Topics:

• Vision-Language Models

CS 4644-DL / 7643-A ZSOLT KIRA

• Project due April 29 11:59pm (grace period May 1st)

• Fill out CIOS! <u>https://b.gatech.edu/cios</u>







Yang et al., MM-ReAct MM-ReAct: Prompting ChatGPT for Multimodal Reasoning and Action

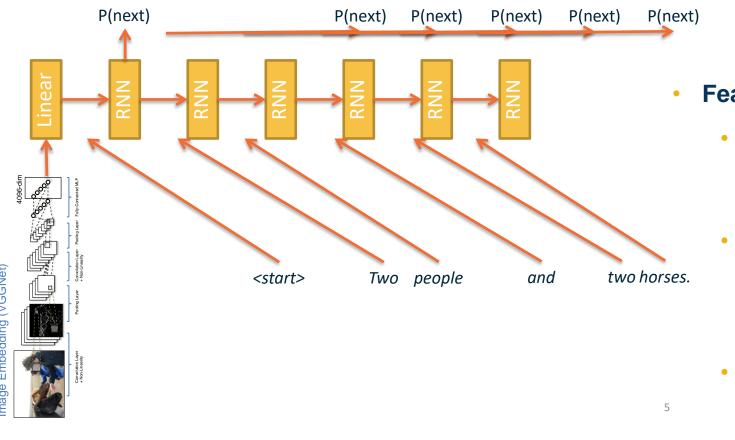
Motivation: Vision-Language Models

Georgia Tech

- Image+LSTM
- CLIP
- Vilbert
- Flamingo
- BLIP/BLIP-2
- LLaVA
- ImageBind / LanguageBind







Features:

- Pre-trained visual encoder (vector)
- Linear projection layer to map to "captionable" space
- Vector serves as initial input to RNN

The Early Days: Neural Image Captioning

Georgia Tech







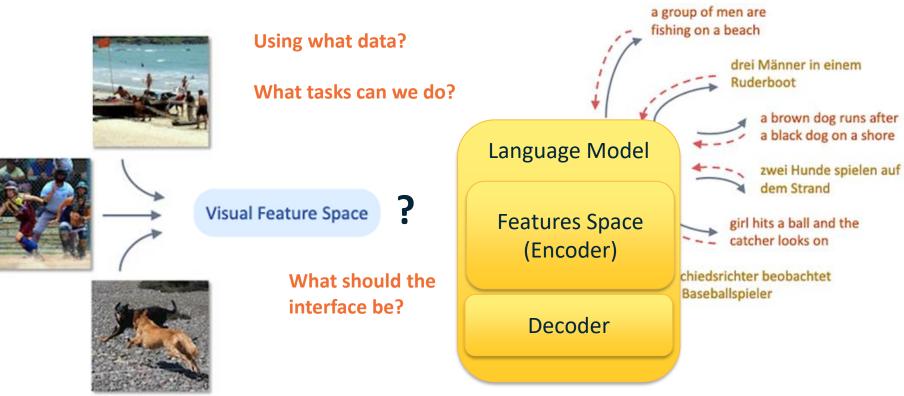
How should we encode this (representations?)?

How will they be learned?

The Early Days: Neural Image Captioning



How/what should we train?

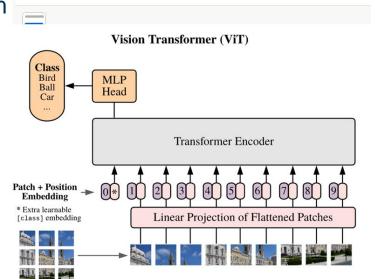


The Early Days: Neural Image Captioning



Potential ways of representing an image?

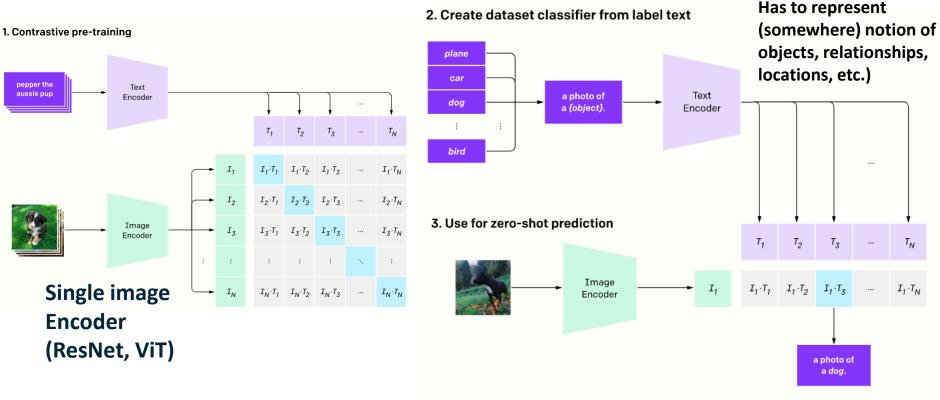
- Image encoder
 - Any architecture: ResNet, Vision transform (ViT)
 - Randomly initialized, SL/SSL pre-trained





Slide by Vicente Ordóñez Georgia Tech

Method of alignment: Contrastive Learning



Radford et al., Learning Transferable Visual Models From Natural Language Supervision

CLIP: Learning More Aligned Represenations

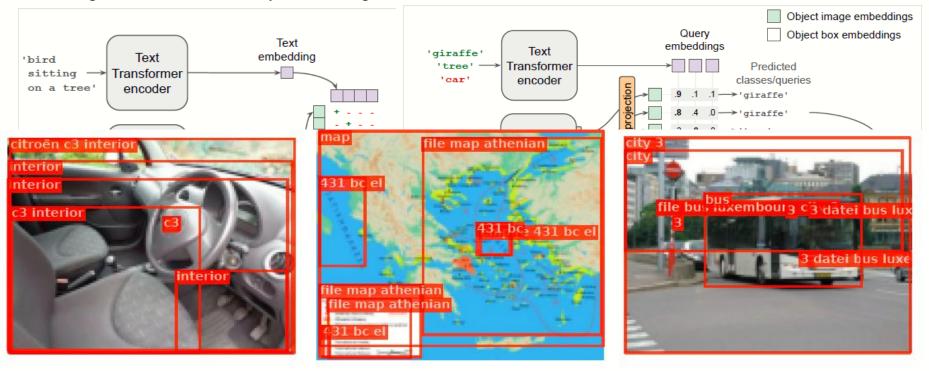


Downside?

Coarse-grained.

Image-level contrastive pre-training

Transfer to open-vocabulary detection



Minderer et al., Simple Open-Vocabulary Object Detection with Vision Transformers Minderer et al., Scaling Open-Vocabulary Object Detection

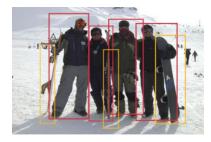
Open-Vocabulary Detection



Downside?

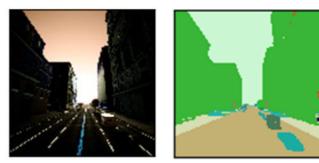
Potential ways of representing an image?

- Image encoder
 - Randomly initialized, SL/SSL pre-trained
- Alternative:
 - Bounding boxes/segments/regions + features



Object Detection

(List of bounding boxes with class distribution per box)

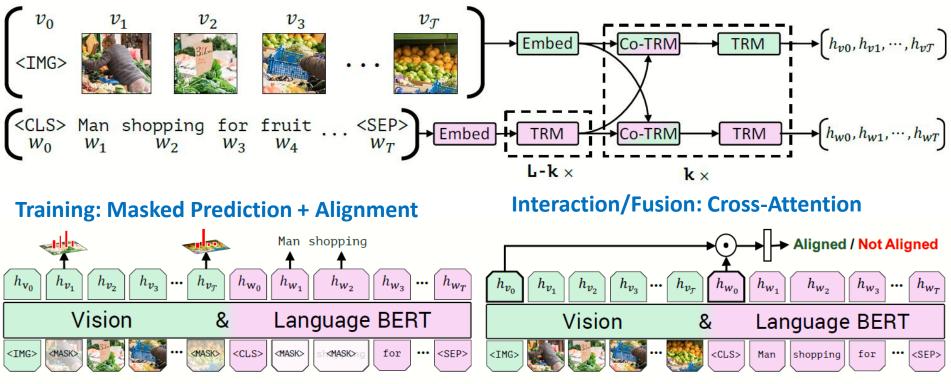


Semantic Segmentation



Instance Segmentation





(a) Masked multi-modal learning

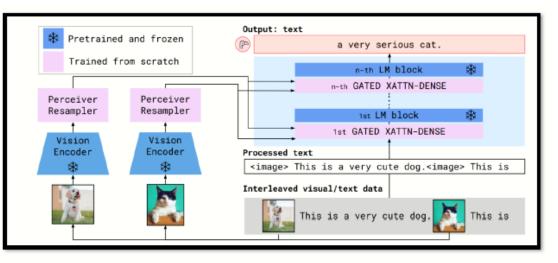
(b) Multi-modal alignment prediction

Lu et al., ViLBERT: Pretraining Task-Agnostic Visiolinguistic Representations for Vision-and-Language Tasks





• Flamingo:



Language Model

Connection Module

Vision Encoder

Pre-trained: 70B Chinchilla

Perceiver Resampler Gated Cross-attention + Dense

Pre-trained: Nonrmalizer-Free ResNet (NFNet)



Multimodal Few-Shot Learning with Frozen Language Models

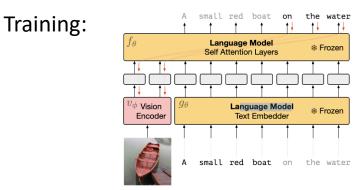
Maria Tsimpoukelli* DeepMind mrts@deepmind.com Jacob Menick* DeepMind University College London jmenick@deepmind.com Serkan Cabi* DeepMind cabi@deepmind.com

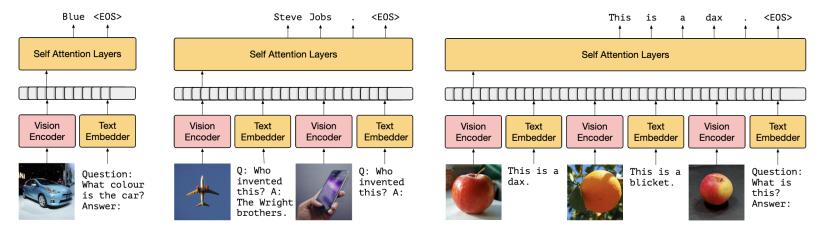
S. M. Ali Eslami DeepMind aeslami@deepmind.com Oriol Vinyals DeepMind vinyals@deepmind.com Felix Hill

DeepMind felixhill@deepmind.com



Slide by Vicente Ordóñez Georgia Tech





(a) **0-shot VQA**

(b) 1-shot outside-knowledge VQA

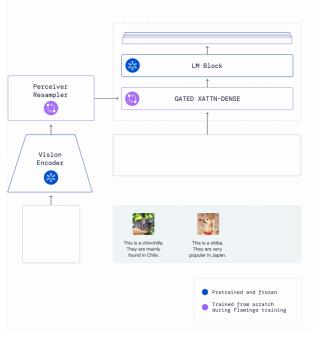
(c) Few-shot image classification

Zero to Few-Shot

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Flamingo VLM^[4]

- What is Flamingo?
 - It's a Visual Language Model (VLM) for Few-Shot Learning that launched by DeepMind.
- Visual Language Model?
 - Processing images to generate reasonable text.
- What can it do?
 - Applicable to image and video understanding tasks via simply
 - prompting it with a few examples
 - captioning, visual dialogue, classification, visual question answering



[4] Jean-Bantiste Alavrac, Jeff Donahue, Pauline Luc, Antoine Miech, Jain Barr, et al Flamingo: a Visual Language Model for Few-Shot Learning DeenMind 2022





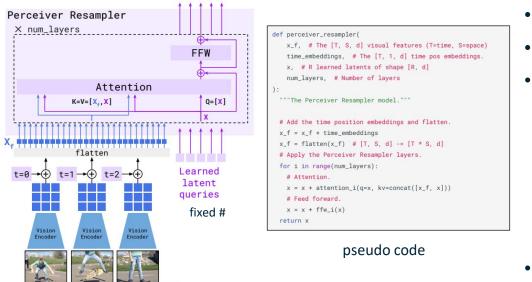
Flamingo VLM 🦩

- Three challenges for training with image/video and text.
 - Supporting both images and videos
 - Images /videos :2D structure with high dimensionality.
 - Text: 1D sequence
 - Sol.: Introduce <u>Perceiver Resample module</u>.
 - The interaction with image/video and text
 - keep the pretrained model's language understanding and generation capabilities fully intact
 - Sol.: Interleave cross-attention layers with frozen self-attention. gating mechanism.
 - Obtaining multimodal dataset to induce good generalist capabilities
 - Dataset with weak matching problem
 - Sol.: <u>combine dataset with standard strong related paired image/text and video/text datasets</u>



Flamingo VLM 🦩

• Model structure - Supporting both images and videos



- Using pre-trained ResNet to get visual features X_f
- Compress the encode image into R tokens
- Core of this module : Attention .
 - Query: the learned latent token X
 - Key=Value: the concatenation of X_f and the learned latent token X
 - Better performance by concatenating keys and values obtained from latent
- If the input is video
 - X_f will add time embeddings

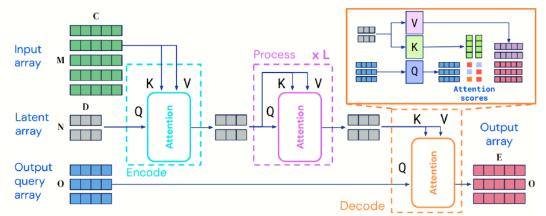
Maps a variable size grid of visual features from the Vision

Encoder to a fixed number of output token (5 in the figure.)

April 16, 2024

Perceiver / Perceiver IO: Transformer for general data perception

- General data processing method given data can be mapped into sequence of vectors
 - Use cross attention to fetch information from input
 - Self attention to process input.
 - Use cross attention to fetch relevant information and send to output.

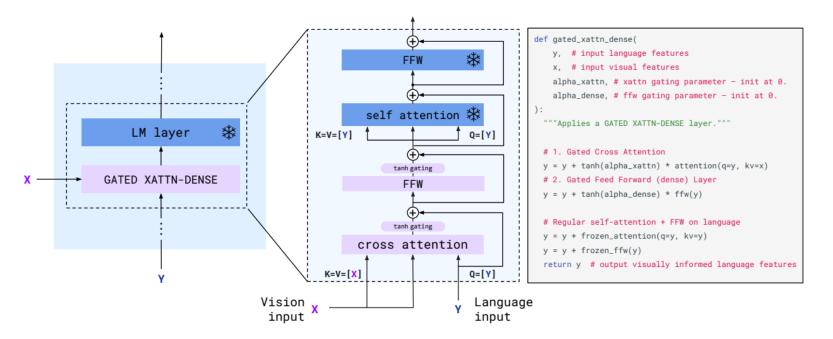


Jaegle, Andrew, et al. "Perceiver: General perception with iterative attention." *ICML*, 2021. Jaegle, Andrew, et al. "Perceiver io: A general architecture for structured inputs & outputs." *ICLR*, 2021



Flamingo VLM

• Model structure - The interaction with image/video and text

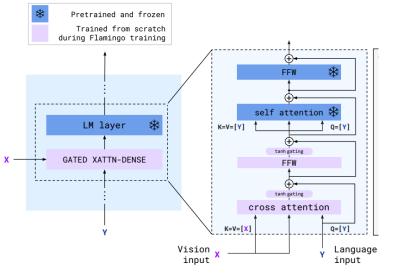


A Gated Cross attention mechanism is proposed to fuse images and text.

Flamingo VLM

•

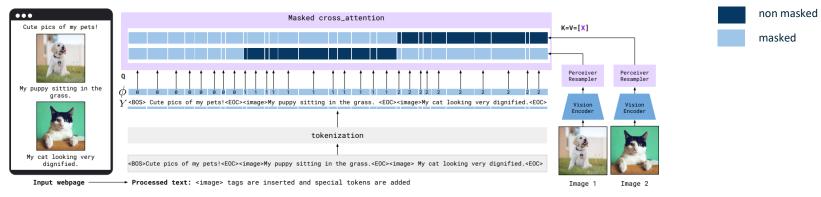
• Model structure - The interaction with image/video and text



- Frozen LM layers
 - LM: 70B parameter Chinchilla
 - keep pretrained LM's language understanding
- Gated Cross Attention:
 - Query: Y, Key=Value: X
 - Tanh Gating: Initialized with 0 then gradually increases
 - Transitions from a fully trained text-only model to a visual language model.
- The LM can generate text conditioned on the above visual tokens



• Model structure - Interleaved visual data and text support

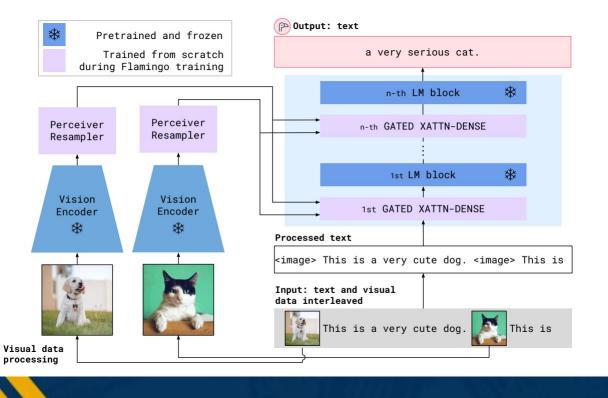


- Multi-visual input support: per-image/video attention masking
- During Cross-attention,
 - each text can only focus on one image before it.
 - Function ϕ : for each token what is the index of the last preceding image
- During final prediction,





• Overview of the Flamingo Model

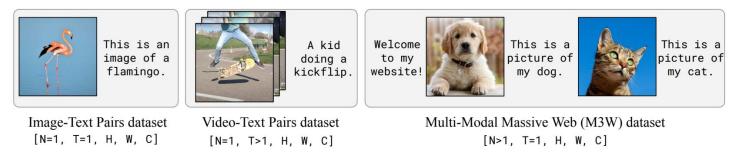


• Each image is encoded

individually

Flamingo VLM

• Model structure - Obtaining multimodal dataset to induce good generalist capabilities

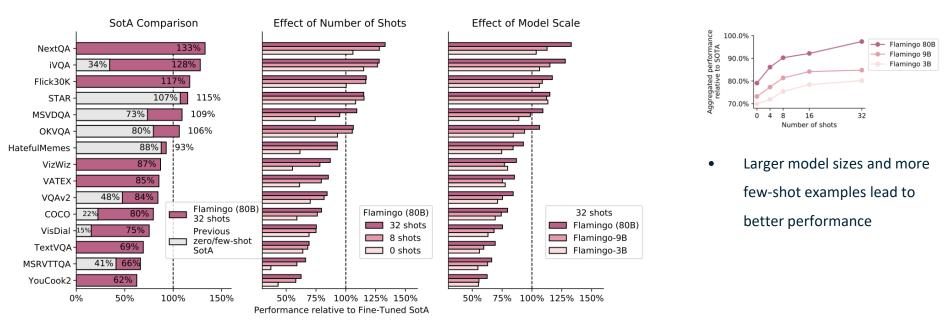


- M3W: Scrapping 43 million webpages from the Internet
- Training on a mixture of vision and language datasets
 - M3W(185M images+ 182G text)
 - ALIGN(1.8B images with alt-text)
 - LTIP (312M images/text)
 - VTP(27M short video/text)



Flamingo VLM

• Result: Overview of the results of the Flamingo models

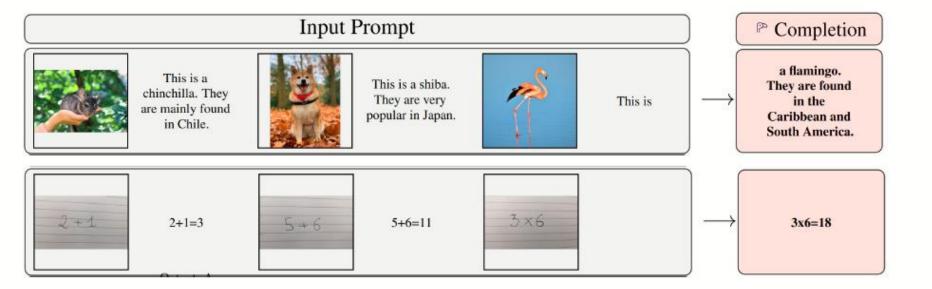


• Performance of Flamingo model using different numbers of shots and of different

sizes, (without fine-tuned) in comparison with SoTA fine-tuned baseline.

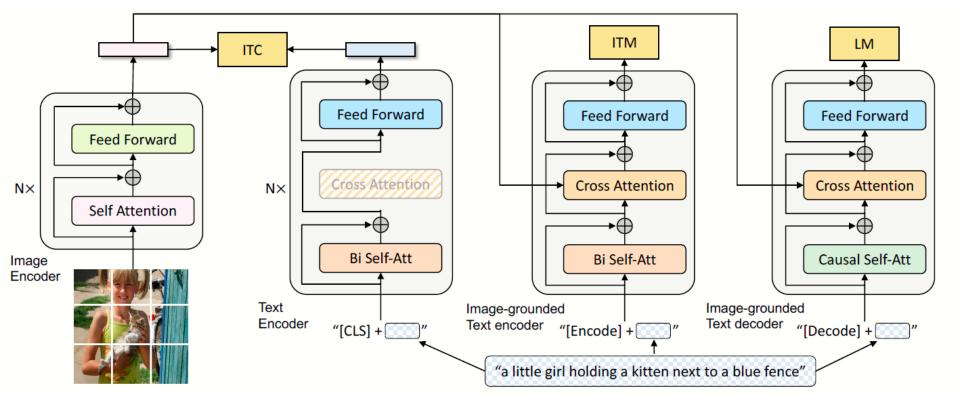
Flamingo: Multimodal In-Context-Learning







Slide by Vicente Ordóñez Georgia Tech

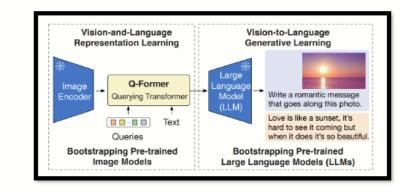


Li et al., BLIP: Bootstrapping Language-Image Pre-training for Unified Vision-Language Understanding and Generation





• BLIP2



Language Model

Connection Module

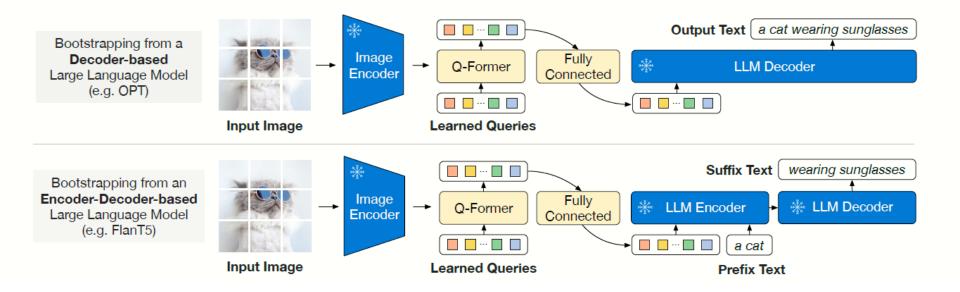
Vision Encoder

Pre-trained: FLAN-T5/OPT

Q-Former: Lightweight Querying Transformer

Contrastive pre-trained: EVA/CLIP





Li et al., BLIP-2: Bootstrapping Language-Image Pre-training with Frozen Image Encoders and Large Language Models





Models	#Trainable Params	#Total Params	V val	QAv2 test-dev	OK-VQA test	GQA test-dev
VL-T5 _{no-vqa}	224M	269M	13.5	-	5.8	6.3
FewVLM (Jin et al., 2022)	740M	785M	47.7	-	16.5	29.3
Frozen (Tsimpoukelli et al., 2021)	40M	7.1B	29.6	-	5.9	-
VLKD (Dai et al., 2022)	406M	832M	42.6	44.5	13.3	-
Flamingo3B (Alayrac et al., 2022)	1.4 B	3.2B	-	49.2	41.2	-
Flamingo9B (Alayrac et al., 2022)	1.8 B	9.3B	-	51.8	44.7	-
Flamingo80B (Alayrac et al., 2022)	10.2 B	80 B	-	56.3	50.6	-
BLIP-2 ViT-L OPT _{2.7B}	104M	3.1B	50.1	49.7	30.2	33.9
BLIP-2 ViT-g OPT _{2.7B}	107 M	3.8B	53.5	52.3	31.7	34.6
BLIP-2 ViT-g OPT _{6.7B}	108 M	7.8B	54.3	52.6	36.4	36.4
BLIP-2 ViT-L FlanT5 _{XL}	103M	3.4B	62.6	62.3	39.4	44.4
BLIP-2 ViT-g FlanT5 _{XL}	107 M	4.1B	63.1	63.0	40.7	44.2
BLIP-2 ViT-g FlanT5 _{XXL}	108M	12.1 B	65.2	65.0	<u>45.9</u>	44.7

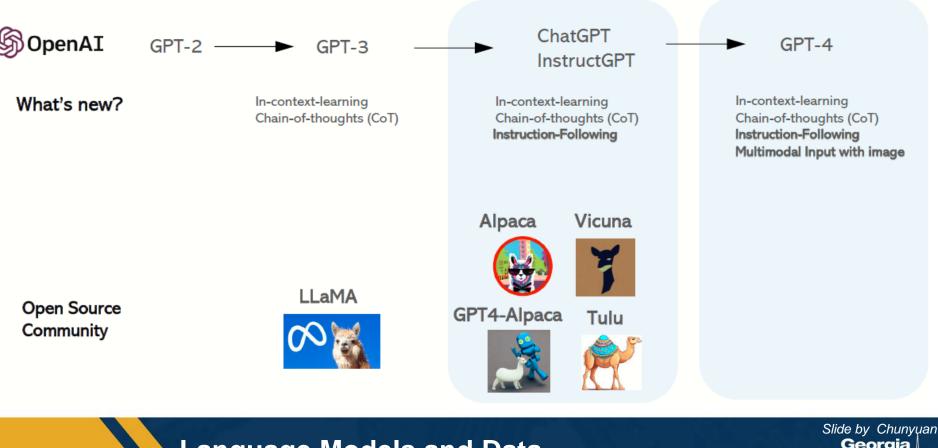
Table 2. Comparison with state-of-the-art methods on zero-shot visual question answering.

Li et al., BLIP-2: Bootstrapping Language-Image Pre-training with Frozen Image Encoders and Large Language Models

Visual Question Answering Examples

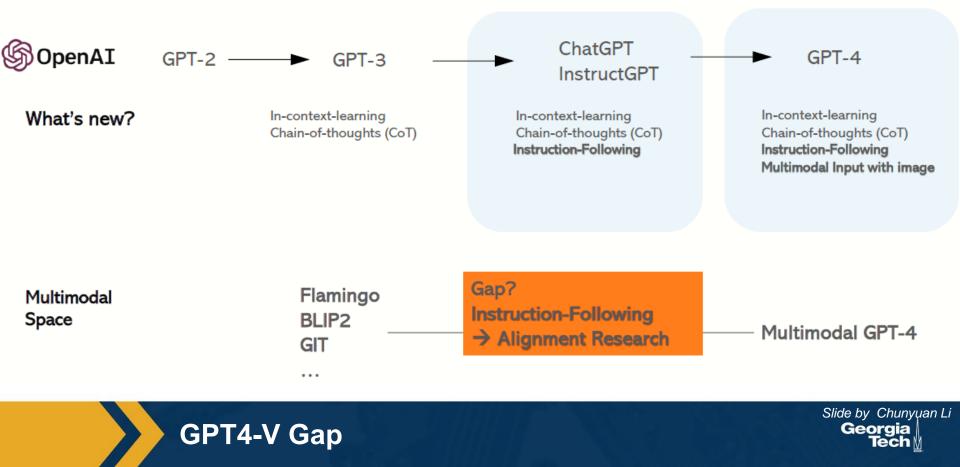


Language Modeling: Large Language Models (LLM)



Language Models and Data

Recap on Language Modeling: Large Language Models (LLM)



Instruction Tuning

Input — Output

Hello, Vancouver

你好,温哥华

Translation

CVPR is the premier annual computer vision event comprising the main conference and several co-located workshops and short courses. This year, CVPR will be single track such that everyone (with full passport registration) can attend everything. *CVPR: top computer vision event, singletrack, accessible to all.*

Summarization

- · Task instructions are implicit.
- · Individual models are trained, or multi-tasking without specifying the instructions
- · Hard to generalize to new tasks in zero-shot

In Language: Various NLP Task Datasets

Instruction Tuning

Instruction

Translate English into Simplified Chinese

Summarize in just 10 words to make the message even more brief and easier to remember. Input — Output

Hello, Vancouver

你好,温哥华

CVPR is the premier annual computer vision event comprising the main conference and several co-located workshops and short courses. This year, CVPR will be single track such that everyone (with full passport registration) can attend everything. *CVPR: top computer vision event, singletrack, accessible to all.*

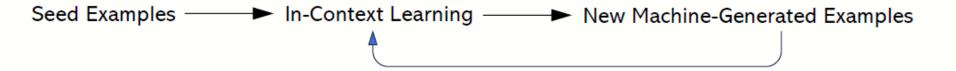
- · Task instructions are explicit, expressed in natural language
- · One single model is trained, multi-tasking with specified instructions
- Natural and easy to generalize to new tasks in zero-shot



How to collect a diverse set of high-quality instructions and their responses?

Human-Human: Collected from humans with high cost
Human-Machine: A Strong LLM Teacher such as GPT3 and GPT4

translation example summarization example Please generate new instructions that meet the requirements:





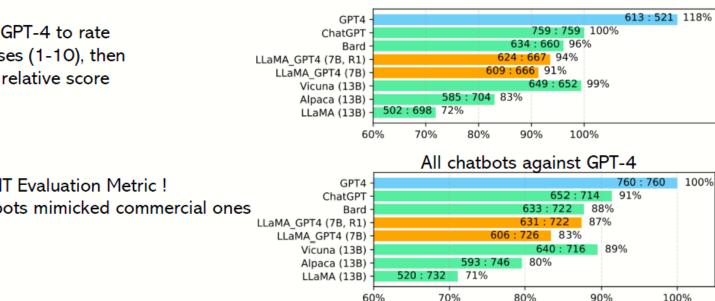
Instruction Tuning with Open-Source LLMs

Self-Instruct with Strong Teacher LLMs & Mixed Human Data

	LLaMA	Alpaca	Vicuna	GPT4-Alpaca	 Tulu
Data Source		GPT-3.5	ShareGPT (Human & GPT)	GPT-4 (text-only)	 Mixed Data
Instruction- following Data (#Turns)	None	52K	500K (~150K conversions)	52K	



Results on Chatbot



60%

All chatbots against ChatGPT

Evaluation Metric: Ask GPT-4 to rate the two model responses (1-10), then compute the ratio, i.e. relative score

Findings:

- A VERY CONSISTENT Evaluation Metric !
- Opensourced Chatbots mimicked commercial ones

It works!



Visual Instruction Tuning with GPT-4

https://llava-vl.github.io/

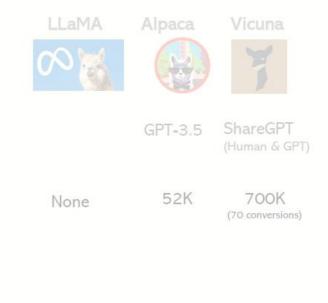
Haotian Liu*, Chunyuan Li*, Qingyang Wu, Yong Jae Lee (* Equal contribution)

Self-Instruct with Strong Teacher LLMs

Teacher

Instructionfollowing

Data



But No Teacher is available on multiGPT4?



- 158K multimodal instruction following data (First & High Quality)
 - Multimodal Chatbot

Large Language and Vision Assistant



Getting the Data - Multimodal

Downside?

GPT-assisted Visual Instruction Data Generation

- Rich Symbolic Representations of Images
- In-context-learning with a few manual examples

→ Text-only GPT-4

Context type 1: Captions

A group of people standing outside of a black vehicle with various luggage. Luggage surrounds a vehicle in an underground parking area

People try to fit all of their luggage in an SUV.

The sport utility vehicle is parked in the public garage, being packed for a trip Some people with luggage near a van that is transporting it.

Data – Using Captions

Context type 2: Boxes

person: [0.681, 0.242, 0.774, 0.694], person: [0.63, 0.222, 0.686, 0.516], person: [0.444, 0.233, 0.487, 0.34], backpack: [0.384, 0.696, 0.485, 0.914], backpack: [0.755, 0.413, 0.846, 0.692], suitcase: [0.758, 0.413, 0.845, 0.69], suitcase: [0.1, 0.497, 0.173, 0.579], bicycle: [0.282, 0.363, 0.327, 0.442], car: [0.786, 0.25, 0.848, 0.322], car: [0.783, 0.27, 0.827, 0.335], car: [0.86, 0.254, 0.891, 0.3], car: [0.261, 0.101, 0.787, 0.626]



GPT-assisted Visual Instruction Data Generation

Three type of instruction-following responses

Response type 1: conversation

Question: What type of vehicle is featured in the image?

Answer: The image features a black sport utility vehicle (SUV).

Question: Where is the vehicle parked?

Answer: The vehicle is parked in an underground parking area, likely in a public garage. Question: What are the people in the image doing?

Answer: The people are trying to fit all of their luggage into the SUV, likely preparing for a trip. Response type 2: detailed description

The image is an underground parking area with a black sport utility vehicle (SUV) parked. There are three people in the scene, with one person standing closer to the left side of the vehicle, another person in the middle, and the third person on the right side. They are all working together to pack their luggage into the SUV for a trip.

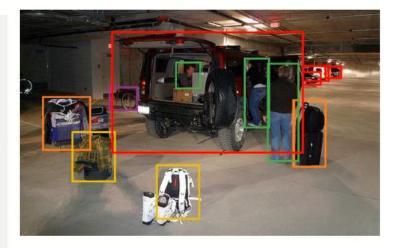
In the parking area, various luggage items are scattered around the vehicle. There are two backpacks, one located near the left rear wheel and the other closer to the right side of the vehicle. Additionally, there are two suitcases, one on the right side of the car and another further away near the center of the parking area. A bicycle can also be seen on the left side of the vehicle.

Other cars are parked around the main SUV, with one car positioned behind it and slightly to the left, another behind and slightly to the right, and the third car further behind on the right side.

Response type 3: complex reasoning

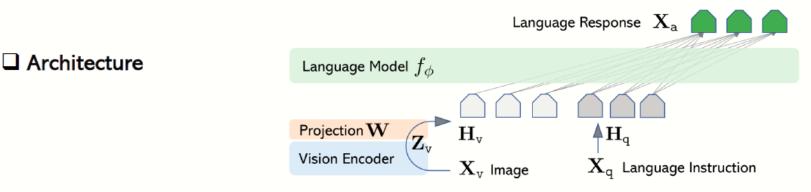
Question: What challenges do these people face?

Answer: In the image, a group of people is standing outside a black SUV in a parking area, surrounded by various pieces of luggage, including suitcases and backpacks. They are facing the challenge of fitting all their luggage into the black SUV. There are multiple suitcases and backpacks to be packed, which suggests that the group has a significant amount of belongings to accommodate. They might have to strategize and arrange the luggage efficiently to ensure that everything fits properly into the vehicle. Additionally, they need to consider the comfort of the passengers and visibility while driving, so the placement of the luggage must not obstruct the driver's view or make the passengers uncomfortable during the trip.



Data – Response Generation

LLaVA: Large Language-and-Vision Assistant



Two-stage Training

•Stage 1: Pre-training for Feature Alignment.

Only the projection matrix is updated, based on a subset of CC3M.

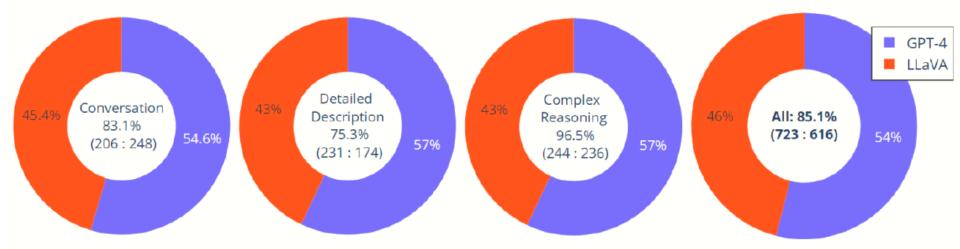
•Stage 2: Fine-tuning End-to-End. Both the projection matrix and LLM are updated

•Visual Chat: Our generated multimodal instruction data for daily user-oriented applications.

•Science QA: Multimodal reasoning dataset for the science domain.

Architecture

Visual Chat: Towards building multimodal GPT-4 level chatbot



An evaluation dataset with 30 unseen images, 90 new language-image instructions

Overall, LLaVA achieves 85.1% relative score compared with GPT-4



Science QA: New SoTA with the synergy of LLaVA with GPT-4

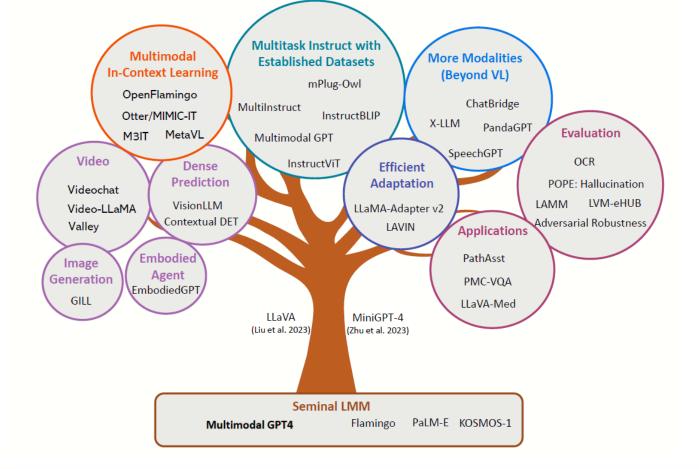
- LLaVA alones achieve 90.92%
- We use the text-only GPT-4 as the juedge, to predict the final answer based on its own previous answers and the LLaVA answers.
- This ``GPT-4 as juedge" scheme yields a new SOTA 92.53%
- GPT-4 is an effective model ensemble method



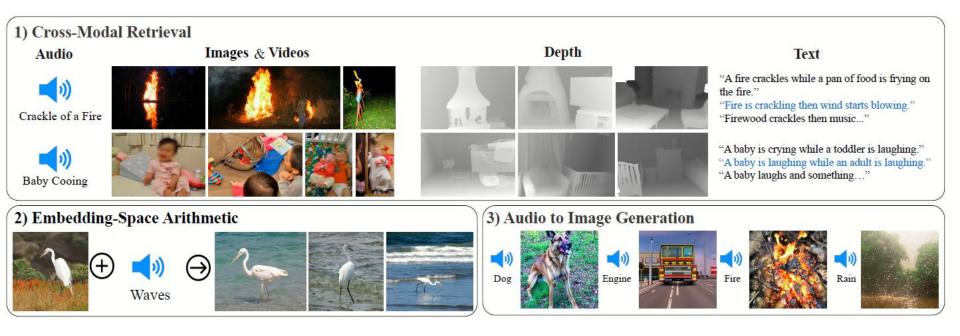


	March	April	IdealGPT			June	lune	
LLaMA	Alpaca Vicu	una	Videochat InstructBL InternGPT LMEye Otter <u>OCR</u> MultiModI-GPT	P <u>POPE</u>	PathAsst ChatBridge GILL LAVIN VisionLLM X-LLM EmbodiedG	MIMIC- Video-L MetaVL <u>LAI</u>	LaMA	
		MiniGPT-4 Llama	a-Adapter V2	PMC-VQ		aVA-Med		
Flamingo	GPT4	LLaVA mPlug-	-Owl	SpeechG	PT Co	ntextual DET	<u>LVLM-eHub</u>	
-	March March 3	April 16 April 27 M	lay hay in May	15 103	22 1/18/29	June Jun	3	

Vision-Language Explosion (2023)







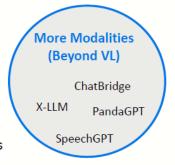
Girdhar et al., ImageBind: One Embedding Space To Bind Them All

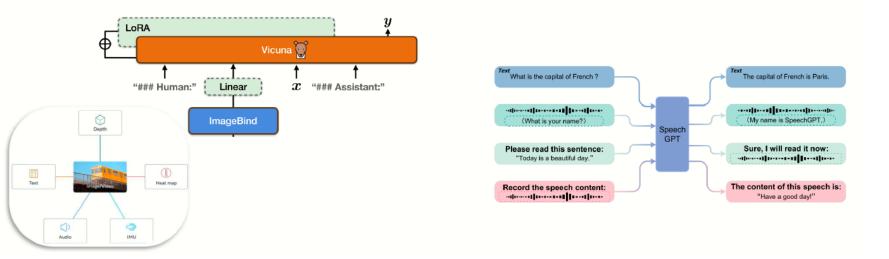


Georgia Tech

More Modalities (Beyond VL)

- ChatBridge: Bridging Modalities with Large Language Model as a Language Catalyst
- PandaGPT: One Model To Instruction-Follow Them All
- SpeechGPT: Empowering large language models with intrinsic cross-modal conversational abilities
- X-LLM: Bootstrapping Advanced Large Language Models by Treating Multi-Modalities as Foreign Languages









Yang et al., MM-ReAct MM-ReAct: Prompting ChatGPT for Multimodal Reasoning and Action

MM-ReAct





Yang et al., MM-ReAct MM-ReAct: Prompting ChatGPT for Multimodal Reasoning and Action

Tasks



Vision+Language (and multi-modal) are hot!

Why?

- Align various interface modalities
- Leverage more data (all modalities)
- Physical world inherently multi-modal

Large number of design choices!

- Vision encoding?
- Method of alignment?
- Method of fusion?

Tasks:

- ► Image ⇔ language
- Visual question answering
 - + Interaction
- Embodied AI

Resources:

https://www.youtube.com/@VLPTutorial



