# Lecture 16: Index Concurrency Control

CREATING THE NEXT®

## Administrivia

- Project 2 Proposal due on Nov 2
- Assignment 4 due on Nov 14



# Today's Agenda

Recap

Latches Overview

Hash Table Latching

**B+Tree Concurrency Control** 

Leaf Node Scans

Rlink-Tree

Conclusion



Recap Latches Overview Hash Table Latching B+Tree Concurrency Control Leaf Node Scans



#### **Index Data Structures**

- List of Data Structures: Hash Tables, B+Trees, Radix Trees
- Most DBMSs automatically create an index to enforce **integrity constraints**.
- B+Trees are the way to go for indexing data.



#### Observation

- We assumed that all the data structures that we have discussed so far are single-threaded.
- But we need to allow multiple threads to safely access our data structures to take advantage of additional CPU cores and hide disk I/O stalls.



## **Concurrency Control**

- A **concurrency control protocol** is the method that the DBMS uses to ensure "correct" results for concurrent operations on a shared object.
- A protocol's correctness criteria can vary:
  - ► **Logical Correctness:** Am I reading the data that I am supposed to read?
  - Physical Correctness: Is the internal representation of the object sound?



# **Latches Overview**

### Locks vs. Latches

#### Locks

- Protects the database's logical contents from other txns.
- ► Held for the duration of the transaction.
- ▶ Need to be able to rollback changes.

#### Latches

- Protects the critical parts of the DBMS's internal <u>physical data structures</u> from other threads.
- ▶ Held for the duration of the operation.
- Do not need to be able to rollback changes.



## Locks vs. Latches

	Locks	Latches
Separate	User transactions	Threads
Protect	Database Contents	In-Memory Data Structures
During	Entire Transactions	Critical Sections
Modes	Shared, Exclusive, Update, Intention	Read, Write (a.k.a., Shared, Exclusive)
Deadlock	Detection & Resolution	Avoidance
by	Waits-for, Timeout, Aborts	Coding Discipline
Kept in	Lock Manager	Protected Data Structure

#### Reference



Recap Latches Overvio

#### **Latch Modes**

#### · Read Mode

- Multiple threads can read the same object at the same time.
- ▶ A thread can acquire the read latch if another thread has it in read mode.

#### · Write Mode

- Only one thread can access the object.
- ▶ A thread cannot acquire a write latch if another thread holds the latch in any mode.

	Read	Write
Read	<b>✓</b>	X
Write	X	X



- Blocking OS Mutex
- Test-and-Set Spin Latch
- Reader-Writer Latch



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#### Approach 1: Blocking OS Mutex

- ► Simple to use
- ► Non-scalable (about 25 ns per lock/unlock invocation)
- Example: std::mutex

```
std::mutex m;
m.lock();
// Do something special...
m.unlock();
```



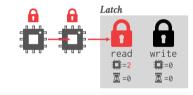
#### Approach 2: Test-and-Set Spin Latch (TAS)

- Very efficient (single instruction to latch/unlatch)
- ▶ Non-scalable, not cache friendly
- Example: std::atomic<T>
- Unlike OS mutex, spin latches do not suspend thread execution
- ► Atomic operations are faster if contention between threads is sufficiently **low**



#### • Approach 3: Reader-Writer Latch

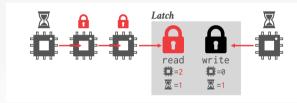
- Allows for concurrent readers
- Must manage read/write queues to avoid starvation
- Can be implemented on top of spinlocks





#### • Approach 3: Reader-Writer Latch

- Allows for concurrent readers
- Must manage read/write queues to avoid starvation
- Can be implemented on top of spinlocks





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# **Hash Table Latching**

## **Hash Table Latching**

- Easy to support concurrent access due to the limited ways in which threads access the data structure.
  - All threads move in the same direction and only access a single page/slot at a time.
  - Deadlocks are <u>not</u> possible.
- To resize the table, take a **global latch** on the entire table (*i.e.*, in the header page).



## **Hash Table Latching**

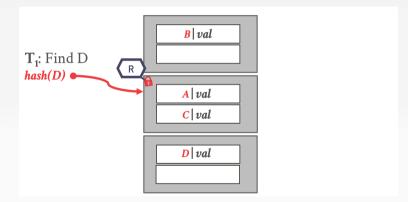
#### • Approach 1: Page Latches

- Each page has its own reader-write latch that protects its entire contents.
- ▶ Threads acquire either a read or write latch before they access a page.

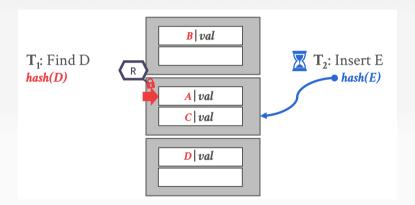
#### • Approach 2: Slot Latches

- Each slot has its own latch.
- Can use a single mode latch to reduce meta-data and computational overhead.

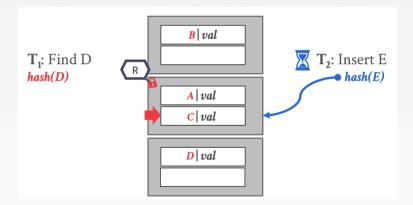




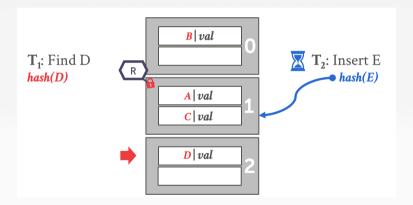




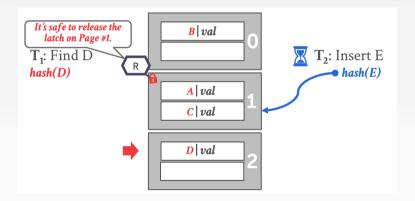




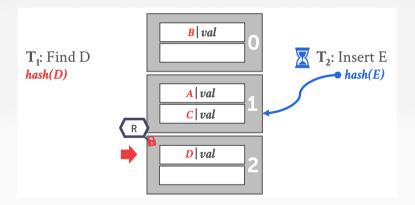




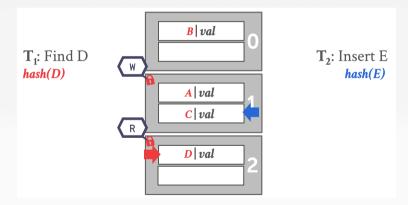




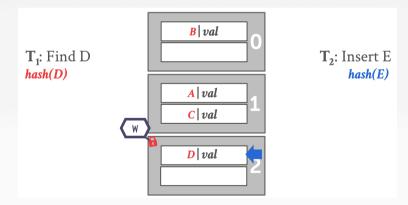




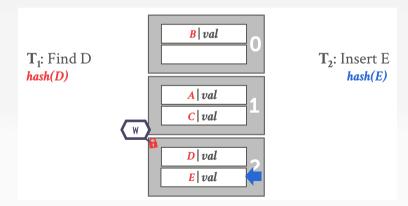




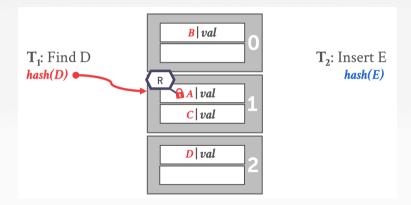




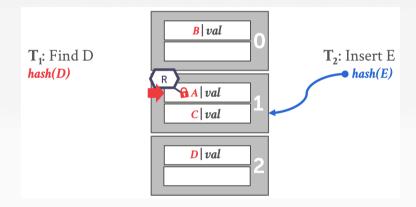




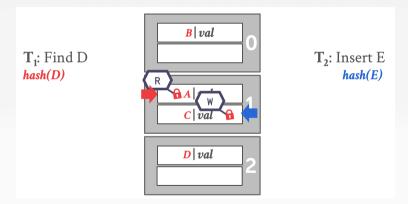




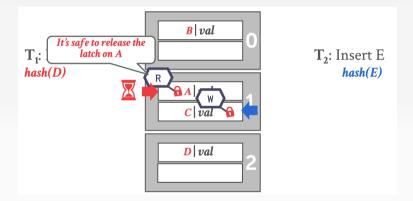




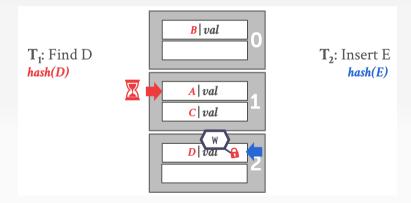




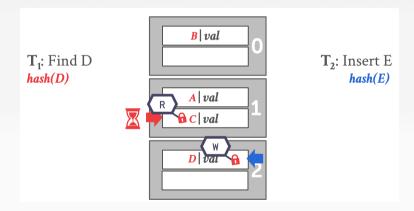




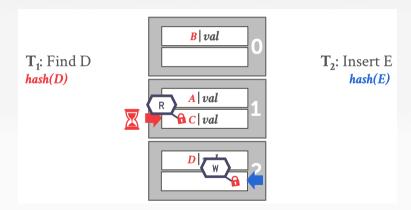




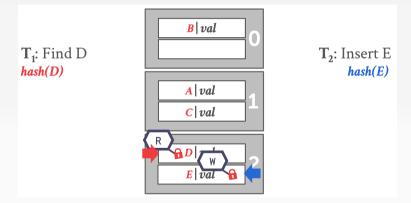












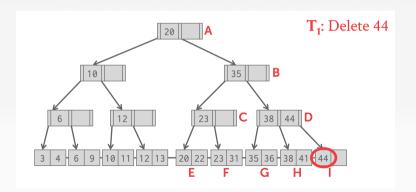


# **B** Tree Concurrency Control

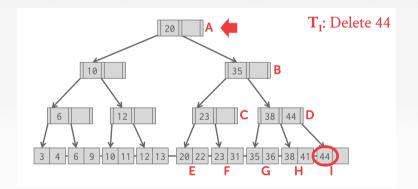
#### **B+Tree Concurrency Control**

- We want to allow multiple threads to read and update a B+Tree at the same time.
- We need to handle two types of problems:
  - ► Threads trying to modify the contents of **a node** at the same time.
  - One thread traversing the tree while another thread splits/merges nodes.

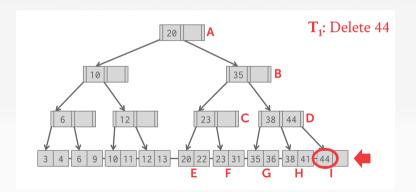




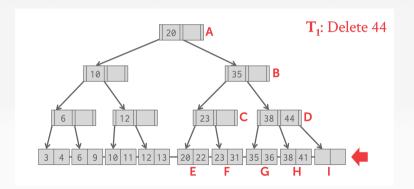




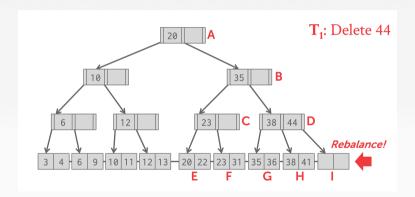




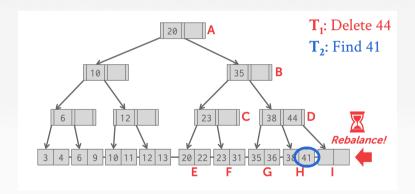




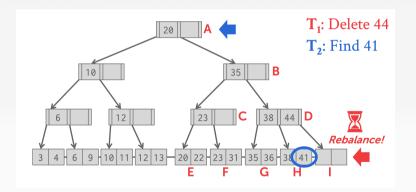




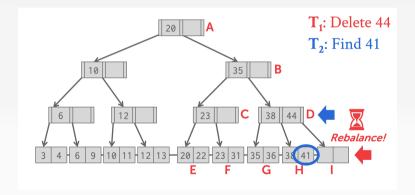




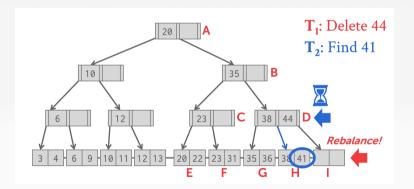




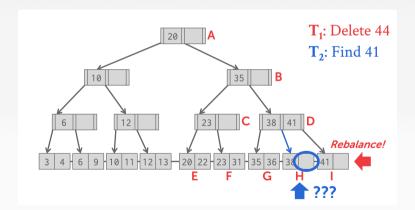














#### **Latch Crabbing/Coupling**

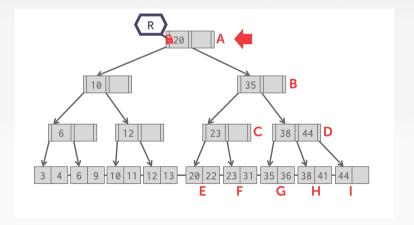
- Protocol to allow multiple threads to access/modify B+Tree at the same time.
- Basic Idea:
  - Get latch for parent.
  - ▶ Get latch for child
  - Release latch for parent if "safe".
- A **safe node** is one that will **not split or merge** when updated.
  - Not full (on insertion)
  - More than half-full (on deletion)



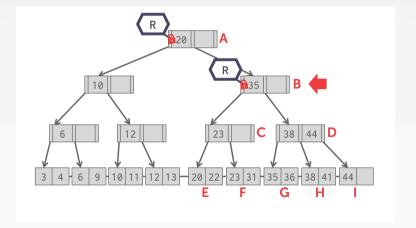
# **Latch Crabbing/Coupling**

- Find: Start at root and go down; repeatedly,
  - ightharpoonup Acquire  $\mathbf{R}$  latch on child
  - ► Then unlatch parent
- <u>Insert/Delete:</u> Start at root and go down, obtaining <u>W</u> latches as needed. Once child is latched, check if it is safe:
  - ▶ If child is safe, release all latches on ancestors.

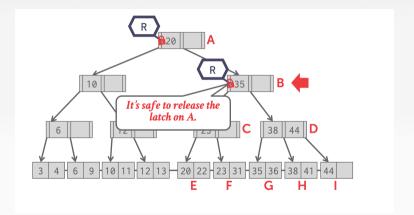




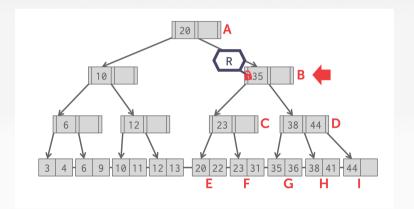




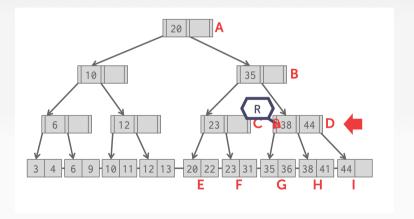




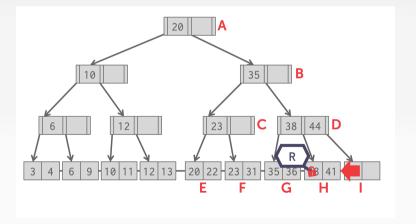




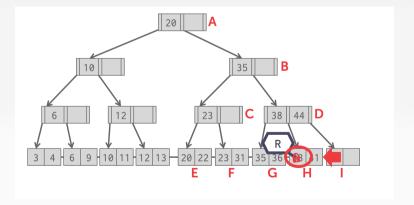




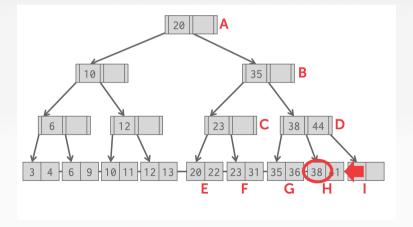




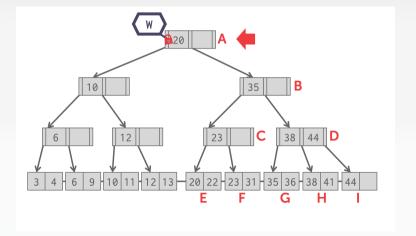




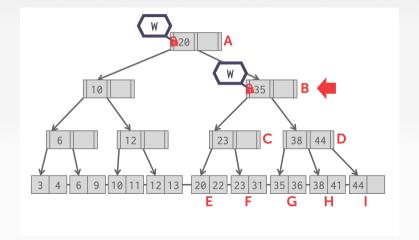




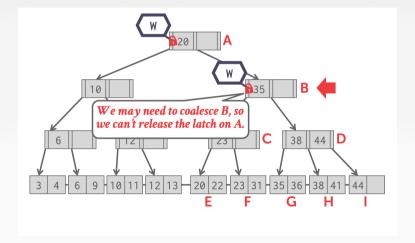




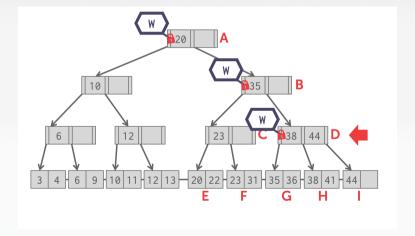




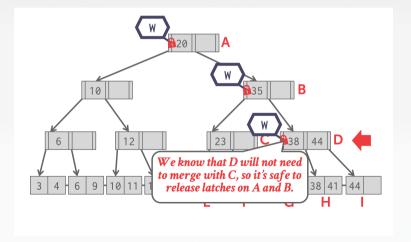




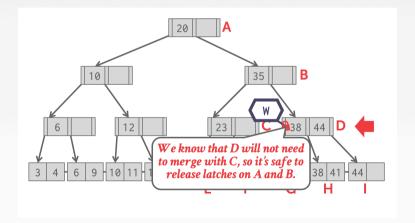




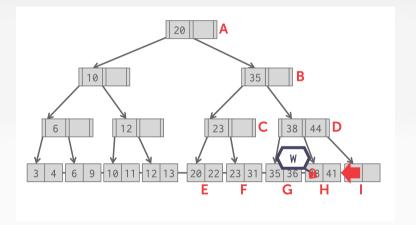




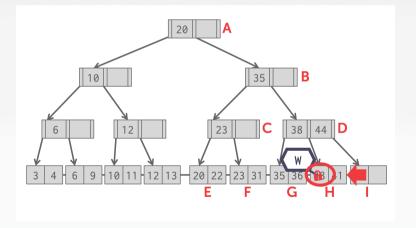




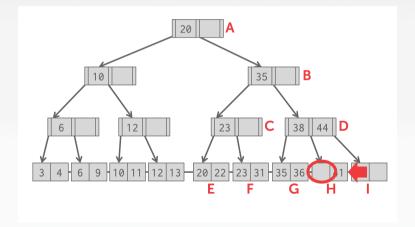




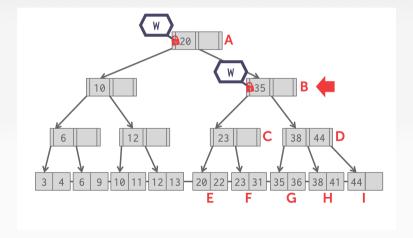




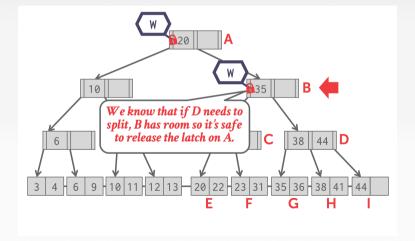




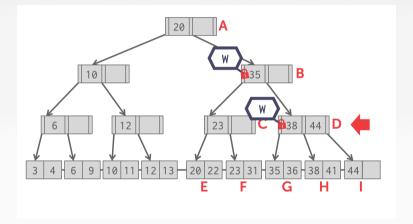




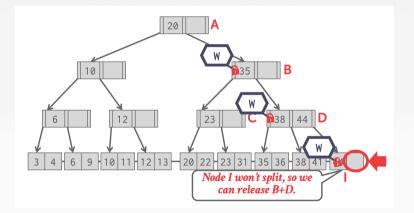




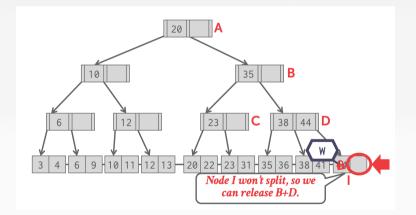




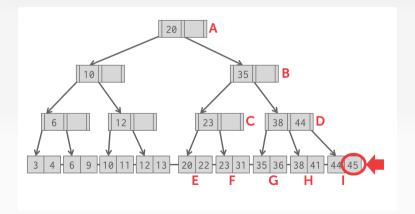




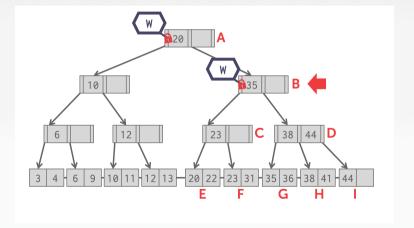




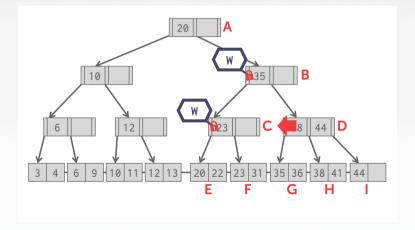




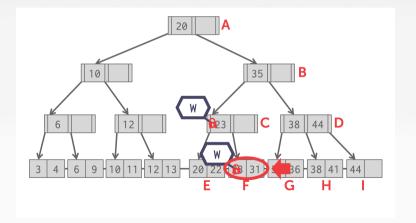




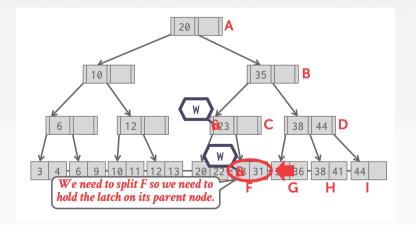




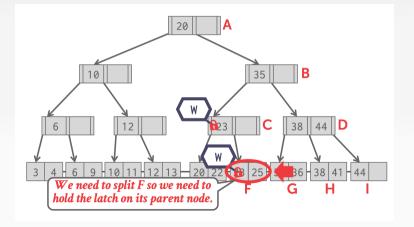




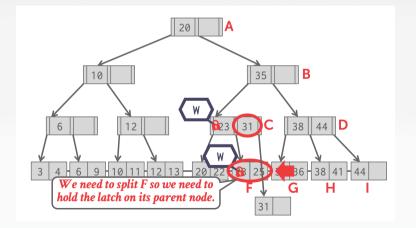








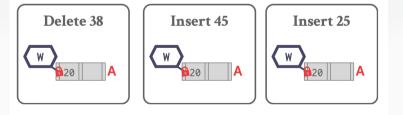






#### **Observation**

- What was the first step that all the update examples did on the B+Tree?
- Taking a write latch on the root every time becomes a bottleneck with higher concurrency.
- Can we do better?

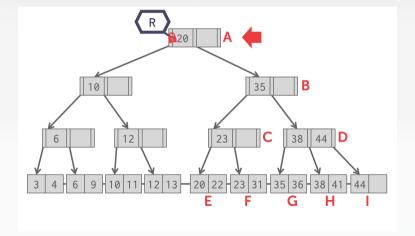




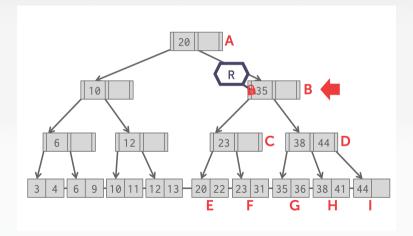
#### **Better Latching Algorithm**

- Assume that the leaf node is safe.
- Use read latches and crabbing to reach it, and then verify that it is safe.
- If leaf is not safe, then do previous algorithm using write latches.
- Reference

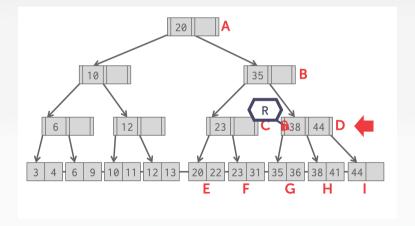




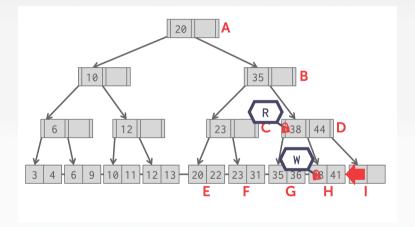




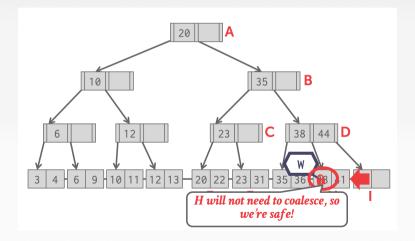




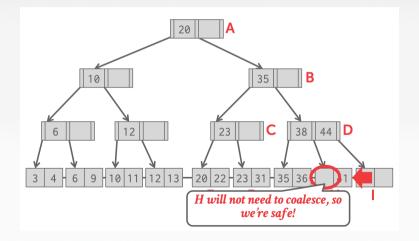




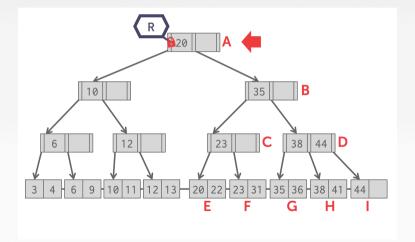




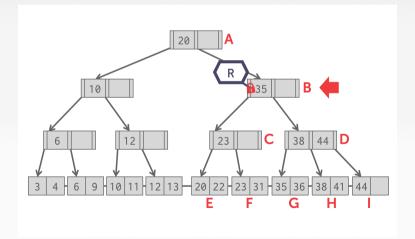




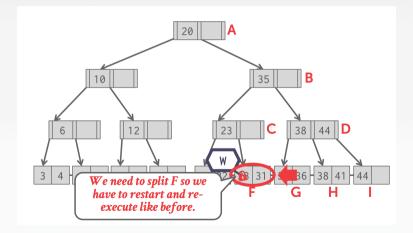














## **Better Latching Algorithm**

- Find: Same as before.
- Insert/Delete:
  - ► Set latches as if for search, get to leaf, and set **W** latch on leaf.
  - If leaf is not safe, release all latches, and restart thread using previous insert/delete protocol with W latches.
- This approach optimistically assumes that only leaf node will be modified; if not, R latches set on the first pass to leaf are wasteful.



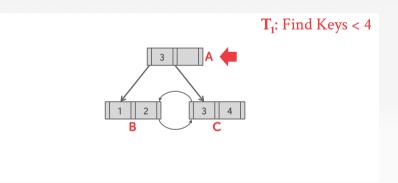
Recap Latches Overview Hash Table Latching B+Tree Concurrency Control Leaf Node Scans

# **Leaf Node Scans**

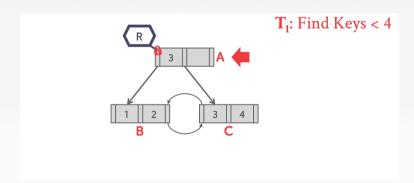
#### Observation

- The threads in all the examples so far have acquired latches in a **top-down** manner.
  - ► A thread can only acquire a latch from a node that is below its current node.
  - ▶ If the desired latch is unavailable, the thread must wait until it becomes available.
- But what if we want to move from one leaf node to another leaf node?
- Leaf nodes can include **hint keys** to approximate the next key at your sibling.

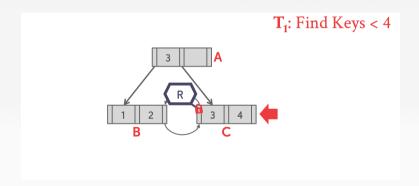




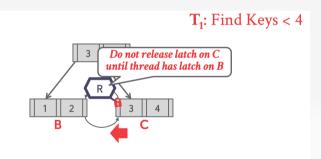




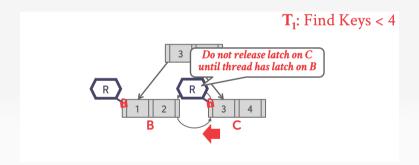




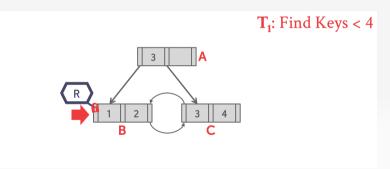




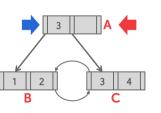








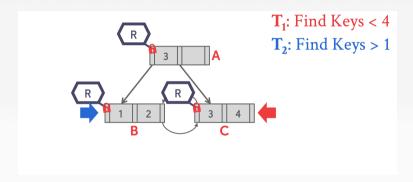




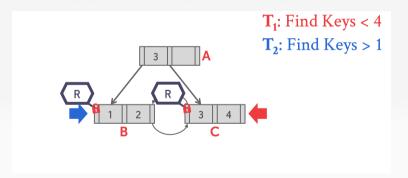
 $T_1$ : Find Keys < 4

 $T_2$ : Find Keys > 1

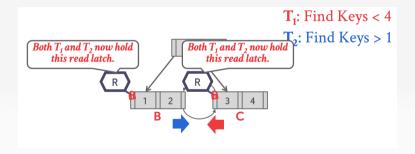




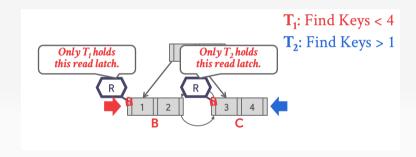




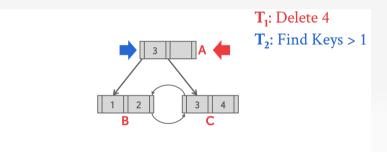




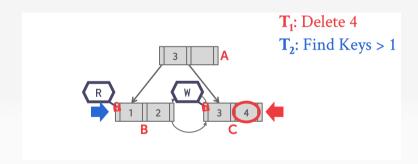




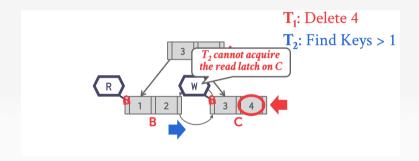




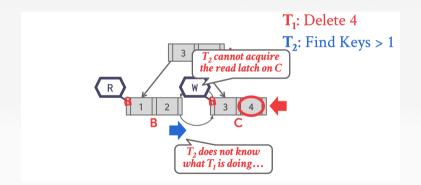






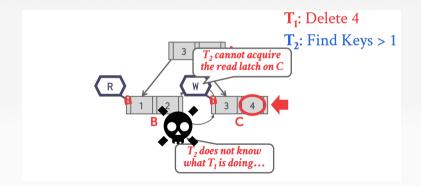








### Leaf Node Scan - Example 3





#### **Leaf Node Scans**

- Latches do **not** support deadlock detection or avoidance.
- The only way we can deal with this problem is through **coding discipline**.
- The leaf node sibling latch acquisition protocol must support a fail-fast <u>no-wait</u> mode.
- B+Tree implementation must cope with failed latch acquisitions.



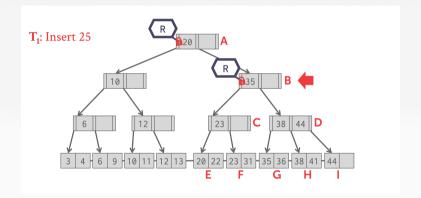
Recap Latches Overview Mash Table Latching B+Tree Concurrency Control Leaf Node Scans

Blink-Tree

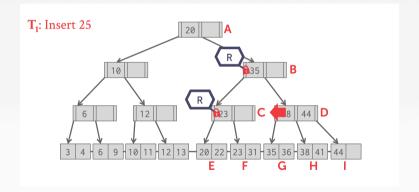
### Blink-Tree

- Every time a leaf node overflows, we must update at least **three** nodes.
  - ► The leaf node being split.
  - ► The new leaf node being created.
  - ► The parent node.
- **Optimization:** When a leaf node overflows, delay updating its parent node.
- Reference

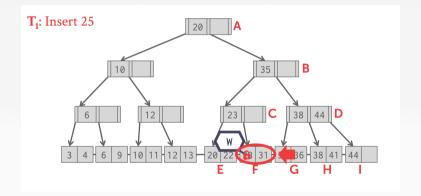






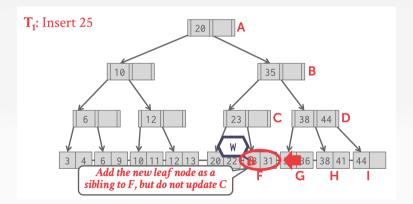




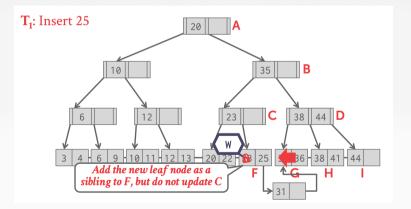




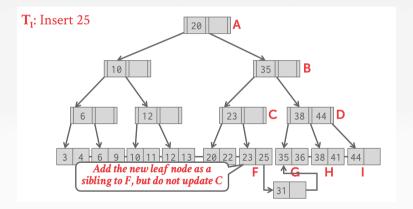
### B<sup>link</sup>-Tree Example



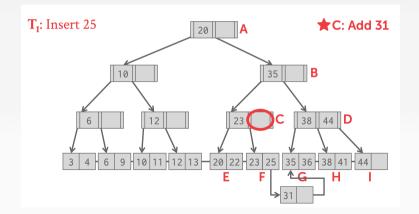






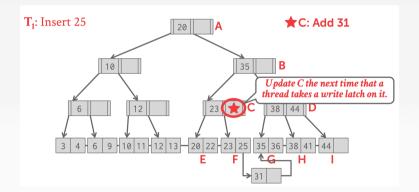




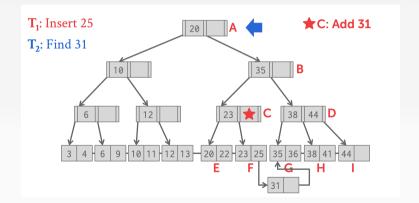




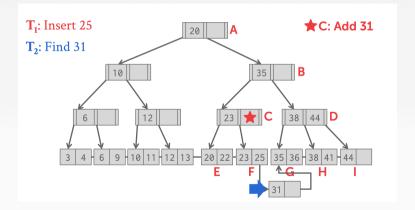
### B<sup>link</sup>-Tree Example



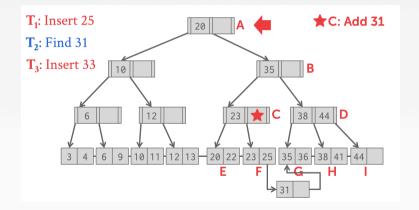




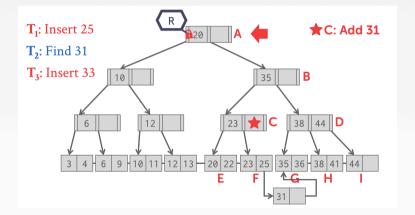




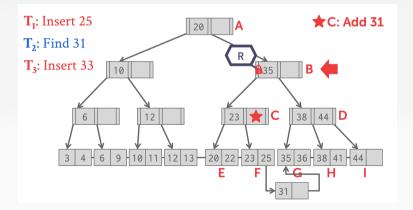




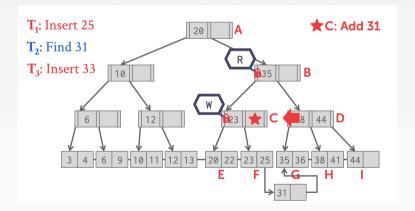




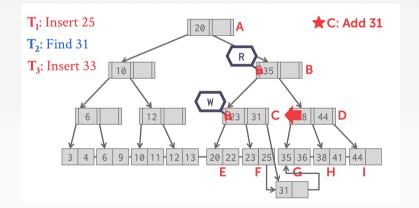














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#### Conclusion

- Making a data structure thread-safe is notoriously difficult in practice.
- We focused on B+Trees but the same high-level techniques are applicable to other data structures.
- Next Class
  - We will learn about modern access methods.

