ECS 122A Algorithm Design and Analysis

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Course slides (partially) adopted from the notes by David Luebke.

Agenda

- Strassen's method for matrix multiplication
- More on master theorem
- Introduction to heapsort

Course updates

About midterm

Strassen's method – Step 1: Divide

$$A = \frac{\frac{n}{2}}{\frac{n}{2}} \begin{bmatrix} \frac{n}{2} & \frac{n}{2} \\ A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \text{ and } B = \frac{\frac{n}{2}}{\frac{n}{2}} \begin{bmatrix} \frac{n}{2} & \frac{n}{2} \\ B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix}$$

Strassen's method

► Strassen's method – Step 2: Compute 10 matrices by ± only:

$$S_{1} = B_{12} - B_{22}$$

$$S_{2} = A_{11} + A_{12}$$

$$S_{3} = A_{21} + A_{22}$$

$$S_{4} = B_{21} - B_{11}$$

$$S_{5} = A_{11} + A_{22}$$

$$S_{6} = B_{11} + B_{22}$$

$$S_{7} = A_{12} - A_{22}$$

$$S_{8} = B_{21} + B_{22}$$

$$S_{9} = A_{11} - A_{21}$$

$$S_{10} = B_{11} + B_{12}$$

Strassen's method – Step 3: Compute 7 matrices by multiplication:

$$P_1 = A_{11} \cdot S_1$$
$$P_2 = S_2 \cdot B_{22}$$
$$P_3 = S_3 \cdot B_{11}$$
$$P_4 = A_{22} \cdot S_4$$
$$P_5 = S_5 \cdot S_6$$
$$P_6 = S_7 \cdot S_8$$
$$P_7 = S_9 \cdot S_{10}$$

Strassen's method – Step 4: Add and subtract the P_i to construct submatrices C_{ij} of the product C

$$C_{11} = P_5 + P_4 - P_2 + P_6$$

$$C_{12} = P_1 + P_2$$

$$C_{21} = P_3 + P_4$$

$$C_{22} = P_5 + P_1 - P_3 - P_7$$

The Master Theorem Revisited

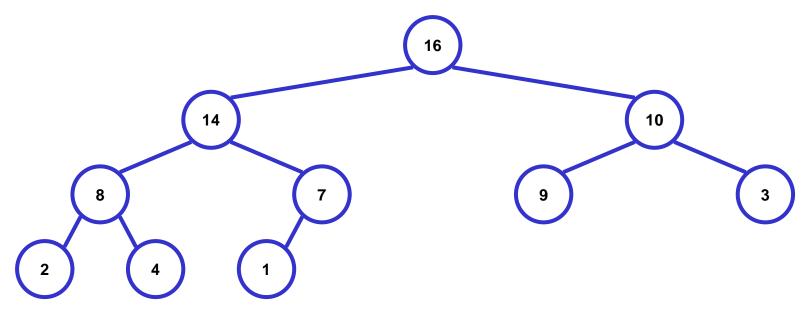
$$T(n) = \begin{cases} \Theta\left(n^{\log_{b} a}\right) & f(n) = O\left(n^{\log_{b} a - \varepsilon}\right) \\ \Theta\left(n^{\log_{b} a} \log n\right) & f(n) = \Theta\left(n^{\log_{b} a}\right) \\ \Theta\left(f(n)\right) & f(n) = \Omega\left(n^{\log_{b} a + \varepsilon}\right) \text{AND} \\ af(n/b) < cf(n) & \text{for large } n \end{cases} \end{cases}$$

Sorting Revisited

- So far we've talked about two algorithms to sort an array of numbers
 - What is the advantage of merge sort?
 - What is the advantage of insertion sort?
- Next on the agenda: *Heapsort*
 - Combines advantages of both previous algorithms

Heaps

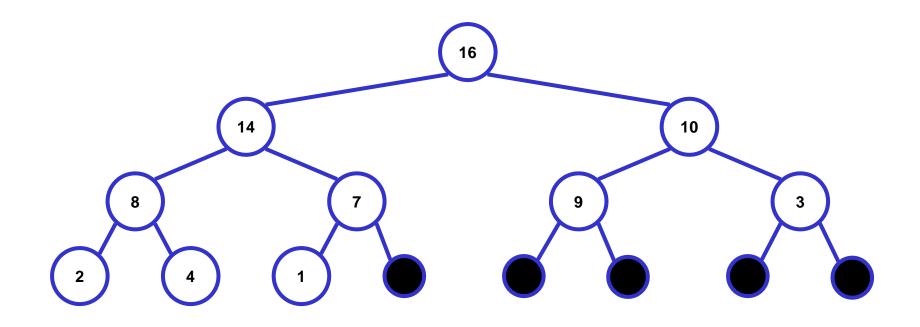
• A *heap* can be seen as a complete binary tree:



- What makes a binary tree complete?
- Is the example above complete?

Heaps

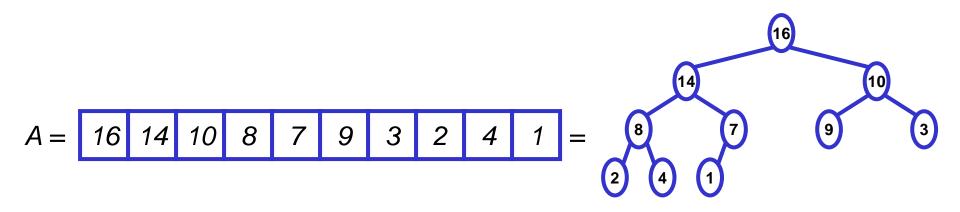
• A *heap* can be seen as a complete binary tree:



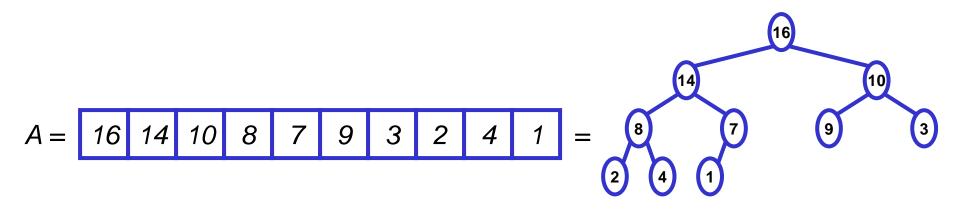
- The book calls them "nearly complete" binary trees; can think of unfilled slots as null pointers

Heaps

• In practice, heaps are usually implemented as arrays:



- To represent a complete binary tree as an array:
 - The root node is A[1]
 - Node *i* is A[*i*]
 - The parent of node *i* is A[*i*/2] (note: integer divide)
 - The left child of node *i* is A[2/]
 - The right child of node *i* is A[2*i*+1]



Referencing Heap Elements

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    So...
        Parent(i) { return [i/2]; }
        Left(i) { return 2*i; }
        right(i) { return 2*i + 1; }
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The Heap Property

- Heaps also satisfy the *heap property*. $A[Parent(i)] \ge A[i]$ for all nodes i > 1
 - In other words, the value of a node is at most the value of its parent
 - Where is the largest element in a heap stored?
- Definitions:
 - The height of a node in the tree = the number of edges on the longest downward path to a leaf
 - The height of a tree = the height of its root

Heap Height

- What is the height of an n-element heap? Why?
- This is nice: basic heap operations take at most time proportional to the height of the heap

