 bits)
- Goal: Minimize the amount of cache misses per lookup
- First known radix tree that supports adaptive node representation.

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- Three array types
 - **Judy1:** Bit array that maps integer keys to true/false.
 - **JudyL**: Map integer keys to integer values.
 - **JudySL:** Map variable-length keys to integer values.
- Open-Source Implementation (LGPL).
- Patented by HP in 2000. Expires in 2022.
- Reference

Judy Arrays

• Do not store meta-data about node in its header.

- This could lead to additional cache misses.
- Instead store meta-data in the pointer to that node.

• Pack meta-data about a node in 128-bit fat pointers stored in its parent node.

- Node Type
- Population Count
- Child Key Prefix / Value (if only one child below)
- 64-bit Child Pointer
- Reference

Node Types

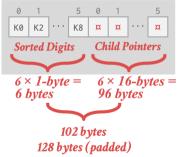
- Every node can store up to 256 digits.
- Not all nodes will be 100% full though.
- Adapt node's organization based on its keys.
 - Linear Node: Sparse Populations (*i.e.*, small number of digits at a level)

- Bitmap Node: Typical Populations
- Uncompressed Node: Dense Population

Linear Nodes

- Store sorted list of partial prefixes up to two cache lines.
 - Original spec was one cache line
- Store separate array of pointers to children ordered according to prefix sorted.
- Can do a linear scan on sorted digits to find a match.

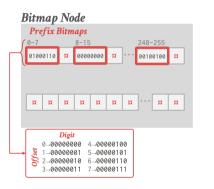
Linear Node



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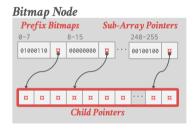
Bitmap Nodes

- 256-bit map to mark whether a prefix (*i.e.*, digit) is present in node.
- Bitmap is divided into eight one-byte chunks
- Each chunk has a pointer to a sub-array with pointers to child nodes.



Bitmap Nodes

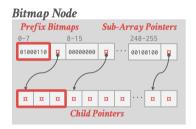
- To look up a digit (*e.g.,* "1")
- Check at offset 1 in prefix bitmap
- Count the number of 1s that came before offset
- Position to jump into the chunk's sub-array



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Bitmap Nodes

- There is a maximum size for the child pointer array
- Although we could present 256 digits in the prefix bitmap, we don't have enough space to store pointers for all of them



Adaptive Radix Tree (ART)

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Adaptive Radix Tree (ART)

- Developed for TUM's HyPer DBMS in 2013.
- 256-way radix tree that supports different node types based on its population.

- Stores meta-data about each node in its header.
- Reference

ART vs. JUDY

• Difference 1: Node Types

- Judy has three node types with different organizations.
- ART has four nodes types that (mostly) vary in the maximum number of children.

• Difference 2: Value Type

- ▶ Judy is a general-purpose associative array. It "owns" the keys and values.
- ▶ ART is a table index and does not need to cover the full keys. Values are pointers to tuples.

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- Store only the 8-bit digits that exist at a given node in a sorted array.
- The offset in sorted digit array corresponds to offset in value array.
- Pack in multiple digits into a single node to improve cache locality.
- First two node types support a small number of digits at that node.
- Use SIMD to quickly find a matching digit per node.

Node4







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• Instead of storing 1-byte digits, maintain an array of 1-byte offsets to a child pointer array that is indexed on the digit bits.

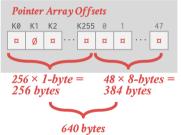
Node48



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• Instead of storing 1-byte digits, maintain an array of 1-byte offsets to a child pointer array that is indexed on the digit bits.

Node48



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- Store an array of 256 pointers to child nodes.
- This covers all possible values in 8-bit digits.
- Same as the Judy Array's Uncompressed Node.

Node256



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Binary Comparable Keys

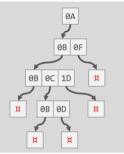
- Not all attribute types can be decomposed into binary comparable digits for a radix tree.
 - Unsigned Integers: Byte order must be flipped for little endian machines.
 - **Signed Integers:** Flip two's-complement so that negative numbers are smaller than positive.
 - Floats: Classify into group (neg vs. pos, normalized vs. denormalized), then store as unsigned integer.

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Compound: Transform each attribute separately.

Binary Comparable Keys

8-bit Span Radix Tree

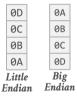


Int Key: 168496141

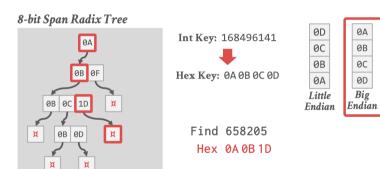
Hex Key: 0A 0B 0C 0D

Find 658205

Hex 0A 0B 1D



Binary Comparable Keys



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MassTree

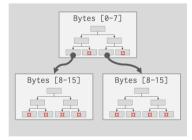
 $\textbf{A} \equiv \textbf{A} = \textbf{A} \equiv \textbf{A} = \textbf{O} \textbf{A} \textbf{C} \qquad \textbf{38} / \textbf{43}$

Masstree

- Instead of using different layouts for each trie node based on its size, use an entire B+Tree.
- Part of the Harvard Silo project.
 - Each B+tree represents 8-byte span.
 - Optimized for long keys (e.g., URLs).
 - Uses a latching protocol that is similar to versioned latches.
 - In any trie node, you can have pointers to tuples in the leaf nodes of the B+tree

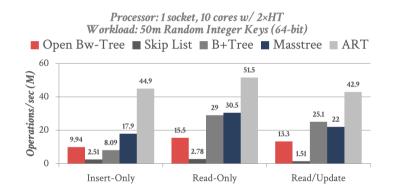
• Reference

Masstree



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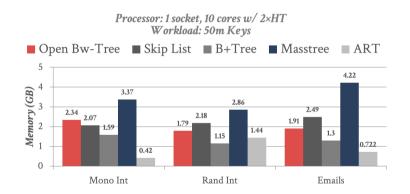
In-Memory Indexes: Performance



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In-Memory Indexes: Performance



Source

Conclusion

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Conclusion

- Bw-Tree vs ART.
- Radix trees have interesting properties, but a well-written B+tree is still a solid design choice.

- Next Class
 - Executing a query