Topics:

- Linear Classification, Loss functions
- Gradient Descent

CS 4644-DL / 7643-A ZSOLT KIRA

- Assignment 1 out!
- Due Feb. 2 ${ }^{\text {nd }} 11: 59$ pm (grace period Feb $4^{\text {th }}$ ).
- Start early, start early, start early!
- HW1 Tutorial, Matrix Calculus tutorial OH: TBA
- Piazza: Should be sync'd with Canvas now (Code: DLSPR2024)
- NOTE: There is an OMSCS section with a Ed. Make sure you are in the right one
- Tentative Office hours schedule: https://piazza.com/class/Icl94yjxkbb59e/post/53
- Calendar on webpage:
https://faculty.cc.gatech.edu/~zk15/teaching/AY2024 cs7643 spring/ind ex.html

Input (and representation)
Functional form of the model
Including parameters
Performance measure to improve

- Loss or objective function
- Algorithm for finding best parameters
- Optimization algorithm


Data: Image



Optimizer


- Input: Continuous number or vector
- Output: A continuous number
- For classification typically a score
- For regression what we want to regress to (house prices, crime rate, etc.)
- w is a vector and weights to optimize to fit target function


This image is $\underline{\text { CCO } 1.0 \text { public domain }}$

- We can move the bias term into the weight matrix, and a "1" at the end of the input

Results in one matrix-vector multiplication!

Model

$$
f(x, W)=W x+b
$$



Weights

Example with an image with 4 pixels, and 3 classes (cat/dog/ship)
Stretch pixels into column



Adapted from slides by Fei-Fei Li, Justin Johnson, Serena Yeung, from CS $231 n$

## Performance Measure for a Classifier

- Input (and representation)
- Functional form of the model Including parameters
- Performance measure to improve Loss or objective function
Algorithm for finding best parameters
- Optimization algorithm


Data: Image


Features: Histogram


Car

- The output of a classifier can be considered a score
- For binary classifier, use rule:

Class Scores
$y= \begin{cases}1 & \text { if } f(x, w)>=0 \\ 0 & \text { otherwise }\end{cases}$

- Can be used for many classes by considering one class versus all the rest (one versus all)

- For multi-class classifier can take the maximum

Several issues with scores:

- Not very interpretable (no bounded value)

We often want probabilitiesMore interpretable

- Can relate to probabilistic view of machine learning

We use the softmax function to convert scores to probabilities

$$
s=f(x, W) \text { Scores }
$$

$P(Y=k \mid X=x)=\frac{e^{s_{k}}}{\sum_{j} e^{s_{j}}} \quad \begin{aligned} & \text { Softmax } \\ & \text { Function }\end{aligned}$

We need a performance measure to optimize

- Penalizes model for being wrong
- Allows us to modify the model to reduce this penalty
- Known as an objective or loss function
In machine learning we use empirical risk minimization
- Reduce the loss over the training dataset
- We average the loss over the training data

Given a dataset of examples:

$$
\left\{\left(\boldsymbol{x}_{i}, y_{i}\right)\right\}_{i=1}^{N}
$$

Where $\boldsymbol{x}_{\boldsymbol{i}}$ is image and

$$
y_{i} \text { is (integer) label }
$$

Loss over the dataset is a sum of loss over examples:

$$
L=\frac{1}{N} \sum L\left(f\left(x_{i}, W\right), y_{i}\right)
$$

## Multiclass SVM loss:

Given an example ( $\boldsymbol{x}_{\boldsymbol{i}} \boldsymbol{y}_{\boldsymbol{i}}$ ) where $x_{i}$ is the image and

scores for other classes score for correct class where $y_{i}$ is the (integer) label,
and using the shorthand for the scores vector: $\boldsymbol{s}=\boldsymbol{f}\left(\boldsymbol{x}_{\boldsymbol{i}}, \boldsymbol{W}\right)$
the SVM loss has the form:

$$
\begin{aligned}
L_{i} & =\sum_{j \neq y_{i}} \begin{cases}0 & \text { if } s_{y_{i}} \geq s_{j}+1 \\
s_{j}-s_{y_{i}}+1 & \text { otherwise }\end{cases} \\
& =\sum_{j \neq y_{i}} \max \left(0, s_{j}-s_{y_{i}}+1\right)
\end{aligned}
$$

## Example: "Hinge Loss"



## Multiclass SVM loss:

Given an example ( $\boldsymbol{x}_{\boldsymbol{i}} \boldsymbol{y}_{\boldsymbol{i}}$ ) where $\boldsymbol{x}_{\boldsymbol{i}}$ is the image and where $y_{i}$ is the (integer) label,
and using the shorthand for the scores vector: $\boldsymbol{s}=\boldsymbol{f}\left(\boldsymbol{x}_{\boldsymbol{i}}, \boldsymbol{W}\right)$
the SVM loss has the form:
$L_{i}=\sum_{j \neq y_{i}} \max \left(0, s_{j}-s_{y_{i}}+1\right)$
$=\max (0,5.1-3.2+1)$ $+\max (0,-1.7-3.2+1)$
$=\max (0,2.9)+\max (0,-3.9)$
$=2.9+0$
$=2.9$

Suppose: 3 training examples, 3 classes. With some $\boldsymbol{W}$ the scores $\boldsymbol{f}(\boldsymbol{x}, \boldsymbol{W})=\boldsymbol{W} \boldsymbol{x}$ are:

1.3
2.2
car
frog
Losses:
cat

## Multiclass SVM loss:

Given an example ( $\boldsymbol{x}_{\boldsymbol{i}} \boldsymbol{y}_{\boldsymbol{i}}$ ) where $\boldsymbol{x}_{\boldsymbol{i}}$ is the image and where $y_{i}$ is the (integer) label,
and using the shorthand for the scores vector: $\boldsymbol{s}=\boldsymbol{f}\left(\boldsymbol{x}_{\boldsymbol{i}}, \boldsymbol{W}\right)$
the SVM loss has the form:
$L_{i}=\sum_{j \neq y_{i}} \max \left(0, s_{j}-s_{y_{i}}+1\right)$
$=\max (0,1.3-4.9+1)$ $+\max (0,2.0-4.9+1)$
$=\max (0,-2.6)+\max (0,-1.9)$
$=0+0$
$=0$

Suppose: 3 training examples, 3 classes. With some $\boldsymbol{W}$ the scores $\boldsymbol{f}(\boldsymbol{x}, \boldsymbol{W})=\boldsymbol{W} \boldsymbol{x}$ are:

cat
car
frog

3.2 5.1

Losses:

2.2 2.5 -3.1

## Multiclass SVM loss:

$L_{i}=\sum_{j \neq y_{i}} \max \left(0, s_{j}-s_{y_{i}}+1\right)$
Q: What happens to loss if car image scores change a bit?

No change for small values
cat
car
frog

Suppose: 3 training examples, 3 classes. With some $\boldsymbol{W}$ the scores $f(x, W)=W \boldsymbol{x}$ are:

3.2 5.1
-1.7

1.3
4.9
2.0
2.2
2.5

-3.1

## Multiclass SVM loss:

$L_{i}=\sum_{j \neq y_{i}} \max \left(0, s_{j}-s_{y_{i}}+1\right)$
Q: What is min/max of loss value?
cat
car frog
[0,inf]
1.3
2.2
4.9
2.5
2.0
-3.1

Suppose: 3 training examples, 3 classes. With some $W$ the scores $f(x, W)=W \boldsymbol{x}$ are:

3.2 5.1
-1.7


## Multiclass SVM loss:

$L_{i}=\sum_{j \neq y_{i}} \max \left(0, s_{j}-s_{y_{i}}+1\right)$
Q: At initialization $W$ is small so all $s \approx 0$. What is the loss?

C-1

Suppose: 3 training examples, 3 classes. With some $\boldsymbol{W}$ the scores $\boldsymbol{f}(\boldsymbol{x}, \boldsymbol{W})=\boldsymbol{W} \boldsymbol{x}$ are:
2.2
2.5
frog
cat
car
-3.1


3.2 5.1
-1.7
1.3
4.9

2.0

## Multiclass SVM loss:

$L_{i}=\sum_{j \neq y_{i}} \max \left(0, s_{j}-s_{y_{i}}+1\right)$
Q: What if the sum was over all classes?
(including $\mathrm{j}=\mathrm{y}$ _i)
No difference (add constant 1)

Suppose: 3 training examples, 3 classes. With some $W$ the scores $f(x, W)=W \boldsymbol{x}$ are:
cat
car
frog

3.2 5.1
-1.7
1.3
2.2
4.9
2.5
2.0
-3.1


## Multiclass SVM loss:

$L_{i}=\sum_{j \neq y_{i}} \max \left(0, s_{j}-s_{y_{i}}+1\right)$
Q: What if we used mean instead of sum?

No difference
Scaling by constant

Suppose: 3 training examples, 3 classes. With some $W$ the scores $f(x, W)=W \boldsymbol{x}$ are:

|  | cat | 3.2 | 1.3 | 2.2 |
| :--- | :--- | ---: | ---: | ---: |
| No difference | car | 5.1 | 4.9 | 2.5 |
| Scaling by constant | frog | -1.7 | 2.0 | -3.1 |

## Multiclass SVM loss:

Given an example ( $\boldsymbol{x}_{\boldsymbol{i}} \boldsymbol{y}_{\boldsymbol{i}}$ ) where $\boldsymbol{x}_{\boldsymbol{i}}$ is the image and where $y_{i}$ is the (integer) label,
and using the shorthand for the scores vector: $\boldsymbol{s}=\boldsymbol{f}\left(\boldsymbol{x}_{\boldsymbol{i}}, \boldsymbol{W}\right)$
the SVM loss has the form:
$L_{i}=\sum_{j \neq y_{i}} \max \left(0, s_{j}-s_{y_{i}}+1\right)$

$$
\begin{aligned}
\mathrm{L} & =(2.9+0+12.9) / 3 \\
& =5.27
\end{aligned}
$$

Suppose: 3 training examples, 3 classes. With some $\boldsymbol{W}$ the scores $\boldsymbol{f}(\boldsymbol{x}, \boldsymbol{W})=\boldsymbol{W} \boldsymbol{x}$ are:

1.3
car frog Losses:

3.2 5.1
-1.7
2.9
4.9

2.0

0
-3.1 12.9
2.2


- If we use the softmax function to convert scores to probabilities, the right loss function to use is cross-entropy
- Can be derived by looking at the distance between two probability distributions (output of model and ground truth)
- Can also be derived from a maximum likelihood estimation perspective

$$
s=f(x, W) \quad \text { Scores }
$$

$$
P(Y=k \mid X=x)=\frac{e^{s_{k}}}{\sum_{j} e^{s_{j}}} \quad \begin{aligned}
& \text { Softmax } \\
& \text { Function }
\end{aligned}
$$

$$
L_{i}=-\log P\left(Y=y_{i} \mid X=x_{i}\right)
$$

Maximize log-prob of correct class = Maximize the log likelihood
$=$ Minimize the negative log likelihood

- If we use the softmax function to convert scores to probabilities, the right loss function to use is cross-entropy
- Goal: Minimize KL-divergence (distance measure b/w probability distributions)
$p^{*}=\left[\begin{array}{l}0 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0\end{array}\right] \quad \hat{p}=\left[\begin{array}{l}P(Y=1 \mid x, w) \\ P(Y=2 \mid x, w) \\ P(Y=3 \mid x, w) \\ P(Y=4 \mid x, w) \\ P(Y=5 \mid x, w) \\ P(Y=6 \mid x, w) \\ P(Y=7 \mid x, w) \\ P(Y=8 \mid x, w)\end{array}\right]=\left[\begin{array}{c}0.5 \\ 0.01 \\ 0.01 \\ 0.01 \\ 0.01 \\ 0.01 \\ 0.15 \\ 0.3\end{array}\right]$
Ground Truth

$$
\min _{w} K L\left(p^{*} \| \hat{p}\right)=\sum_{y} p^{*}(y) \log \frac{p^{*}(y)}{\hat{p}(y)}
$$

$$
=\sum_{y} p^{*}(y) \log \left(p^{*}(y)\right)-\sum_{y} p^{*}(y) \log (\hat{p}(y))
$$

$$
-H\left(p^{*}\right)
$$

(negative entropy, term goes away because not a function of model, $W$, parameters we are minimizing over)

Since $p^{*}$ is one-hot ( 0 for non-ground truth classes), all we need to minimize is (where $i$ is ground truth class): $\min _{w}\left(-\log \hat{p}\left(y_{i}\right)\right)$

## Softmax Classifier (Multinomial Logistic Regression)



## Softmax Classifier (Multinomial Logistic Regression)



Want to interpret raw classifier scores as probabilities
$s=f\left(x_{i} ; W\right)$
Probabilities must be $>=0$

$$
P\left(Y=k \mid X=x_{i}\right)=\frac{e^{s_{k}}}{\sum_{j} e^{s_{j}}}
$$

Softmax Function

$$
\begin{aligned}
& \text { Probabilities } \\
& \text { must sum to } 1
\end{aligned} L_{i}=-\log P\left(Y=y_{i} \mid X=x_{i}\right)
$$

$$
L_{i}=-\log (0.13)
$$

Q: What is the min/max of possible loss L_i?

Infimum is 0 , max is unbounded (inf)

## Softmax Classifier (Multinomial Logistic Regression)



Want to interpret raw classifier scores as probabilities
$s=f\left(x_{i} ; W\right)$
Probabilities must be $>=0$

$$
P\left(Y=k \mid X=x_{i}\right)=\frac{e^{s_{k}}}{\sum_{j} e^{s_{j}}} \quad \begin{aligned}
& \text { Softmax } \\
& \text { Function }
\end{aligned}
$$

$$
\begin{aligned}
& \text { Probabilities } \\
& \text { must sum to } 1
\end{aligned} L_{i}=-\log P\left(Y=y_{i} \mid X=x_{i}\right)
$$

$$
L_{i}=-\log (0.13)
$$

Q: At initialization all s will be approximately equal; what is the loss?
$\log (C)$, e.g. $\log (10) \approx 2$

Often, we add a regularization term to the loss function

$$
\begin{gathered}
\text { L1 Regularization } \\
L_{i}=\left|y-W x_{i}\right|^{2}+|W|
\end{gathered}
$$

## Example regularizations:

- L1/L2 on weights (encourage small values)


## Gradient Descent

- Input (and representation)
- Functional form of the model
- Including parameters
- Performance measure to improve

Loss or objective function
Algorithm for finding best parameters

- Optimization algorithm


Data: Image


Features: Histogram

cenetrar

Given a model and loss function, finding the best set of weights is a search problem

- Find the best combination of weights that minimizes our loss function

Several classes of methods:

- Random search
- Genetic algorithms (population-based search)
- Gradient-based optimization

In deep learning, gradient-based methods are dominant although not the only approach possible


As weights change, the loss changes as well

- This is often somewhatsmooth locally, so small changes in weights produce small changes in the loss

We can therefore think about iterative algorithms that take current values of weights and modify them a bit



Strategy: Follow the Slope!

- We can find the steepest descent direction by computing the derivative (gradient):

$$
f^{\prime}(a)=\lim _{h \rightarrow 0} \frac{f(a+h)-f(a)}{h}
$$

- Steepest descent direction is the negative gradient
- Intuitively: Measures how the function changes as the argument a changes by a small step size
- As step size goes to zero

In Machine Learning: Want to know how the loss function changes as weights are varied

- Can consider each parameter separately by taking partial derivative of loss function with respect to that parameter


Derivatives

$$
f^{\prime}(a)=\lim _{h \rightarrow 0} \frac{f(a+h)-f(a)}{h}
$$



This idea can be turned into an algorithm (gradient descent)

1. Choose a model: $\boldsymbol{f}(\boldsymbol{x}, \boldsymbol{W})=\mathrm{Wx}$
2. Choose loss function: $\boldsymbol{L}_{\boldsymbol{i}}=\left(\boldsymbol{y}-\boldsymbol{W} \boldsymbol{x}_{\boldsymbol{i}}\right)^{2}$
3. Calculate partial derivative for each parameter: $\frac{\partial L}{\partial w_{i}}$
4. Update the parameters: $\boldsymbol{w}_{\boldsymbol{i}}=\boldsymbol{w}_{\boldsymbol{i}}-\frac{\partial L}{\partial \boldsymbol{w}_{\boldsymbol{i}}}$

Add learning rate to prevent too big of a step: $\boldsymbol{w}_{\boldsymbol{i}}=\boldsymbol{w}_{\boldsymbol{i}}-\alpha \frac{\partial L}{\partial w_{i}}$
5. Repeat (from Step 3)


## original W

## negative gradient direction



Gradient Descent

Often, we only compute the gradients across a small subset of data

- Full Batch Gradient Descent

$$
L=\frac{1}{N} \sum L\left(f\left(x_{i}, W\right), y_{i}\right)
$$

Mini-Batch Gradient Descent $\quad L=\frac{1}{M} \sum L\left(f\left(x_{i}, W\right), y_{i}\right)$

- Where M is a subset of data
- We iterate over mini-batches:
- Get mini-batch, compute loss, compute derivatives, and take a set

Gradient descent is guaranteed to converge under some conditions

- For example, learning rate has to be appropriately reduced throughout training
- It will converge to a local minima
- Small changes in weights would not decrease the loss
- It turns out that some of the local minima that it finds in practice (if trained well) are still pretty good!

We know how to compute the model output and loss function

## Several ways to compute $\frac{\partial L}{\partial w_{i}}$

Manual differentiation- Symbolic differentiation

Numerical differentiation

- Automatic differentiation



## Computing Gradients

current W:

$[0.34$,
-1.11,
0.78,
0.12,
0.55,
2.81,
-3.1,
-1.5,
$0.33, \ldots]$
loss 1.25347
gradient dW:
$[?$,
$?$,
$?$,
$?$
$?$
$?$
$?$
$?$
$?$
$?$
$?, \ldots]$

| current W: | $\mathbf{W}+\mathbf{h}$ (first dim): | gradient dW: |
| :--- | :--- | :--- |
|  |  |  |
| $[0.34$, | $[0.34+\mathbf{0 . 0 0 0 1}$, | $[?$, |
| -1.11, | -1.11, | $?$, |
| 0.78, | 0.78, | $?$, |
| 0.12, | 0.12, | $?$, |
| 0.55, | 0.55, | $?$, |
| 2.81, | 2.81, | $?$, |
| -3.1, | -3.1, | $?$, |
| -1.5, | -1.5, | $?, \ldots]$ |
| $0.33, \ldots]$ | $0.33, \ldots]$ |  |


| current W: | $\mathbf{W}+\mathbf{h}($ first dim): | gradient dW: |
| :--- | :--- | :---: |
|  |  |  |
| $[0.34$, | $[0.34+\mathbf{0 . 0 0 0 1}$, | $[-2.5$, |
| -1.11, | -1.11, | $?$, |
| 0.78, | 0.78, | $?$, |
| 0.12, | 0.12, | $(1.25322-1.25347) / 0.0001$ |
| 0.55, | 0.55, | -2.5 |
| 2.81, | 2.81, | $\frac{d f(x)}{d x}=\lim _{h \rightarrow 0} \frac{f(x+h)-f(x)}{h}$ |
| -3.1, | -3.1, | $?$, |
| -1.5, | -1.5, | $?, \ldots]$ |
| $0.33, \ldots]$ | $0.33, \ldots]$ |  |


| current W: | $\mathbf{W}+\mathbf{h}$ (second dim): | gradient dW: |
| :--- | :--- | :--- |
|  |  |  |
| $[0.34$, | $[0.34$, | $[-2.5$, |
| -1.11, | $-1.11+\mathbf{0 . 0 0 0 1}$, | $?$, |
| 0.78, | 0.78, | $?$, |
| 0.12, | 0.12, | $?$, |
| 0.55, | 0.55, | $?$, |
| 2.81, | 2.81, | $?$, |
| -3.1, | -3.1, | $?$, |
| -1.5, | -1.5, | $?$, |
| $0.33, \ldots]$ | $0.33, \ldots]$ | $?, \ldots]$ |
| loss 1.25347 | loss 1.25353 |  |


| current W: | $\mathbf{W}+\mathbf{h}$ (second dim): | gradient dW: |
| :--- | :--- | :---: |
|  |  |  |
| $[0.34$, | $[0.34$, | $[-2.5$, |
| -1.11, | $-1.11+\mathbf{0 . 0 0 0 1}$, | 0.6, |
| 0.78, | 0.78, | $?$, |
| 0.12, | 0.12, | $?$, |
| 0.55, | 0.55, | $(1.25353-1.25347) / 0.0001$ |
| 2.81, | 2.81, | $=0.6$ |
| -3.1, | -3.1, | $\frac{d f(x)}{d x}=\lim _{h \rightarrow 0} \frac{f(x+h)-f(x)}{h}$ |
| -1.5, | -1.5, | $?, \ldots]$ |
| $0.33, \ldots]$ | $0.33, \ldots]$ |  |
| loss 1.25347 | loss 1.25353 |  |


| current W: | $\mathbf{W}+\mathbf{h}$ (third dim): | gradient dW: |
| :--- | :--- | :--- |
|  |  |  |
| $[0.34$, | $[0.34$, | $[-2.5$, |
| -1.11, | -1.11, | 0.6, |
| 0.78, | $0.78+\mathbf{0 . 0 0 0 1}$, | $?$, |
| 0.12, | 0.12, | $?$, |
| 0.55, | 0.55, | $?$, |
| 2.81, | 2.81, | $?$, |
| -3.1, | -3.1, | $?$, |
| -1.5, | -1.5, | $?$, |
| $0.33, \ldots]$ | $0.33, \ldots]$ | $?, \ldots]$ |
| loss 1.25347 | loss 1.25347 |  |


| current W: | $\mathbf{W}+\mathbf{h}$ (third dim): | gradient dW: |
| :--- | :--- | :--- |
|  |  |  |
| $[0.34$, | $[0.34$, | $[-2.5$, |
| -1.11, | -1.11, | 0.6, |
| 0.78, | $0.78+\mathbf{0 . 0 0 0 1}$, | 0, |
| 0.12, | 0.12, | $?$, |
| 0.55, | 0.55, | $(1.25347-1.25347) / 0.0001$ |
| 2.81, | 2.81, | $=0$ |
| -3.1, | -3.1, | $\frac{d f(x)}{d x}=\lim _{h \rightarrow 0} \frac{f(x+h)-f(x)}{h}$ |
| -1.5, | -1.5, | $?, \ldots]$ |
| $0.33, \ldots]$ | $0.33, \ldots]$ |  |

## Numerical vs Analytic Gradients

$$
\frac{d f(x)}{d x}=\lim _{h \rightarrow 0} \frac{f(x+h)-f(x)}{h}
$$

Numerical gradient: slow :(, approximate :(, easy to write :) Analytic gradient: fast :), exact :), error-prone :(

In practice: Derive analytic gradient, check your implementation with numerical gradient.
This is called a gradient check.

- Components of parametric classifiers:
- Input/Output: Image/Label
- Model (function): Linear Classifier + Softmax
- Loss function: Cross-Entropy
- Optimizer: Gradient Descent
- Ways to compute gradients
- Numerical
- Next: Analytical, automatic differentiation

For some functions, we can analytically derive the partial derivative

## Example:

Derivation of Update Rule

Function
$f\left(w, x_{i}\right)=w^{T} x_{i}$

Loss
$\left(y_{i}-w^{T} x_{i}\right)^{2}$

Update Rule
$w_{j} \leftarrow w_{j}+2 \alpha \sum_{k=1}^{N} \delta_{k} x_{k j}$

## For some functions, we can analytically derive the partial derivative

## Example:

## Derivation of Update Rule

Function
$f\left(w, x_{i}\right)=w^{T} x_{i}$

Loss

$$
\left(y_{i}-w^{T} x_{i}\right)^{2}
$$

$\mathrm{L}=\sum_{k=1}^{N}\left(y_{k}-w^{T} x_{k}\right)^{2}$
Gradient descent tells us we should update $\boldsymbol{w}$ as follows to minimize $L$ :
$w_{j} \leftarrow w_{j}-\eta \frac{\partial L}{\partial w_{j}}$

$$
\begin{aligned}
& \frac{\partial L}{\partial w_{j}}=\sum_{k=1}^{N} \frac{\partial}{\partial w_{j}}\left(y_{k}-w^{T} x_{k}\right)^{2} \\
&=\sum_{k=1}^{N} 2\left(y_{k}-w^{T} x_{k}\right) \frac{\partial}{\partial w_{j}}\left(y_{k}-w^{T} x_{k}\right) \\
&=-2 \sum_{k=1}^{N} \delta_{k} \frac{\partial}{\partial w_{j}} \boldsymbol{w}^{T} x_{k} \\
& \begin{array}{c}
\ldots \text { where } \ldots \\
\delta_{k}=y_{k}-w^{T} x_{k}
\end{array}
\end{aligned}
$$

$$
=-2 \sum_{k=1}^{N} \delta_{k} \frac{\partial}{\partial w_{j}} \sum_{i=1}^{m} w_{i} x_{k i}
$$

$$
=-2 \sum_{k=1}^{N} \delta_{k} x_{k j}
$$

If we add a non-linearity (sigmoid), derivation is more complex

$$
\sigma(x)=\frac{1}{1+e^{-x}}
$$

First, one can derive that: $\boldsymbol{\sigma}^{\prime(x)}=\boldsymbol{\sigma}(\boldsymbol{x})(\mathbf{1}-\boldsymbol{\sigma}(x))$

$$
\begin{aligned}
\mathrm{f}(\mathrm{x}) & =\sigma\left(\sum_{k} w_{k} x_{k}\right) \\
\mathrm{L} & =\sum_{i}\left(y_{i}-\sigma\left(\sum_{k} w_{k} x_{i k}\right)\right)^{2} \\
\frac{\partial L}{\partial w_{j}} & =\sum_{i} 2\left(y_{i}-\sigma\left(\sum_{k} w_{k} x_{i k}\right)\right)\left(-\frac{\partial}{\partial w_{j}} \sigma\left(\sum_{k} w_{k} x_{i k}\right)\right) \\
& =\sum_{i}-2\left(y_{i}-\sigma\left(\sum_{k} w_{k} x_{i k}\right)\right) \sigma^{\prime}\left(\sum_{k} w_{k} x_{i k}\right) \frac{\partial}{\partial w_{j}} \sum_{k} w_{k} x_{i k} \\
& =\sum_{i}-2 \delta_{i} \sigma\left(\mathbf{d}_{i}\right)\left(1-\sigma\left(\mathbf{d}_{i}\right)\right) x_{i j}
\end{aligned}
$$



The sigmoid perception update rule:

$$
\text { where } \quad \delta_{i}=y_{i}-\mathbf{f}\left(x_{i}\right) \quad d_{i}=\sum w_{k} x_{i k}
$$

$$
\begin{gathered}
w_{j} \leftarrow w_{j}+2 \alpha \sum_{k=1}^{N} \delta_{i} \sigma_{i}\left(1-\sigma_{i}\right) x_{i j} \\
\text { where } \sigma_{i}=\sigma\left(\sum_{j=1}^{m} w_{j} x_{i j}\right) \\
\delta_{i}=y_{i}-\sigma_{i}
\end{gathered}
$$

Given a library of simple functions


Adapted from slides by: Marc'Aurelio Ranzato, Yann LeCun

